

CITATION REPORT

List of articles citing

Zero Phase Error Tracking Algorithm for Digital Control

DOI: 10.1115/1.3143822

Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 1987, 109, 65-68.

Source: <https://exaly.com/paper-pdf/19098387/citation-report.pdf>

Version: 2024-04-28

This report has been generated based on the citations recorded by exaly.com for the above article. For the latest version of this publication list, visit the link given above.

The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

#	Paper	IF	Citations
1088	Robust motion control with autonomous consideration algorithm of joint torque saturation.		0
1087	Redundant manipulator control with autonomous consideration algorithm of torque saturation.		6
1086	.		3
1085	.		34
1084	Control of Robot Manipulators under Repetitive Tasks -Segmented Repetitive Control Approach.		2
1083	.		4
1082	Design and control of a prototype platform manipulator for workholding and workhandling applications. 1989 , 20, 305-314		5
1081	Robot Path Control with Variable Speed by Preview Control and Adaptive Control. 1990 , 23, 121-126		
1080	Design of a Feedforward Controller for Trajectory Tracking Based on Steady State Error Analysis: Its Application to Robotic Joint Controller. 1990 , 23, 127-132		
1079	Discrete-Time Adaptive Control for Continuous-Time Systems Using Limiting-Zero Model and Its Application. 1990 , 23, 113-118		
1078	. 1990 , 20, 1115-1124		54
1077	. 1990 , 10, 16-20		208
1076	Steady-State and Stochastic Performance of a Modified Discrete-Time Prototype Repetitive Controller. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1990 , 112, 35-41	1.6	71
1075	. 1990 , 6, 735-745		49
1074	. 1991 ,		2
1073	.		11
1072	Variable-Gain Cross-Coupling Controller for Contouring. 1991 , 40, 371-374		279

1071	Experimental Research on the Linear Motor Micro-Feed Device with High-Frequency Response, Long Travel and High Accuracy. 1991 , 40, 379-382	9
1070	Modelling and control of flexible robots. 1991 , 32, 1595-1619	21
1069	On mimo optimal preview tracking control for known trajectory models. 1991 , 12, 119-130	2
1068	Steady-state feedforward compensation for discrete time multivariable systems. 1991 , 1, 253-276	1
1067	Feedforward digital tracking controllers for motion control applications. 1992 , 7, 575-586	4
1066	.	21
1065	.	2
1064	Advanced Controllers for Feed Drives. 1992 , 41, 689-698	137
1063	Fast and accurate tracking control of a flexible one-link robot based on real-time link deflection measurements. 1992 , 2, 29-41	15
1062	. 1993 , 13, 48-54	66
1061	.	3
1060	.	10
1059	Characterization and compensation of discrete-time non-minimum-phase systems for precision tracking control. 1993 , 24, 1189-1205	4
1058	.	2
1057	Robust Discrete-Time Adaptive Control Scheme for Servo Systems and Its Application. 1993 , 26, 115-120	
1056	Feedforward Tracking Controller Design for High-Speed Motion Control. 1993 , 26, 299-302	1
1055	Feedforward Controllers for Perfect Tracking that does not Invert Plant Zeros Outside the Unit Disc. 1993 , 26, 547-550	
1054	.	15

1053	High-speed end mill boring and rounded corner cutting.			2
1052	A self-tuning adaptive feed-forward control for a retrofit milling machine. 1994 , 4, 565-580			2
1051	Accurate Motion Controller Design Based on an Extended Pole Placement Method and a Disturbance Observer. 1994 , 43, 367-372			22
1050	. <i>IEEE Transactions on Control Systems Technology</i> , 1994 , 2, 382-391	4.8		46
1049	Perfect tracking of non minimum phase process. Application to flexible joint robot. 1994 , 27, 729-734			
1048	Trajectory Preshaping for High-Speed Articulated Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1995 , 117, 304-310	1.6		14
1047	Extended Pole Placement Method With Noncausal Reference Model for Digital Servo-Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1995 , 117, 641-644	1.6		5
1046	Active Sound Attenuation in Finite-Length Ducts Using Close-Form Transfer Function Models. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1995 , 117, 143-154	1.6		18
1045	Real-time vision-based tracking control of an unmanned vehicle. 1995 , 5, 973-991			18
1044	Application of self-tuning feed-forward and cross-coupling control in a retrofitted milling machine. 1995 , 35, 577-591			16
1043	Effect of Low-Friction Guideways and Lead-Screw Flexibility on Dynamics of High-Speed Machines. 1995 , 44, 353-356			33
1042	Precision tracking control of non-minimum phase systems with zero phase error. 1995 , 61, 791-807			48
1041	.			1
1040	Linear discrete-time H/sub /spl infin//-optimal tracking with preview.			
1039	Optimal feedforward tracking control of linear motors for machine tool drives.			2
1038	Robust tracking controller design for high-speed machining.			0
1037	Design of bi-causal inverse models for non-minimum phase systems and its applications to precision tracking control.			
1036	. 1995 , 40, 743-747			12

1035	Wheel servo control based on feedforward compensation for an autonomous mobile robot.		2
1034	Data-based tracking control for nonminimum-phase systems.		
1033	. <i>IEEE Transactions on Industrial Electronics</i> , 1996 , 43, 48-55	8.9	243
1032	Mechatronics-a powerful concurrent engineering framework. <i>IEEE/ASME Transactions on Mechatronics</i> , 1996 , 1, 127-136	5.5	36
1031	Application and comparison of alternative position sensors in high-accuracy control of an X-Y table.		4
1030	Robust digital tracking controller design for high-speed positioning systems-a new design approach and implementation techniques.		3
1029	Extended discrete-time prototype repetitive controllers and its application.		5
1028	Efficient implementation of adaptive feedforward runout cancellation in a disk drive. 1996 , 32, 3920-3922		12
1027	High-Speed End Milling Using a Feedforward Control Architecture. 1996 , 118, 178-187		12
1026	Tracking Control with a Smooth Transient Response. 1996 , 29, 1287-1291		2
1025	Output Synchronization Using Predictive Control. 1996 , 29, 1440-1445		
1024	Repetitive Control Theory and Applications - A Survey. 1996 , 29, 1446-1451		17
1023	Effects of Non-Periodic Disturbances on Repetitive Control Systems. 1996 , 29, 1452-1457		1
1022	Extended 2-Delay Model Reference Adaptive Controllers with Reduced Input Amplitude. 1996 , 29, 4947-4952		
1021	Optimal Feedforward Prefilter With Frequency Domain Specification for Nonminimum Phase Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1996 , 118, 791-795	1.6	7
1020	Feedforward and feedback strategies applying the principle of input balancing for minimal tracking errors in CNC machine tools.		2
1019	Application of grey predictor and fuzzy speed regulator in controlling a retrofitted machining table. 1996 , 36, 477-489		4
1018	The regulation of position error in contouring systems. 1996 , 36, 713-728		11

1017	Accurate tracking control of linear synchronous motor machine tool axes. 1996 , 6, 507-521		86
1016	Robust digital tracking controller design for high-speed positioning systems. <i>Control Engineering Practice</i> , 1996 , 4, 527-536	3.9	39
1015	Cross-coupled biaxial step control for CNC EDM. 1996 , 36, 1363-1383		4
1014	Robustness properties of repetitive controllers. 1996 , 65, 939-961		8
1013	Control of Cutting Force for End Milling Processes Using an Extended Model Reference Adaptive Control Scheme. 1996 , 118, 339-347		29
1012	Using preaction with infinite or finite preview for perfect or almost perfect digital tracking.		6
1011	Frequency response based feedforward control design with uncertainty considerations. 1997 ,		5
1010	Control of Machine Tools. 1997 , 119, 749-755		77
1009	High performance robust motion control of machine tools: an adaptive robust control approach and comparative experiments. 1997 ,		1
1008	Modeling and control of magnetically levitated rotating machines. 1997 ,		3
1007	Refining the Shuttle training aircraft controller.		1
1006	Robust robot manipulator control with autonomous consideration algorithm of torque saturation. 1997 , 12, 755-769		2
1005	Mechatronics for computer data storage devices.		2
1004	Modified AFC runout cancellation and its influence on track following.		4
1003	Zero Phase Error Tracking System With Arbitrarily Specified Gain Characteristics. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1997 , 119, 260-264	1.6	10
1002	System Identification and Adaptive Control of the Multi-Axis Bending and Twisting Process. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1997 , 119, 782-790	1.6	7
1001	Industrial Perspective on Robust Control: Application to Storage Systems. 1997 , 30, 9-20		
1000	Adaptive Zero Phase Error Tracking Controller with Precision Tracking Performance. 1997 , 30, 837-842		1

