

A Resilient, Untethered Soft Robot

Soft Robotics

1, 213-223

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Citation Report

#	ARTICLE	IF	CITATIONS
1	Soft pneumatic actuators for legged locomotion. , 2014, , .		22
2	An untethered jumping soft robot. , 2014, , .		124
3	Biorobotics: Using robots to emulate and investigate agile locomotion. Science, 2014, 346, 196-203.	6.0	367
4	Microrobotic tentacles with spiral bending capability based on shape-engineered elastomeric microtubes. Scientific Reports, 2015, 5, 10768.	1.6	109
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6	Design Methodologies for Soft-Material Robots Through Additive Manufacturing, From Prototyping to Locomotion. , 2015, , .		5
7	Bioinspired design and fabrication principles of reliable fluidic soft actuation modules. , 2015, , .		13
8	Poroelastic Foams for Simple Fabrication of Complex Soft Robots. Advanced Materials, 2015, 27, 6334-6340.	11.1	109
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17	Biologically inspired vine-like and tendril-like robots. , 2015, , .		17
18	A soft pneumatic actuator that can sense grasp and touch. , 2015, , .		66

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