

# CITATION REPORT

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## ITC: Infused Tangential Curves for Smooth 2D and 3D Navigation of Mobile Robots

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Sensors, 2019, 19, .

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#	Paper	IF	Citations
6	HPPRM: Hybrid Potential Based Probabilistic Roadmap Algorithm for Improved Dynamic Path Planning of Mobile Robots. <i>IEEE Access</i> , <b>2020</b> , 8, 221743-221766	3.5	13
5	Safe mobile robot navigation in human-centered environments using a heat map-based path planner. <i>Artificial Life and Robotics</i> , <b>2020</b> , 25, 264-272	0.6	0
4	Multi-robot path planning for smart access of distributed charging points in map. <i>Artificial Life and Robotics</i> , <b>2021</b> , 26, 52-60	0.6	3
3	A Dynamic Motion Analysis of a Six-Wheel Ground Vehicle for Emergency Intervention Actions. <i>Sensors</i> , <b>2021</b> , 21,	3.8	2
2	Autonomous and Safe Navigation of Mobile Robots in Vineyard with Smooth Collision Avoidance. <i>Agriculture (Switzerland)</i> , <b>2021</b> , 11, 954	3	4
1	A Generalized Laser Simulator Algorithm for Mobile Robot Path Planning with Obstacle Avoidance. <b>2022</b> , 22, 8177		1