999	Adaptive Robust Control of Non linear Systems: Effective Use of Information. 1997 , 30, 873-878		4
998	A study on position control of piezoelectric actuators.		15
997	Linear discrete-time H/sub /spl infin//-optimal tracking with preview. 1997 , 42, 270-276		56
996	An effective pole-zero cancellation in feedforward controllers for nonminimum phase systems. 1997 ,		
995	Adaptive robust contour tracking of machine tool feed drive systems-a task coordinate frame approach. 1997 ,		15
994	High performance adaptive robust control of nonlinear systems: a general framework and new schemes.		66
993	High-performance robust motion control of machine tools: an adaptive robust control approach and comparative experiments. <i>IEEE/ASME Transactions on Mechatronics</i> , 1997 , 2, 63-76	5.5	172
992	Reducing the manufacturing costs associated with hard disk drives-a new disturbance rejection control scheme. <i>IEEE/ASME Transactions on Mechatronics</i> , 1997 , 2, 77-85	5.5	24
991	High-speed and high-precision motion control with an optimal hybrid feedforward controller. <i>IEEE/ASME Transactions on Mechatronics</i> , 1997 , 2, 110-122	5.5	44
990	A receding time horizon optimal feedrate control with cross-coupled structure for multiaxial systems. 1997 , 11, 419		2
989	Improved fuzzy sliding-mode control for a linear servo motor system. <i>Control Engineering Practice</i> , 1997 , 5, 219-227	3.9	6
988	CNC machine tool interpolator with path compensation for repeated contour machining. 1998 , 30, 55-62		33
987	Design for Precision: Current Status and Trends. 1998 , 47, 557-586		155
986	.		14
985	Intelligent control for handling motion nonlinearity in a retrofitted machining table. 1998 , 145, 403-408		1
984	Industrial perspective on robust control: Application to storage systems. 1998 , 22, 47-58		1
983	A method of tool path compensation for repeated machining process. 1998 , 38, 205-213		36
982	A feedforward controller by modified series approximation. <i>IEEE/ASME Transactions on Mechatronics</i> , 1998 , 3, 249-251	5.5	6

981	Application of model-matching techniques to feedforward active noise controller design. <i>IEEE Transactions on Control Systems Technology</i> , 1998 , 6, 33-42	4.8	17
980	Use of accelerometer for precision motion control of linear motor driven positioning system.		9
979	Advanced motion control in redundant motion systems.		1
978	Predictive and time delay control of transmission mechanisms. 1998 ,		
977	Comparison of two feedforward design methods aiming at accurate trajectory tracking of the end point of a flexible robot arm. <i>IEEE Transactions on Control Systems Technology</i> , 1998 , 6, 2-14	4.8	55
976	Advanced Motion Control: An Industrial Perspective. 1998 , 4, 278-293		85
975	Nonlinear system identification using genetic algorithms with application to feedforward control design. 1998 ,		
974	Contour tracking of machine tool feed drive systems. 1998 ,		9
973	Discrete-time prototype repetitive controllers considering pole-assignment and its application.		
972	A general framework of coordinated motion control subjected to actuator saturation. 1998 ,		
971	A Tracking Controller for Linear Time-Varying Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1998 , 120, 111-116	1.6	4
970	Linear Motor Ripple Compensation Using Position-Triggered Repetitive Control. 1998 , 31, 353-357		1
969	Control of Linear Motors for Machine Tool Feed Drives: Experimental Investigation of Optimal Feedforward Tracking Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1998 , 120, 137-142	1.6	3
968	Optimal precision tracking control of discrete time nonminimum phase systems. 1999 ,		
967	Discrete-time LQ optimal repetitive control. 1999 ,		2
966	Input-output data based tracking control. 1999 ,		
965	Tangential-Contouring Controller for Biaxial Motion Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1999 , 121, 126-129	1.6	61
964	Theory and Applications of the Robust Cross-Coupled Control Design. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1999 , 121, 524-530	1.6	55

963	Real-time compensation of two-dimensional contour error in CNC machine tools. 1999,		11
962	Synthesis and stability of a multirate repetitive learning controller. 1999,		
961	Synthesis, stability analysis, and experimental implementation of a multirate repetitive learning controller. 1999,		1
960	Disturbance observer and feedforward design for a high-speed direct-drive positioning table. <i>IEEE Transactions on Control Systems Technology</i> , 1999 , 7, 513-526	4.8	383
959	Analysis and design of the integrated controller for precise motion systems. <i>IEEE Transactions on Control Systems Technology</i> , 1999 , 7, 706-717	4.8	40
958	Reducing resonances in profiling machine tools by generating smooth commands.		
957	Closed loop pneumatic position control using discrete time model regulation. 1999,		1
956	Adaptive calibration of feedforward controllers for laser profiling machines. 1999,		2
955	Multi-rate feedforward tracking control for plants with nonminimum phase discrete time models. 1999,		
954	Continuous zero phase error tracking controller with gain error compensation. 1999,		
953	Pre-filter design for high speed contouring machines.		1
952	Rejection of disk drive vibration and shock disturbances with a disturbance observer. 1999,		7
951	Design of discrete-time repetitive control system for pole placement and application. <i>IEEE/ASME Transactions on Mechatronics</i> , 1999 , 4, 110-118	5.5	34
950	An optimal and adaptive design of the feedforward motion controller. <i>IEEE/ASME Transactions on Mechatronics</i> , 1999 , 4, 428-439	5.5	44
949	Proposal of perfect tracking and perfect disturbance rejection control by multirate sampling and applications to hard disk drive control.		22
948	Solving discrete-time nonlinear servomechanism problem with feedforward neural networks.		1
947	Generalized Optimal Zero Phase Error Tracking Controller Design. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 1999 , 121, 165-170	1.6	10
946	Cost effective repetitive controllers for data storage devices. 1999 , 32, 891-896		1

945	High performance perfect tracking control based on multirate feedforward / feedback controllers with generalized sampling periods. 1999 , 32, 1079-1084		1
944	Mechatronics: From The 20th to 21st Century. 2000 , 33, 1-10		10
943	Velocity Estimator Based Compensation for Loudspeakers. 2000 , 33, 419-424		
942	Precise Speed Control of a Travelling Wave Ultrasonic Motor for Prosthetic Hands. 2000 , 33, 401-406		
941	Adaptive compensation of microactuator resonance in hard disk drives. 2000 , 36, 2247-2250		11
940	Machining parameters for an intelligent machining system for composite laminates. 2000 , 40, 415-426		86
939	High speed servo control of multi-axis machine tools. 2000 , 40, 539-559		67
938	Modified adaptive feedforward runout compensation for dual-stage servo system. 2000 , 36, 3581-3584		29
937	Coordination control and deposition planning for improving deposition accuracy in layered manufacturing process.		1
936	Repetitive learning controller for CVCF PWM DC/AC converter.		3
935	Experimental comparison of the performance of different chain conveyor controllers. 2000 , 214, 361-370		4
934	A cost effective repetitive controller and its design. 2000 ,		3
933	Robust high speed tracking servo system for optical disk system. 2000 ,		19
932	.		0
931	Improved track following in magnetic disk drives using a disturbance observer. <i>IEEE/ASME Transactions on Mechatronics</i> , 2000 , 5, 3-11	5.5	108
930	New hybrid controller for systems with deterministic uncertainties. <i>IEEE/ASME Transactions on Mechatronics</i> , 2000 , 5, 342-348	5.5	9
929	. 2000 , 16, 36-45		19
928	A new approach to bi-axial cross-coupled control.		1

