Learning Control Supported by Dynamic Event Commu Systems

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Citation Report

#	Article	IF	CITATIONS
1	Eventâ€ŧriggered guaranteed cost faultâ€ŧolerant optimal tracking control for uncertain nonlinear system via adaptive dynamic programming. International Journal of Robust and Nonlinear Control, 2021, 31, 2572-2592.	2.1	31
2	Event-Triggered Near-Optimal Control of Discrete-Time Constrained Nonlinear Systems With Application to a Boiler-Turbine System. IEEE Transactions on Industrial Informatics, 2022, 18, 3926-3935.	7.2	29
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6	Neural network-based adaptive decentralized learning control for interconnected systems with input constraints. Control Theory and Technology, 2021, 19, 392-404.	1.0	O
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18	Learning-Based Control With Decentralized Dynamic Event-Triggering for Vehicle Systems. IEEE Transactions on Industrial Informatics, 2023, 19, 2629-2639.	7.2	7
19	Fixed-Time Cooperative Tracking for Delayed Disturbed Multi-Agent Systems Under Dynamic Event-Triggered Control. IEEE/CAA Journal of Automatica Sinica, 2022, 9, 930-933.	8.5	30

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21	基于安全自é€,应强åŒ−å¦ä¹çš"自主éෑ障控å^¶æ−¹æ³•. Scientia Sinica Informationis, 2022, , .	0.2	O
22	Adaptive Optimal Tracking Control for Spacecraft Formation Flying With Event-Triggered Input. IEEE Transactions on Industrial Informatics, 2023, 19, 6418-6428.	7.2	6
23	Finite-Time Command-Filtered Backstepping Control for Dual-Motor Servo Systems With LuGre Friction. IEEE Transactions on Industrial Informatics, 2023, 19, 6376-6386.	7.2	7
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