

# CITATION REPORT

List of articles citing

**Kinect Enabled Monte Carlo Localisation for a Robotic Wheel**

**DOI: 10.1007/978-3-642-35485-4\_2**  
**Studies in Computational Intelligence, 2013, , 17-27.**

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#	Paper	IF	Citations
1	Enhanced PCA-Based Localization Using Depth Maps with Missing Data. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , <b>2015</b> , 77, 341-360	2.9	10