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Compliant actuator designs

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#	Paper	IF	Citations
588	Joint torque sensing for the upper-body of the iCub humanoid robot. 2009,		23
587	The Safety of a Robot Actuated by Pneumatic Muscles A Case Study. 2010, 2, 289-303		28
586	Dynamic Modeling of the 4 DoF BioRob Series Elastic Robot Arm for Simulation and Control. <i>Lecture Notes in Computer Science, 2010,</i> 411-422	0.9	5
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