927	A ZPET-repetitive speed controller for ultrasonic motors.		4
926	Discrete-time repetitive control system with multiple periods. 2000 ,		8
925	Proposal of seeking control of hard disk drives based on perfect tracking control using multirate feedforward control. 2000 ,		29
924	The design of precise motion systems by applying both the advanced controllers and the interpolators. 2000 ,		5
923	Position control of XY table in CNC machining center with non-rigid ballscrew. 2000 ,		6
922	Design of precise multi-axis motion control systems. 2000 ,		1
921	Robust performance control of electrohydraulic actuators for electronic cam motion generation. <i>IEEE Transactions on Control Systems Technology</i> , 2000 , 8, 220-227	4.8	36
920	Modified FIR filter with phase compensation technique to feedforward active noise controller design. <i>IEEE Transactions on Industrial Electronics</i> , 2000 , 47, 444-453	8.9	8
919	Digital repetitive learning controller for three-phase CVCF PWM inverter. <i>IEEE Transactions on Industrial Electronics</i> , 2001 , 48, 820-830	8.9	113
918	Contouring control of machine tool feed drive systems: a task coordinate frame approach. <i>IEEE Transactions on Control Systems Technology</i> , 2001 , 9, 130-139	4.8	167
917	A New Approach of Coordinated Motion Control Subjected to Actuator Saturation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 496-504	1.6	7
916	. <i>IEEE Transactions on Industrial Electronics</i> , 2001 , 48, 636-644	8.9	176
915	Robust feedforward tracking servo system for optical disk recording system.		14
914	A dual-stage control algorithm for magnetic disk drives based on coarse motion prediction.		
913	Iterative Learning Control for Nonlinear Nonminimum Phase Plants1. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 21-30	1.6	20
912	Comparison of Two Iterative Learning Concepts Applied on a Manipulator with Cogging Force Disturbances. 2001 , 34, 71-76		
911	High-speed contouring using a novel dynamic interpolation mechanism. 2001 , 41, 773-794		7
910	High speed CNC system design. Part I: jerk limited trajectory generation and quintic spline interpolation. 2001 , 41, 1323-1345		381

909	Torsional displacement compensation in position control for machining centers. <i>Control Engineering Practice</i> , 2001 , 9, 79-87	3.9	21
908	High speed CNC system design. Part II: modeling and identification of feed drives. 2001 , 41, 1487-1509		153
907	High speed CNC system design. Part III: high speed tracking and contouring control of feed drives. 2001 , 41, 1637-1658		98
906	. 2001 ,		15
905	Analysis and comparison of resonance compensation in dual-stage actuation system of HDDs. 2001 ,		1
904	Iterative learning control with advanced output data for nonminimum phase systems. 2001 ,		1
903	Multi-level optimization techniques for designing digital input shapers. 2001 ,		11
902	Pitch control of the space shuttle training aircraft. <i>IEEE Transactions on Control Systems Technology</i> , 2001 , 9, 542-551	4.8	8
901	FUZZY ADAPTIVE CONTROL OF NONLINEAR PROCESSES WITH FEEDFORWARD COMPENSATOR AND ITS APPLICATION. 2002 , 33, 171-187		1
900	Noise suppression in buffer-state iterative learning control, applied to a high precision wafer stage.		8
899	Concurrent Design of Input Shaping and Proportional Plus Derivative Feedback Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2002 , 124, 398-405	1.6	36
898	Synthesis, Stability Analysis, and Experimental Implementation of a Multirate Repetitive Learning Controller. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2002 , 124, 668-674	1.6	8
897	ADVANCED DIGITAL MOTION CONTROL BASED ON MULTIRATE SAMPLING CONTROL. 2002 , 35, 331-336		0
896	NONLINEAR INTERNAL MODEL CONTROL FOR MISO SYSTEMS BASED ON LOCAL LINEAR NEURO-FUZZY MODELS. 2002 , 35, 303-308		4
895	Robust motion control with the consideration algorithm of joint torque saturation for a redundant manipulator. 2002 , 16, 345-359		3
894	Design of feedforward filters for improving tracking performances of existing feedback control systems. 2002 ,		
893	Unified robust zero-error tracking control of CVCF PWM converters. 2002 , 49, 492-501		14
892	Robust feedforward track following control system for an optical disk.		3

891	Robust two degree-of-freedom add-on controller design for automatic steering. <i>IEEE Transactions on Control Systems Technology</i> , 2002 , 10, 137-148	4.8	46
890	Predictive control with enhanced robustness for precision positioning in frictional environment. <i>IEEE/ASME Transactions on Mechatronics</i> , 2002 , 7, 385-392	5.5	6
889	Contouring control of biaxial systems based on polar coordinates. <i>IEEE/ASME Transactions on Mechatronics</i> , 2002 , 7, 329-345	5.5	64
888	Estimation of the contouring error vector for the cross-coupled control design. <i>IEEE/ASME Transactions on Mechatronics</i> , 2002 , 7, 44-51	5.5	165
887	High-performance servo systems based on multirate sampling control. <i>Control Engineering Practice</i> , 2002 , 10, 773-781	3.9	35
886	Mechatronics: from the 20th to 21st century. <i>Control Engineering Practice</i> , 2002 , 10, 877-886	3.9	50
885	Tracking position control of piezoelectric actuators for periodic reference inputs. 2002 , 12, 669-684		45
884	A novel cross-coupling control design for Bi-axis motion. 2002 , 42, 1539-1548		97
883	A tool-path control scheme for five-axis machine tools. 2002 , 42, 79-88		33
882	Identification of acceleration deceleration profile of feed drive systems in CNC machines. 2003 , 43, 441-451		32
881	Implementation of a fast tool servo with repetitive control for diamond turning. 2003 , 13, 243-257		25
880	Trajectory planning for the tracking control of systems with unstable zeros. 2003 , 13, 127-139		10
879	Comparative analysis on resonance compensation in HDD dual-stage actuation systems. <i>IEEE Transactions on Industrial Electronics</i> , 2003 , 50, 1179-1186	8.9	16
878	. <i>IEEE Transactions on Control Systems Technology</i> , 2003 , 11, 375-382	4.8	73
877	Digital repetitive controlled three-phase PWM rectifier. 2003 , 18, 309-316		112
876	A design method of perfect tracking control for discrete-time systems using multirate control.		
875	Robust feedforward track following control system for an optical disk drive system.		4
874	Synchronizing dual-drive gantry of chip mounter with LQR approach.		3

873	Discrete-Time Adaptive Repetitive Control and Its Application to a Linear BLDC Motor. 2003,			1
872	Control of a flexible manipulator tip using a multirate repetitive learning controller based on filtered tip reference input.			
871	Design of a Repetitive Control System for a Piezoelectric Actuator Based on the Inverse Hysteresis Model. 2003,			
870	Multirate repetitive control and applications.			7
869	Time-frequency analysis of a motion system with learning control.			10
868	Robust tracking servo system considering force disturbance for optical disk recording system.			1
867	Robust Perfect Tracking Control With Discrete Sliding Mode Controller. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2003 , 125, 27-32	1.6		23
866	Model-based feedforward for motion systems.			22
865	Phase correction for learning feedforward control.			
864	High Speed Motion Control Method of Industrial Robot Based on Dynamic Torque Compensation and Two-Degrees-of-Freedom Control System. <i>IEEJ Transactions on Industry Applications</i> , 2003 , 123, 525-532	0.2		18
863	Positioning and Tracking Control of an X-Y Table with Sliding Mode Control. 2003 , 36, 157-162			1
862	A new discrete-time voltage controller based on the internal model principle for three-phase voltage source PWM inverters with /spl Delta/Y output transformer.			2
861	Control of a Non-Orthogonal Reconfigurable Machine Tool. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2004 , 126, 397-405	1.6		6
860	Perfectly Matched Feedback Control and Its Integrated Design for Multiaxis Motion Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2004 , 126, 547-557	1.6		35
859	Advanced controller design and implementation of a sensorized microgripper for micromanipulation. 2004,			1
858	Design and implementation of command and friction feedforward control for CNC motion controllers. 2004 , 151, 13-20			21
857	Fractional Order Disturbance Observer for Robust Vibration Suppression. 2004 , 38, 355-367			52
856	Model-based controller design for machine tool direct feed drives. 2004 , 44, 465-477			45

