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Adaptive Sliding-Mode Control for Nonlinear Active Suspension Vehicle Systems Using TS Fuzzy Approach

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588	Low-Speed Control of Heavy-Load Transfer Robot with Long Telescopic Boom Based on Stribeck Friction Model. <i>Mathematical Problems in Engineering</i> , 2012 , 2012, 1-12	1.1	4
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- 1 Event-Triggered Vibration Control for Active Full-Vehicle Suspension Systems Based on Preview Information. ○