

A Model of the Upper Extremity for Simulating Muscular Neuromuscular Control

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Citation Report

#	ARTICLE	IF	CITATIONS
1	Moment arms of forearm rotators. <i>Clinical Biomechanics</i> , 2006, 21, 683-691.	0.5	34
2	Task-level approaches for the control of constrained multibody systems. <i>Multibody System Dynamics</i> , 2006, 16, 73-102.	1.7	24
3	A Probabilistic Model of Glenohumeral External Rotation Strength for Healthy Normals and Rotator Cuff Tear Cases. <i>Annals of Biomedical Engineering</i> , 2006, 34, 465-476.	1.3	22
4	Variability in Surgical Technique for Brachioradialis Tendon Transfer<sbid="1121202">Evidence and Implications</sbid>. <i>Journal of Bone and Joint Surgery - Series A</i> , 2006, 88, 2009.	1.4	25
5	Arm Motion Reconstruction via Feature Clustering in Joint Angle Space. , 2006, , .		0
6	The control of kinematically constrained shoulder complexes: physiological and humanoid examples. , 0, , .		12
7	Computational model of a primate arm: from hand position to joint angles, joint torques and muscle forces. <i>Journal of Neural Engineering</i> , 2006, 3, 327-337.	1.8	111
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