855	Two-degree-of-freedom \mathcal{H}_2 -optimal tracking with preview. <i>Automatica</i> , 2004 , 40, 155-162	5.7	15
854	. <i>IEEE Transactions on Control Systems Technology</i> , 2004 , 12, 12-20	4.8	22
853	Design of feedforward filters for improving tracking performances of existing feedback control systems. <i>IEEE Transactions on Control Systems Technology</i> , 2004 , 12, 742-749	4.8	7
852	High performance motion control of linear motors based on multirate adaptive robust control.		0
851	.		
850	Designing Robust Repetitive Controllers. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2004 , 126, 865-872	1.6	18
849	The integrated linear and nonlinear motion control design for precise CNC machine tools.		2
848	A survey of repetitive control.		25
847	Improving contour accuracy by Fuzzy-logic enhanced cross-coupled precompensation method. 2004 , 20, 65-76		55
846	Switching based repetitive control for hard disk drives: experiments on RIDR and RPTC methods.		3
845	Robust tracking control of optical disk recording system based on ZPET control and sudden disturbance observer.		
844	Experimental study of time-frequency based ILC.		
843	On noise- and period-time sensitivity in high order repetitive control. 2004 ,		7
842	Optimal Cross-Coupled Synchronizing Control of Dual-Drive Gantry System for a SMD Assembly Machine. 2004 , 47, 939-945		24
841	Comparison of Standard and Lifted ILC on a Motion System. 2004 , 37, 205-210		2
840	RRO COMPENSATION OF HARD DISK DRIVES WITH MULTIRATE REPETITIVE PTC. 2005 , 38, 127-132		1
839	Precision Tracking Controller Design for High Speed Feed Drives. 2005 , 657		5
838	Digital repetitive plug-in controller for odd-harmonic periodic references and disturbances. <i>Automatica</i> , 2005 , 41, 153-157	5.7	75

837	Theory and application of a combined self-tuning adaptive control and cross-coupling control in a retrofit milling machine. 2005 , 15, 193-211		49
836	Tracking and contour error control in CNC servo systems. 2005 , 45, 301-326		114
835	Adaptive interpolation scheme for NURBS curves with the integration of machining dynamics. 2005 , 45, 433-444		102
834	New Control Techniques Based on State Space Observers for Improving the Precision and Dynamic Behaviour of Machine Tools. 2005 , 54, 393-396		21
833	Trajectory planning and feedforward design for electromechanical motion systems. <i>Control Engineering Practice</i> , 2005 , 13, 145-157	3.9	165
832	Demonstration of the internal model principle by digital repetitive control of an educational laboratory plant. 2005 , 48, 73-80		59
831	A loop shaping perspective for tuning controllers with adaptive feedforward cancellation. 2005 , 29, 27-40		40
830	A design based on final-state control for residual vibrationless seeking in hard disk drives. 2005 , 11, 688-695		4
829	Model-based reference trajectory generation for tip-based learning controller. 2005 , 19, 357-363		4
828	Ein neues Vorfilter zur Verbesserung des Folgeverhaltens von Bewegungsregelungen. 2005 , 122, 308-313		
827	Zero phase two-degrees of freedom H_{∞} robust tracking control for permanent magnet linear synchronous motor.		
826	.		1
825	Robust internal model control with feedforward controller for a high-speed motion platform. 2005 ,		3
824	Adaptive nonlinear contour coupling control for a machine tool system.		2
823	The influence of disturbances in iterative learning control.		2
822	A simplified approach to the design of nonlinear disturbance observer for axial motion systems.		
821	Improvement of the Performance in Machine Tools by Means of State Space Control Strategies.		2
820	A Two Parameter Robust Linear Parameter Varying Repetitive Control Approach to Variable Speed Electronic CAM Follower Problem. 2005 , 109		0

819	Modeling and Controller Tuning Techniques for Feed Drive Systems. 2005 , 669		16
818	A minimax approach to robust repetitive learning control.		0
817	Multirate adaptive robust control for discrete-time non-minimum phase systems and application to linear motors. <i>IEEE/ASME Transactions on Mechatronics</i> , 2005 , 10, 371-377	5.5	30
816	Identification and control of a sensorized microgripper for micromanipulation. <i>IEEE/ASME Transactions on Mechatronics</i> , 2005 , 10, 601-606	5.5	22
815	Laser beam raster scan under variable process speed - an application of time varying model reference repetitive control system.		
814	Force sensorless robust tracking servo system suppressing periodic disturbance and sudden disturbance for optical disk system. 2005 ,		3
813	Power amplifier design in magnetic suspension system. 2005 ,		
812	On real-time contour error estimation for contour following tasks.		7
811	Application of active disturbance rejection to tracking control of a fast tool servo system.		1
810	A Three-Phase PWM Inverter For Double Conversion UPS That Complies With the Standard IEC 62040-3.		0
809	Concerning "Odd-harmonic digital repetitive control of a single-phase current active filter". 2005 , 20, 511-513		3
808	Learning-based identification and iterative learning control of direct-drive robots. <i>IEEE Transactions on Control Systems Technology</i> , 2005 , 13, 537-549	4.8	28
807	On the tracking performance improvement of optical disk drive servo systems using error-based disturbance observer. <i>IEEE Transactions on Industrial Electronics</i> , 2005 , 52, 270-279	8.9	48
806	Perfect tracking control using multirate control in magnetic levitation system.		
805	Zero-phase odd-harmonic repetitive controller for a single-phase PWM inverter. 2006 , 21, 193-201		121
804	Design and Implementation of a New Approach Based on the Error Feedforward Compensation for Motion Controller. 2006 ,		1
803	Removing non-repetitive disturbances in iterative learning control by wavelet filtering. 2006 ,		4
802	Robust tracking servo system considering force disturbance for the optical disk recording system. <i>IEEE Transactions on Industrial Electronics</i> , 2006 , 53, 838-847	8.9	41

801	Development of command-based iterative learning control algorithm with consideration of friction, disturbance, and noise effects. <i>IEEE Transactions on Control Systems Technology</i> , 2006 , 14, 511-518	4.8	30
800	The Motion Message Estimator in Real-Time Network Control Systems. 2006 ,		1
799	Digital PLL-based adaptive repetitive control.		16
798	Design and Control of Fast Tool Servo for Boring of Engine Piston Pin Holes. 2006 , 1007		1
797	Nominal and Robust Feedforward Design With Time Domain Constraints Applied to a Wafer Stage. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2006 , 128, 204-215	1.6	16
796	THE WINDUP PROBLEM IN REPETITIVE CONTROL: A SIMPLE ANTI-WINDUP STRATEGY. 2006 , 39, 307-311		2
795	Hierarchical optimal force/position/contour control of machining processes. <i>Control Engineering Practice</i> , 2006 , 14, 909-922	3.9	8
794	Virtual Computer Numerical Control System. 2006 , 55, 399-402		26
793	Precision tracking control of a horizontal arm coordinate measuring machine in the presence of dynamic flexibilities. <i>International Journal of Advanced Manufacturing Technology</i> , 2006 , 27, 960-968	3.2	5
792	Position command shaping control in a retrofitted milling machine. 2006 , 46, 293-303		21
791	Virtual CNC system. Part II. High speed contouring application. 2006 , 46, 1124-1138		102
790	Virtual CNC system. Part I. System architecture. 2006 , 46, 1107-1123		74
789	Motion stages for electronic packaging design and control. 2006 , 13, 51-61		29
788	Robust feedforward control system considering sudden disturbance for optical disk recording system. 2006 , 156, 60-68		
787	The Application of ZPETC Based on Optimal Design of L2-Norm in Servo Tracking Control. 2006 ,		
786	Adaptive Contouring Control for High-Accuracy Tracking Systems. 2006 ,		3
785	Iterative learning control with advanced output data for nonlinear non-minimum phase systems. 2006 , 37, 1051-1058		4
784	Contour Controller Design for Two-Dimensional Stage System with Friction. 2006 , 505-507, 1267-1272		1

