

Handling of irregular-sized mailpieces by adaptive robot

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#	ARTICLE	IF	CITATIONS
1	Object pose determination from range data. Computers and Industrial Engineering, 1992, 22, 245-255.	6.3	6
2	e-Learning Experiences in Control Education. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 9093-9098.	0.4	0
3	An H&inf; and a Z&inf; approach to fault detection for multirate sampled-data systems with frequency specifications. , 2016, , .		0
4	Robotic System for Post Office Package Handling. Applied Sciences (Switzerland), 2023, 13, 7643.	2.5	1