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Human-Machine Cooperative Grasping/Manipulating System Using Force-based Compliance Controller with Force Threshold

DOI: 10.1541/ieejia.5.39

IEEJ Journal of Industry Applications, 2016, 5, 39-46.

Source: <https://exaly.com/paper-pdf/87358332/citation-report.pdf>

Version: 2024-04-19

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#	Paper	IF	Citations
10	Which, When, and How: Hierarchical Clustering with HumanMachine Cooperation. <i>Algorithms</i> , 2016 , 9, 88	1.8	2
9	Proposal of impedance control for electric vehicles with wheel resolver - application to hand assisted parking and position adjustment -. 2016 ,		1
8	Realization of stable contact motion based on concept of resonance ratio control. 2016 ,		0
7	Proposal of Lateral Force Disturbance Estimation Method for In-Wheel-Motored Electric Vehicles. 2018 ,		
6	Tracking Control Method Considering Obstacle Avoidance by Reflective Motion for Mobile Robot. 2018 ,		1
5	Hysteresis Compensation in Force/Torque Sensor based on Machine Learning. 2018 ,		1
4	Filtered Disturbance Observer for High Backdrivable Robot Joint. 2018 ,		2
3	Design of Nominal Parameters for Robust Sensorless Force Control Based on Disturbance Observer. <i>IEEJ Journal of Industry Applications</i> , 2019 , 8, 342-351	0.7	3
2	Force and Impedance Control for Automatic Violin Performance. 2020 ,		
1	Temperature estimation of lead screw drive using disturbance observer for sensorless force control. 2021 ,		