Developments in nonholonomic control problems

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Citation Report

#	Article	IF	Citations
1	Design of oscillatory control systems. , 0, , .		0
2	Adaptive tracking control of nonholonomic systems: an example. , 0, , .		6
3	A universal saturation controller design for mobile robots. , 0, , .		3
4	Mixing input-output pseudolinearization and gain scheduling techniques for stabilization of mobile robots. , 0, , .		0
5	Steering marine vehicles: a drag coefficient modulation approach. , 0, , .		1
6	A global-stabilizing near-optimal control for real-time trajectory tracking of nonholonomic chained systems. , 0, , .		1
7	A hybrid switched mode control approach for V/STOL flight control problems. , 0, , .		9
8	Adaptive fuzzy controller design for trajectory tracking of a 2 DOF wheeled mobile robot using genetic algorithm. , 0, , .		1
9	Control of a nonholonomic mobile robot using neural networks. , 0, , .		5
10	Nonlinear control of a class of underactuated systems. , 0, , .		50
11	Stabilization of nonholonomic mobile robots by a GA-based fuzzy sliding mode control. , 0, , .		0
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