## Tutorial on Lyapunov-based methods for time-delay sy

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Citation Report

#	Article	IF	CITATIONS
1	Quaternion-based H <inf>â^ž</inf> kinematic attitude control subjected to input time-varying delays. , 2015, , .		1
2	Stability of a class of delayed port-Hamiltonian systems with application to droop-controlled microgrids. , 2015, , .		7
3	Improved delay-range-dependent stability criterion for Markovian jump systems with interval time-varying delay. , 2015, , .		1
4	New result on delay-range-dependent stability analysis for linear system with interval time-varying delay. , 2015, , .		0
5	Further results on mixed-delay-dependent robust stability for uncertain linear neutral systems. , 2015, , .		0
6	Quaternion-based â,,‹ <inf>â^ž</inf> attitude tracking control of rigid bodies with time-varying delay in attitude measurements. , 2016, , .		1
7	Simple LMIs for stabilization by using delays. , 2016, , .		2
8	Unknown input estimation via observers for nonlinear systems with measurement delays. , 2016, , .		4
9	Scanning the space of parameters for stability regions of neutral type delay systems: A Lyapunov matrix approach. , 2016, , .		6
	proposed in Appendix A is supported solely by the grant from the Russian Science Foundation (project) Tj ETQq1	1 0.78431	l4 rgBT /Ov€
10	supported solely by the Russian Federation President Grant (No. 14.W01.16.6325-MD (MD-6325.2016.8)). The other researches were partially supported by grants of RFBR (16-08-00282, 16-08-00686, 14-08-01015).	0.5	0
11	Ministry o. IFAC-PapersOnLine, 2016, 49, 25-30. Controlled synchronization in two hybrid FitzHugh-Nagumo systems. IFAC-PapersOnLine, 2016, 49, 137-141.	0.5	8
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18	Observer Design for Singularly Perturbed Systems With Multirate Sampled and Delayed Measurements. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2016, 138, .	0.9	11

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31	A Polynomial Method for Stability Analysis of LTI Systems Independent of Delays. SIAM Journal on Control and Optimization, 2017, 55, 2661-2683.	1.1	4
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