783	Study on the Compound Fuzzy Motion Control for the Ultra Precision Machine Tools. 2006 , 315-316, 813-816		
782	Iterative Learning Control and Repetitive Control in Hard Disk Drive Industry - A Tutorial. 2006 ,		21
781	Zero Phase Error Robust Controller Design Based on Neural Compensation. 2006 ,		
780	Robust Tracking Control of Optical Disk Recording System based on Sudden Disturbance Observer. 2006 ,		6
779	Settle time performance comparisons of stable approximate model inversion techniques. 2006 ,		8
778	Model Inversion Architectures for Settle Time Applications with Uncertainty. 2006 ,		11
777	Position Synchronized Control of Dual Linear Motors Servo System Using Fuzzy Logic. 2006 ,		0
776	Adaptive-repetitive control of a hard disk drive. 2007 ,		10
775	Torsion Vibration Analysis of Lead-screw Feed Drives with Changeable Table Position and Work-piece Mass. 2007 ,		2
774	A Novel Repetitive Controlled 3-Phase CVCF PWM Inverter for UPS. 2007 ,		2
773	High Performance Motion Tracking Control for Electronic Manufacturing. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2007 , 129, 767-776	1.6	26
772	Precision Motion Control Methodology for Complex Contours. 2007 , 129, 1060-1068		13
771	Tracking Control of Nonminimal Phase System Without using Preview Information of the Desired Output. 2007 ,		2
770	Research on Robust Control Strategy for High-Accuracy Hydraulic Flight Motion Simulator. 2007 ,		1
769	High-Speed Tracking Servo Using Zero Phase Error Tracking-Feed-Forward Method for Professional-Use Optical Disks over 10000 rpm. 2007 , 46, 3765-3770		16
768	Optimal Design of Spline-Based Feedforward for Trajectory Tracking. 2007 ,		5
767	Characterization and Compensation of Disturbances Caused by Head-Disk Contact in Hard Disk Drives. 2007 ,		2
766	. 2007 ,		1

765	Fixed Structure Feedforward Controller Tuning Exploiting Iterative Trials, Applied to a High-Precision Electromechanical Servo System. 2007,		6
764	DEALING WITH PERIODIC DISTURBANCES IN CONTROLS OF MECHANICAL SYSTEMS. 2007, 40, 187-195		
763	. <i>IEEE Transactions on Industrial Electronics</i> , 2007, 54, 2120-2136	8.9	46
762	Contouring Control of Smooth Paths for Multiaxis Motion Systems Based on Equivalent Errors. <i>IEEE Transactions on Control Systems Technology</i> , 2007, 15, 1151-1158	4.8	66
761	Precision Motion Control Methodology for Complex Contours. 2007,		
760	Compensation of Dominant Frequency Components of Nonrepeatable Disturbance in Hard Disk Drives. 2007, 43, 3756-3762		19
759	Modeling and Identification for High-Speed Milling Machines. 2007,		
758	Two-mode ILC with pseudo-downsampled learning in high frequency range. 2007, 80, 349-362		13
757	Design of Tracking Controller for Holographic Digital Data Storage. 2007,		
756	Research of Control of Two-Degree-of-Freedom Pneumatic Trajectory Tracking System. 2007,		
755	Two-Degree-of-Freedom Based Cross-Coupled Control for High-Accuracy Tracking Systems. 2007,		2
754	Combined Feedforward/Feedback Control of Atomic Force Microscopes. 2007,		31
753	Coordination Control of Positioning and Deposition in Layered Manufacturing. <i>IEEE Transactions on Industrial Electronics</i> , 2007, 54, 651-659	8.9	11
752	Motion Controller Design for Contour-Following Tasks Based on Real-Time Contour Error Estimation. 2007, 54, 1686-1695		111
751	Unified Approximate Tracking Control of Linear Systems with Unacceptable Zeros. 2007, 19, 239-250		2
750	Design of noise and period-time robust high-order repetitive control, with application to optical storage. <i>Automatica</i> , 2007, 43, 2086-2095	5.7	114
749	Rapid identification technique for virtual CNC drives. 2007, 47, 1381-1392		27
748	Biaxial contouring control with friction dynamics using a contour index approach. 2007, 47, 1542-1555		49

747	Adaptive parameter identification of servo control systems with noise and high-frequency uncertainties. <i>Mechanical Systems and Signal Processing</i> , 2007 , 21, 1437-1451	7.8	14
746	Disturbance-observer-based adaptive feedforward cancellation of torque ripples in harmonic drive systems. 2007 , 90, 95-106		16
745	Enhanced disturbance suppression in sampled-data systems and its application to high density data storage servos. 2007 , 13, 911-921		2
744	Pseudo-downsampled iterative learning control. 2008 , 18, 1072-1088		12
743	Iterative learning control with wavelet filtering. 2008 , 18, 1052-1071		10
742	Performance improvement of repetitive controlled PWM inverters: A phase-lead compensation solution. 2008 , 38, n/a-n/a		12
741	Short-span seeking control of hard disk drive with vibration suppression PTC. 2008 , 162, 66-72		1
740	Iterative learning control and repetitive control in hard disk drive industry: A tutorial. 2008 , 22, 325-343		96
739	Measuring the higher order sinusoidal input describing functions of a non-linear plant operating in feedback. <i>Control Engineering Practice</i> , 2008 , 16, 101-113	3.9	16
738	Dealing with periodic disturbances in controls of mechanical systems. 2008 , 32, 193-199		59
737	Adaptive two-degree-of-freedom control of feed drive systems. 2008 , 48, 437-445		10
736	Contouring accuracy improvement using cross-coupled control and position error compensator. 2008 , 48, 1444-1453		70
735	Analysis and applications of the motion message estimator for network control systems. 2008 , 10, 45-54		7
734	Design of an Optimal Unknown Input Observer for Load Compensation in Motion Systems. 2008 , 3, 204-215		8
733	ERROR SPACE MOTION CONTROL METHODOLOGY FOR COMPLEX CONTOURS. 2008 , 7, 20-28		5
732	Adaptive Iterative Learning Control for High Precision Motion Systems. <i>IEEE Transactions on Control Systems Technology</i> , 2008 , 16, 1075-1082	4.8	55
731	Linear Phase Lead Compensation Repetitive Control of a CVCF PWM Inverter. <i>IEEE Transactions on Industrial Electronics</i> , 2008 , 55, 1595-1602	8.9	148
730	Analysis and design of repetitive controller for harmonic elimination in PWM voltage source inverter systems. 2008 , 1, 497		47

