

# Controlled flight of a microrobot powered by soft artificial muscles

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Citation Report

#	ARTICLE	IF	CITATIONS
1	Power optimization of a conical dielectric elastomer actuator for resonant robotic systems. <i>Extreme Mechanics Letters</i> , 2020, 35, 100619.	2.0	36
2	Lighting up soft robotics. <i>Nature Materials</i> , 2020, 19, 134-135.	13.3	5
3	High-strain Peano-HASEL Actuators. <i>Advanced Functional Materials</i> , 2020, 30, 1908821.	7.8	50
4	Mimicking nature's flyers: a review of insect-inspired flying robots. <i>Current Opinion in Insect Science</i> , 2020, 42, 70-75.	2.2	21
5	Dynamic modeling, simulation and design of smart membrane systems driven by soft actuators of multilayer dielectric elastomers. <i>Nonlinear Dynamics</i> , 2020, 102, 1463-1483.	2.7	15
6	Recent advances in bioelectronics chemistry. <i>Chemical Society Reviews</i> , 2020, 49, 7978-8035.	18.7	54
7	An agglutinate magnetic spray transforms inanimate objects into millirobots for biomedical applications. <i>Science Robotics</i> , 2020, 5, .	9.9	115
8	Elastomeric high- $\hat{\nu}$ composites of low dielectric loss tangent: Experiment and simulation. <i>Composites Part B: Engineering</i> , 2020, 201, 108337.	5.9	11
9	Mechanisms of collision recovery in flying beetles and flapping-wing robots. <i>Science</i> , 2020, 370, 1214-1219.	6.0	79
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18	Characterization and Optimization of Elastomeric Electrodes for Dielectric Elastomer Artificial Muscles. <i>Materials</i> , 2020, 13, 5542.	1.3	4

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