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An IPMC-enabled bio-inspired bending/twisting fin for underwater applications

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Smart Materials and Structures, 2013, 22, 014003.

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90	Design optimization of a twist compliant mechanism with nonlinear stiffness. <i>Smart Materials and Structures</i> , 2014 , 23, 104010	3.4	3
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87	Grasshopper Knee Joint Inverse Kinematic Modeling and Simulation of Ionic Polymer Metal Composites (IPMC) Actuators. <i>Journal of Biomimetics, Biomaterials, and Tissue Engineering</i> , 2014 , 19, 1-11		6
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