729	Nonlinear dynamic contouring control for biped robot walking. 2008,		
728	. 2008,		2
727	A calculation method on dynamic force feedback in complex free-form contour pre-generation. 2008,		0
726	A novel algorithm for unknown periodic disturbance cancellation in HDDs. 2008,		2
725	Position loop-based cross-coupled control for high-speed machining. 2008,		2
724	Walking pattern generation for Humanoid robots with LQR and feedforward control method. 2008,		2
723	Single rate fine perfect tracking controller for high speed optical disk system. 2008,		0
722	Controller Design Procedure for Two-Mass Systems With Single Flexible Mode. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2008 , 130,	1.6	2
721	Fixed Structure Feedforward Controller Design Exploiting Iterative Trials: Application to a Wafer Stage and a Desktop Printer. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2008 , 130,	1.6	81
720	RRO compensation of hard disk drives with RPTC considering correlation of adjacent tracks. 2008,		
719	The effect of nonminimum-phase zero locations on the performance of feedforward model-inverse control techniques in discrete-time systems. 2008,		41
718	Adaptive Compensation of Spatial Contour Error Based on Neural Networks in Three-Axis Machining. 2008 , 392-394, 7-12		
717	High-Speed Recording up to 15,000 rpm Using Thin Optical Disks. 2008 , 47, 5822-5827		23
716	Experimental studies on a micromanipulator for micro/nano manipulation. 2008,		
715	Adaptive ZPETC method for dual-stage actuator controller design in miniaturized optical disc drive. 2008,		2
714	Taylor series expansion error compensation for a bi-axial CNC machine. 2008,		0
713	Head-disk spacing control for an advanced rotary tester. 2008,		
712	Robust high-order repetitive control. 2008,		3

711	A Novel Settling Controller for Dual-Stage Servo Systems. 2008 , 44, 3757-3760	4
710	Semi-automatic tuning of PID gains for Atomic Force Microscopes. 2008 ,	31
709	. 2008 ,	
708	Development of Cutting Device with Enlargement Mechanism of Displacement -Application of Non-Circle Cutting-. 2008 , 2, 474-481	1
707	Robust Discrete-Time Output Tracking Controller Design for Nonminimum Phase Systems. 2008 , 2, 950-961	4
706	Design of Seeking Control Based on Two-Degree-of-Freedom Controller Using Frequency Shaped Final-State Control. 2008 , 41, 1803-1808	1
705	Nano-Positioning of a Electromagnetic Scanner with a MEMS Capacitive Sensor. 2008 , 41, 3130-3135	
704	Architectures for Tracking Control in Atomic Force Microscopes. 2008 , 41, 8236-8250	8
703	Use of Cranes in System Dynamics and Controls Education. 2008 , 41, 9099-9104	4
702	Design and Simulation on Improved Repetitive Controller for Inverted Power Supply. 2008 , 41, 11990-11994	
701	Position Tracking Control with Velocity from Accelerometer and Encoder. 2008 , 41, 14828-14833	1
700	Short-span seeking control of hard disk drive with learning based PTC in acceleration and deceleration period. 2009 ,	1
699	Walking pattern generation method with feedforward and feedback control for humanoid robots. 2009 ,	3
698	An analysis and synthesis of internal model principle type controllers. 2009 ,	3
697	Adaptive rejection of stochastic and deterministic sinusoidal disturbances with unknown frequency. 2009 ,	1
696	Multiple-period adaptive-repetitive control of a hard disk drive. 2009 ,	1
695	Iterative learning based repetitive disturbance rejection with application to color registration error reduction in flatbed document scanners. 2009 ,	1
694	l-delay input reconstruction for discrete-time linear systems. 2009 ,	4

693 . 2009,

692 Zero phase error tracking control with friction compensation based motion control system. 2009, 0

691 The study of accurate digital control for precision AC servo table. 2009,

690 Amplitude adjusting filtering zero phase error tracking sliding mode control for piston lathe linear servo system. 2009,

689 High-speed tracking servo of modified ZPET-feedforward control for optical disk drives. 2009, 4

688 High-speed high-precision control of atomic force microscope by surface topography learning observer. 2009, 2

687 Design of distributed cross-coupled controller based on motion control bus. 2009, 1

686 Repetitive Control System Under Actuator Saturation and Windup Prevention. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, 2009, 131, 1.6 18685 A Review of Feedforward Control Approaches in Nanopositioning for High-Speed SPM. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, 2009, 131, 1.6 251

684 Modeling and Control of Contouring Errors for Five-Axis Machine Tools Part II: Precision Contour Controller Design. 2009, 131, 27

683 Force sensorless robust tracking servo system suppressing periodic disturbance and sudden disturbance for optical disk system. 2009, 166, 82-90

682 Discrete-time controller design to attenuate effects of external disturbances. 2009, 15, 1645-1651 5

681 Discrete-time robust adaptive multi-axis control for feed drive systems. 2009, 49, 1204-1213 5

680 Repetitive tracking position control on LonWorks/IP network with time varying delay. 2009, 7, 930-938 1

679 Contouring accuracy improvement using a tangential contouring controller with a fuzzy logic-based feedrate regulator. *International Journal of Advanced Manufacturing Technology*, 2009, 41, 75-85 3.2 5678 Applications of integrated motion controllers for precise CNC machines. *International Journal of Advanced Manufacturing Technology*, 2009, 44, 906-920 3.2 20

677 Short-Span seeking control of hard disk drives with multirate vibration suppression perfect tracking control. 2009, 4, 184-191 1

676 Servo techniques for optical disk drives High-speed and precise optical beam-positioning control 2009, 4, 240-247 1

675	Improving contouring accuracy by tuning gains for a bi-axial CNC machine. 2009 , 49, 395-406		41
674	Cyclic pseudo-downsampled iterative learning control for high performance tracking. <i>Control Engineering Practice</i> , 2009 , 17, 957-965	3.9	9
673	A new tracking controller for discrete-time SISO non minimum phase systems. 2009 , 12, n/a-n/a		
672	A comparison of control architectures for atomic force microscopes. 2009 , 11, 175-181		44
671	Semi-automatic tuning of PID gains for atomic force microscopes. 2009 , 11, 188-195		19
670	A fuzzy cross-coupled linear quadratic regulator for improving the contour accuracy of bi-axis machine tools. 2009 ,		0
669	Repetitive control applied to a walking piezo actuator. 2009 ,		3
668	Nonminimum Phase Dynamic Inversion for Settle Time Applications. <i>IEEE Transactions on Control Systems Technology</i> , 2009 , 17, 989-1005	4.8	78
667	A Passive Repetitive Controller for Discrete-Time Finite-Frequency Positive-Real Systems. 2009 , 54, 800-804		10
666	Approximate Input Reconstruction for Diagnosing Aircraft Control Surfaces. 2009 ,		0
665	Repetitive control with Prandtl-Ishlinskii hysteresis inverse for piezo-based nanopositioning. 2009 ,		15
664	A Synchronization Approach for the Minimization of Contouring Errors of CNC Machine Tools. 2009 , 6, 720-729		38
663	A 252-Mb/s Recording Experiment Using Flexible Optical Disks for Broadcast Use. 2009 , 45, 2190-2193		20
662	Adaptive inverse control for settling performance improvements. 2009 ,		3
661	Accurate tracking control of a linear fast tool servo unit for noncircular cutting. 2009 ,		0
660	Self-tuning controller design for motion control systems. 2009 ,		
659	A Neural-Networks-Based Adaptive Disturbance Rejection Method and Its Application to the Control of Hard Disk Drives. 2009 , 45, 2140-2150		13
658	A walking pattern generation method with feedback and feedforward control for humanoid robots. 2009 ,		2

