

# CITATION REPORT

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## Cooperative control of a nonuniform gantry crane with constrained tension

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#	Paper	IF	Citations
481	Mathematical modeling of nonlinear dynamic system of the truck crane. <b>2016</b> , 9, 487-495		1
480	Optimization of the Parameters of RISE Feedback Controller Using Genetic Algorithm. <b>2016</b> , 2016, 1-9		1
479	Boundary control based on an infinite dimensional system of a marine riser with constraint. <b>2016</b> ,		
478	Boundary control design for a flexible string system with input backlash. <b>2016</b> ,		2
477	Adaptive Neural Network Control of Biped Robots. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2016</b> , 1-12	7.3	68
476	Robust control of uncertain semi-Markovian jump systems using sliding mode control method. <b>2016</b> , 286, 72-87		68
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474	Active vibration control for a flexible string system with input backlash. <i>IET Control Theory and Applications</i> , <b>2016</b> , 10, 800-805	2.5	76
473	Adaptive control of a class of switched nonlinear discrete-time systems with unknown parameter. <i>Neurocomputing</i> , <b>2016</b> , 214, 1-6	5.4	11
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469	Modeling and vibration control of flexible wings with output constraint. <b>2016</b> ,		
468	Zero gravity tracking system using constant tension suspension for a multidimensional framed structure space antenna. <b>2016</b> ,		2
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110	Adaptive Fuzzy Control for Nonstrict-Feedback Systems Under Asymmetric Time-Varying Full State Constraints Without Feasibility Condition. <b>2021</b> , 29, 976-985		12
109	Event-Based Secure Leader-Following Consensus Control for Multiagent Systems With Multiple Cyber Attacks. <i>IEEE Transactions on Cybernetics</i> , <b>2021</b> , 51, 162-173	10.2	58
108	. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2021</b> , 51, 3111-3124	7.3	12
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