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Developments in nonholonomic control problems

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938	Stabilization of wheeled vehicles by hybrid nonlinear time-varying feedback laws.		2
937	Robust control of mobile manipulators. 1996, 13, 699-708		2
936	Asymptotic feedback stabilization of a nonholonomic mobile robot using a nonlinear oscillator.		3
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928	Mixing input-output pseudolinearization and gain scheduling techniques for stabilization of mobile robots with two independently driven wheels. 1997 , 15, 573-582	1
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919	Inclination control of the motion of a rolling disk by using a rotor. 1997 , 146, 253-263	15
918	Tracking Control of Mobile Robots: A Case Study in Backstepping**This paper was not presented at any IFAC meeting. This paper was recommended for publication in revised form by Associate Editor Alberto Isidori under the direction of Editor Tamer Başar. <i>Automatica</i> , 1997 , 33, 1393-1399	5-7 557
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913	Path-tracking for articulated vehicles with off-axle hitching. <i>IEEE Transactions on Control Systems Technology</i> , 1998 , 6, 515-523	4.8	80
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