657	RRO Compensation of Hard Disk Drives With Multirate Repetitive Perfect Tracking Control. <i>IEEE Transactions on Industrial Electronics</i> , 2009 , 56, 3825-3831	8.9	34
656	Generalised repetitive control: relaxing the period-delay-based structure. 2009 , 3, 1528-1536		8
655	A New Method of Generating Pulse Sequence for Numerical Controllers -with Velocity and Acceleration Bounds Adapting to the Servomotor System. 2009 , 3, 269-276		
654	. 2010 ,		
653	Adaptive Repetitive Control Systems for Fast Rejection of Periodic Disturbances with Uncertain Multiple Periods. 2010 , 43, 150-155		
652	Application of Perfect Tracking Control to Large-Scale High-Precision Stage. 2010 , 43, 188-193		4
651	An Indirect Adaptive Approach to Reject Multiple Narrow-Band Disturbances in Hard Disk Drives. 2010 , 43, 44-49		3
650	Directional Repetitive Control of a Metrological AFM. 2010 , 43, 206-211		
649	Analysis of Residual Vibrations above the Nyquist Frequency in Head-Positioning Control of Hard Disk Drives. 2010 , 43, 76-83		
648	Control of Machine Tools and Machining Processes. 2010 , 10-1-10-18		
647	Constrained identification of virtual CNC drives using a genetic algorithm. <i>International Journal of Advanced Manufacturing Technology</i> , 2010 , 50, 275-288	3.2	7
646	Nonminimum phase adaptive inverse control for settle performance applications. 2010 , 20, 35-44		25
645	Development of a 3-axis desktop milling machine and a CNC system using advanced modern control algorithms. 2010 , 11, 39-47		23
644	DISCRETE-TIME OBSERVER-BASED OUTPUT TRACKING CONTROLLER DESIGN FOR NONMINIMUM PHASE SYSTEMS WITH PERTURBATIONS. 2010 , 9, 435-441		
643	Nano-positioning of an electromagnetic scanner with a MEMS capacitive sensor. 2010 , 20, 27-34		12
642	Improving CNC contouring accuracy by integral sliding mode control. 2010 , 20, 442-452		30
641	Robust compensation of elastic deformations in ball screw drives. 2010 , 50, 559-574		44
640	A new method for synthesizing multiple-period adaptive repetitive controllers and its application to the control of hard disk drives. <i>Automatica</i> , 2010 , 46, 1186-1195	5.7	28

639	Compound Control for Hydraulic Flight Motion Simulator. 2010 , 23, 240-245	13
638	The Design of QFT Robust Compensators with Magnitude and Phase Specifications. 2010 , 2010, 1-20	5
637	Electro-Hydraulic Fully Flexible Valve Actuation System for Engine Test Cell. 2010 ,	2
636	On the Design of Discrete Time Repetitive Controllers in Closed Loop Configuration. 2010 , 51, 333-344	2
635	Controlador vetorial neural para mesa de coordenadas XY. 2010 , 21, 406-424	1
634	Model Predictive Approach to Precision Contouring Control for Feed Drive Systems. 2010 , 6, 844-851	
633	Analysis and Compensation Following Error of Feed Drive in CNC. 2010 , 26-28, 591-597	0
632	Closed-Loop Identification and Composed Controller Design for Precise Machining. 2010 , 97-101, 3139-3145	1
631	. 2010 ,	1
630	Model predictive control with repetitive control for periodic signal tracking and constraint handling of fast sampled-data control systems. 2010 ,	
629	Sensitivity reduction of adaptive repetitive control system with asymptotical rejection against uncertain periodic disturbance. 2010 ,	1
628	Positioning control for Piezo scanner using multirate perfect inverse model based iterative learning control. 2010 ,	6
627	Anti-windup schemes comparison for digital repetitive control. 2010 ,	
626	Self-Tuning Zero Phase Error Tracking Control of AC Permanent Magnet Linear Synchronous Motor Servo System. 2010 ,	
625	Short-span seeking control of hard disk drive based on integral type learning PTC. 2010 ,	1
624	Zero phase error tracking control system with multi harmonics disturbance suppression loop. 2010 ,	3
623	Enhanced feedforward control of non-minimum phase systems for tracking predefined trajectory. 2010 , 83, 2440-2452	5
622	. 2010 ,	

621	Optimal feedforward controller design for periodic inputs. 2010 , 83, 1044-1053		7
620	Optimal Sliding Mode Dual-Stage Actuator Control in Computer Disk Drives. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2010 , 132,	1.6	5
619	Application of Combined Feedforward and Feedback Controller With Shaped Input to Benchmark Problem. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2010 , 132,	1.6	4
618	Mechatronic Modeling and Analyzing for Feed Servo Control System Based on Torsion Dynamics of Lead-Screw. 2010 ,		
617	Error Prediction Robust Tracking Control System Suppressing Harmonics Disturbance for Optical Disk Recording System. 2010 , 49, 08KC08		9
616	On the Theory and Design of Linear Repetitive Control Systems. 2010 , 16, 447-496		53
615	Precision Control and Compensation of Servomotors and Machine Tools via the Disturbance Observer. <i>IEEE Transactions on Industrial Electronics</i> , 2010 , 57, 420-429	8.9	101
614	Development and Assessment of a Novel Decoupled XY Parallel Micropositioning Platform. <i>IEEE/ASME Transactions on Mechatronics</i> , 2010 , 15, 125-135	5.5	88
613	Design of the Tracking Controller for Holographic Digital Data Storage. <i>IEEE/ASME Transactions on Mechatronics</i> , 2010 , 15, 242-252	5.5	6
612	Control of the DLC coated ball bearing linear stage in high vacuum. 2010 ,		
611	A fractional-order synchronization of two networked motion control systems. 2010 ,		2
610	Enhanced feedforward control of non-minimum phase systems for tracking predefined trajectory. 2010 ,		0
609	Position tracking control of a direct-drive submersible grinding robot: A comparative study. 2010 ,		5
608	DC motor speed regulation using repetitive control. 2010 ,		1
607	Discrete sliding mode current control of grid-connected three-phase PWM converters with LCL filter. 2010 ,		12
606	. 2011 ,		14
605	Real-time control of non-minimum phase electro-hydraulic system using trajectory-adaptive ZPETC. 2011 ,		2
604	An error compensation method for multi-axis machining based on the actual contour measurement. 2011 ,		

603	Adaptive Repetitive Control of System Subject to Periodic Disturbance with Time-Varying Frequency. 2011,	13
602	Iterative learning control for near-field scanning optical microscope applications. 2011,	
601	Optimizing the performance of a novel seesaw-swivel actuator for a holographic module. 2011,	
600	Modeling and controller design for non-minimum phase system with application to XY-table. 2011,	1
599	Tracking control for electro-hydraulic actuator using ZPETC. 2011,	1
598	Lift force control of a flapping-wing microrobot. 2011,	12
597	Adding Feedforward Blade Pitch Control for Load Mitigation in Wind Turbines: Non-Causal Series Expansion, Preview Control, and Optimized FIR Filter Methods. 2011,	26
596	Feed drive control considering multi-axis coupling effects and extension to contouring control. 2011,	
595	Unobservable Settling Vibration on Head-Positioning Control in Hard Disk Drives. 2011, 44, 4052-4060	
594	Combined Feedforward/Feedback Control for Tape Head Track-Following Servo Systems. 2011, 44, 4040-4045	
593	State Space Disturbance Compensation for Robust Fast Servo Track Writer Seek Control*. 2011, 44, 5291-5296	
592	A Survey of Control Issues in Optical Data Storage Systems. 2011, 44, 854-868	7
591	Measurement and Control of Machine Tool Motion. 2011, 77, 2814-2821	1
590	Analysis of Residual Vibrations beyond the Nyquist Frequency in Sampled-Data Positioning Control System. 2011, 5, 1444-1459	3
589	Spiral Servo Writing in Hard Disk Drives Using Iterative Learning Based Tracking Control. 2011, 44, 5279-5285	1
588	Research of Compound Controller for Flight Simulator with Disturbance Observer. 2011, 24, 613-621	16
587	Bias Compensation for Fast Servo Track Writer Seek Control. 2011, 47, 1937-1943	9
586	A Novel Contour Error Estimation for Position Loop-Based Cross-Coupled Control. <i>IEEE/ASME Transactions on Mechatronics</i> , 2011, 16, 643-655	5.5 105

