

Flatness and defect of non-linear systems: introductory

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Citation Report

#	ARTICLE	IF	CITATIONS
1	Design of oscillatory control systems. , 0, , .		0
2	Pseudospectral methods for optimal motion planning of differentially flat systems. , 0, , .		15
3	A new approach to dynamic feedback linearization control of an induction motor. , 0, , .		10
4	Flatness of heavy chain systems. , 0, , .		11
5	Control of robots with elastic joints based on automatic generation of inverse dynamics models. , 0, , .		15
6	On Coursat normal forms, prolongations, and control systems. , 0, , .		7
7	Feedback linearization of a class of nonlinear descriptor systems. , 0, , .		15
8	A different look at output tracking: control of a VTOL aircraft. , 0, , .		56
9	Nonlinear control and Lie-Backlund transformations: towards a new differential geometric standpoint. , 0, , .		23
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58	A toy more difficult to control than the real thing. , 1997, , .		9
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