## A Real-Time Collision Avoidance Strategy in Dynamic A Potential Field Algorithm

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**Citation Report** 

CITATION REDORT

#	Article	IF	CITATIONS
1	Multi UAV Cluster Control Method Based on Virtual Core in Improved Artificial Potential Field. IEEE Access, 2020, 8, 131647-131661.	4.2	31
2	Reactive Collision Avoidance Algorithm for UAV Using Bounding Tube Against Multiple Moving Obstacles. IEEE Access, 2020, 8, 218131-218144.	4.2	5
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