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Automatic Vehicle Tracking with LiDAR-Enhanced Roadside Infrastructure

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4	Background Filtering and Object Detection With a Stationary LiDAR Using a Layer-Based Method. <i>IEEE Access</i> , 2020 , 8, 184426-184436	3.5	3
3	Augmented Multiple Vehicles Trajectories Extraction Under Occlusions With Roadside LiDAR Data. <i>IEEE Sensors Journal</i> , 2021 , 1-1	4	1
2	Object Classification with Roadside LiDAR Data Using a Probabilistic Neural Network. <i>Electronics (Switzerland)</i> , 2021 , 10, 803	2.6	2
1	Optimizing Moving Object Trajectories from Roadside Lidar Data by Joint Detection and Tracking. <i>Remote Sensing</i> , 2022 , 14, 2124	5	1