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Citation Report

#	Article	IF	CITATIONS
1	Robust Probabilistic Occupancy Grid Estimation from Positive and Negative Distance Fields., 2012,,.		0
2	Least Commitment, Viewpoint-Based, Multi-view Stereo. , 2012, , .		26
3	Learning a Confidence Measure for Optical Flow. IEEE Transactions on Pattern Analysis and Machine Intelligence, 2013, 35, 1107-1120.	9.7	74
4	Flow-Based Correspondence Matching in Stereovision. Lecture Notes in Computer Science, 2013, , 106-113.	1.0	7
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6	Aggregation functions to combine RGB color channels in stereo matching. Optics Express, 2013, 21, 1247.	1.7	18
7	Local Signal Equalization for Correspondence Matching. , 2013, , .		3
8	Integrating the whole cost-curve of stereo into occupancy grids. , 2013, , .		2
9	Efficient active depth sensing by laser speckle projection system. Optical Engineering, 2014, 53, 013105.	0.5	15
10	Towards an Embedded Real-Time High Resolution Vision System. Lecture Notes in Computer Science, 2014, , 541-550.	1.0	O
11	Stereo confidence metrics using the costs of surrounding pixels., 2014,,.		4
12	Confidence-guided adaptive scanline optimization for stereo matching. , 2014, , .		O
13	Two-step supervised confidence measure for automatic face recognition. , 2014, , .		2
14	High-Resolution Stereo Datasets with Subpixel-Accurate Ground Truth. Lecture Notes in Computer Science, 2014, , 31-42.	1.0	661
15	Learning to Detect Ground Control Points for Improving the Accuracy of Stereo Matching. , 2014, , .		82
16	On modeling ego-motion uncertainty for moving object detection from a mobile platform. , 2014, , .		10
17	Stem localization of sweet-pepper plants using the support wire as a visual cue. Computers and Electronics in Agriculture, 2014, 105, 111-120.	3.7	65
18	Multi-View Stereo: A Tutorial. Foundations and Trends in Computer Graphics and Vision, 2015, 9, 1-148.	2.8	325

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