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Clasificacin de objetos usando percepcin bimodal de palpacin nica en acciones de agarre robtico

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4	Tactile-Driven Grasp Stability and Slip Prediction. <i>Robotics</i> , <b>2019</b> , 8, 85	2.8	5
3	Generation of Tactile Data From 3D Vision and Target Robotic Grasps. <i>IEEE Transactions on Haptics</i> , <b>2021</b> , 14, 57-67	2.7	2
2	Manipulacili de 7 servomotores con FPGA iCEstick Evaluation Kit. <i>Revista De Clinputo Aplicado</i> , 17-23		
1	Manipulacifi visual-tfitil para la recogida de residuos domEticos en exteriores. <b>2023</b> , 20, 163-174		O