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Output Feedback Image-Based Visual Servoing of Rotorcrafts

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Journal of Intelligent and Robotic Systems: Theory and Applications, 2019, 93, 277-287.

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7	Vision Based Autonomous Landing of the Quadrotor Using Fuzzy Logic Control. 2019 ,		1
6	Vision Based Autonomous Tracking and Landing on an Arbitrary Object of Quadrotor. 2019 ,		0
5	Robust Vision-Based Control of a Rotorcraft UAV for Uncooperative Target Tracking. <i>Sensors</i> , 2020 , 20,	3.8	2
4	. <i>IEEE Transactions on Aerospace and Electronic Systems</i> , 2020 , 56, 3182-3196	3.7	14
3	. <i>IEEE Access</i> , 2020 , 8, 74175-74194	3.5	30
2	Image-Based Visual Servoing of Rotorcrafts to Planar Visual Targets of Arbitrary Orientation. <i>IEEE Robotics and Automation Letters</i> , 2021 , 6, 7861-7868	4.2	3
1	Visual Servoing of Unknown Objects for Family Service Robots. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , 2022 , 104, 1	2.9	