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## Adaptive Neural Impedance Control of a Robotic Manipulator With Input Saturation

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#	Paper	IF	Citations
617	Development and Implementation of a Wheeled Inverted Pendulum Vehicle Using Adaptive Neural Control with Extreme Learning Machines. <b>2015</b> , 7, 740-752		7
616	Adaptive neural network control of unknown nonlinear affine systems with input deadzone and output constraint. <b>2015</b> , 58, 96-104		38
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