585	Delay-varying repetitive control with application to a walking piezo actuator. <i>Automatica</i> , 2011 , 47, 1737-1743	17	
584	Machine tool feed drives. 2011 , 60, 779-796		326
583	Positioning and Tracking Control of an XY table. 2011 ,		0
582	Pulse shaping in ISO/IEC14443 measurement systems using inverse system parameters for feed-forward compensation. 2011 ,		1
581	l-Delay Input and Initial-State Reconstruction for Discrete-Time Linear Systems. 2011 , 30, 233-262		20
580	Experimental implementation of Taylor series expansion error compensation on a bi-axial CNC machine. <i>International Journal of Advanced Manufacturing Technology</i> , 2011 , 53, 285-299	3.2	13
579	Observer-based robust controller design and realization of a gantry stage. 2011 , 21, 185-203		21
578	Cross-coupling position command shaping control in a multi-axis motion system. 2011 , 21, 625-632		32
577	Dynamics and contouring control of a 3-DoF parallel kinematics machine. 2011 , 21, 215-226		24
576	Precision tracking control of a biaxial piezo stage using repetitive control and double-feedforward compensation. 2011 , 21, 239-249		40
575	Contouring controller design based on iterative contour error estimation for three-dimensional machining. 2011 , 27, 802-807		43
574	Directional Repetitive Control of a Metrological AFM. <i>IEEE Transactions on Control Systems Technology</i> , 2011 , 19, 1622-1629	4.8	7
573	Improvement of settling performance by mode switching control with split Initial Value Compensation based on Input Shaper. 2011 ,		
572	. 2011 ,		
571	Feedforward control for high precision linear servo system. 2011 ,		
570	High performance motion controller design for linear piezoelectric ceramic motors. 2011 ,		
569	Robust Tracking Control Based QFT and Pade Approximation for Flight Simulator. 2011 , 383-390, 7600-7606		
568	LIDAR-based FX-RLS feedforward control for wind turbine load mitigation. 2011 ,		2

567	A new control method with perfect tracking control for flight simulator. 2011,	2
566	Positioning Control System Based on ZPETC and Optimal Control Method for Plant with Dead-Time. 2012, 152-154, 1795-1800	
565	Hysteresis compensation and high-performance tracking control of piezoelectric actuators. 2012, 226, 1050-1059	3
564	Phase compensation multiple resonant control of single-phase PWM inverter. 2012,	0
563	FES based rehabilitation of the upper limb using input/output linearization and ILC. 2012,	11
562	PID contour tracking control in position domain. 2012,	2
561	Point-to-point trajectory tracking with two-degree-of-freedom robust control for a non-minimum phase electro-hydraulic system. 2012,	2
560	A new Robust Delay-Variable Repetitive Controller with application to media transport in a printer. 2012,	
559	Wing trajectory control for flapping-wing microrobots using combined repetitive and minimum-variance adaptive methods. 2012,	4
558	Synchronization of tool tip and tool orientation contour errors in five-axis machining. 2012,	2
557	. 2012,	7
556	Feed-forward control of non-minimum phase XY table system using Trajectory Fuzzy-RLS Hybrid ZPETC. 2012,	
555	Adaptive feedforward zero phase error tracking control with model reference for high precision X-Y table. 2012,	0
554	Feedforward control for disturbance rejection: Model matching and other methods. 2012,	9
553	An enhanced repetitive control algorithm using the structure of disturbance observer. 2012,	5
552	Multiple harmonics control of single-phase PWM rectifiers. 2012,	1
551	Load-side acceleration control for industrial robot arm with axial torsion. 2012,	1
550	A composite pulsating controller for achieving high-performance positioning. 2012, 34, 26-55	

549	Contouring Performance Improvement of Biaxial Motion Control Systems Using Friction and Disturbance Compensation. 2012 , 579, 287-296		0
548	Learning Based Cross-Coupled Control for Multi-Axis High Precision Positioning Systems. 2012 ,		4
547	Robust Fast Seek Control of a Servo Track Writer Using a State Space Disturbance Observer. <i>IEEE Transactions on Control Systems Technology</i> , 2012 , 20, 346-355	4.8	21
546	A Discrete-Time Single-Parameter Combined Feedforward/Feedback Adaptive-Delay Algorithm With Applications to Piezo-Based Raster Tracking. <i>IEEE Transactions on Control Systems Technology</i> , 2012 , 20, 416-423	4.8	13
545	Predictive Contour Control With Adaptive Feed Rate. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 669-679	5.5	47
544	References. 2012 , 407-420		
543	Adaptive feedforward Zero Phase Error Tracking Control for minimum phase and non-minimum phase systems - XY table real-time application. 2012 ,		2
542	Discrete-time dual peak control for disturbance rejection. 2012 , 18, 1645-1650		1
541	Control repetitivo digital de sistemas con frecuencia incierta o variante en el tiempo. 2012 , 9, 219-230		2
540	. 2012 ,		1
539	Trajectory ZPETC design using comparing coefficients method: The studies on the effects of zero locations to tracking performance. 2012 ,		0
538	Robust trajectory tracking controller for XY table. 2012 ,		1
537	Trajectory tracking control method based on zero-phase minimum-phase factorization for nonminimum-phase continuous-time system. 2012 ,		3
536	Adaptive Integrated Contouring Control of Biaxial Systems. 2012 ,		
535	Real-time adaptive feedforward Zero Phase Error Tracking Control for X-Y motion. 2012 ,		1
534	Precision Tracking Control and Constraint Handling of Mechatronic Servo Systems Using Model Predictive Control. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 593-605	5.5	31
533	The strategy of three-axis photoelectric tracking system without blind region. 2012 , 56, 89-98		4
532	FX-RLS-Based Feedforward Control for LIDAR-Enabled Wind Turbine Load Mitigation. <i>IEEE Transactions on Control Systems Technology</i> , 2012 , 20, 1212-1222	4.8	62

531	Analysis and comparison of three discrete-time feedforward model-inverse control techniques for nonminimum-phase systems. 2012 , 22, 577-587		118
530	Rejecting multi-stage and low-frequency resonance with disturbance observer and feedforward control for engine servo. 2012 , 22, 819-826		7
529	Real-time control of non-minimum phase XY table system using trajectory-adaptive ZPETC. 2012 ,		1
528	Optimal Tracking Control of Motion Systems. <i>IEEE Transactions on Control Systems Technology</i> , 2012 , 20, 1548-1558	4.8	34
527	Optimized tool path generation for fast tool servo diamond turning of micro-structured surfaces. <i>International Journal of Advanced Manufacturing Technology</i> , 2012 , 63, 1137-1152	3.2	54
526	Adaptive nonlinear contour coupling control for a machine tool system. <i>International Journal of Advanced Manufacturing Technology</i> , 2012 , 61, 1057-1065	3.2	21
525	Energy-efficient power assisting methods for periodic motions and its experimental verification. 2012 ,		2
524	Two-degree-of-freedom robust control for a non-minimum phase electro-hydraulic system. 2012 ,		2
523	Discrete-time repetitive controller for time-delay systems with disturbance observer. 2012 , 14, 1340-1354		19
522	Auto-tuning and adaptive control of sheet metal forming. <i>Control Engineering Practice</i> , 2012 , 20, 156-164	3.9	11
521	Feed-system autotuning of a CNC machining center: Rapid system identification and fine gain tuning based on optimal search. 2012 , 36, 339-348		8
520	DC Motor Drive Speed Regulation: Using a Repetitive Control Application in a Flatbed Scanner. 2012 , 18, 38-46		6
519	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 356-369	5.5	245
518	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 345-355	5.5	50
517	Discrete-Time State Feedback With Velocity Estimation Using a Dual Observer: Application to an Underwater Direct-Drive Grinding Robot. <i>IEEE/ASME Transactions on Mechatronics</i> , 2012 , 17, 187-191	5.5	16
516	Milling contour error control using multilevel fuzzy controller. <i>International Journal of Advanced Manufacturing Technology</i> , 2013 , 66, 1641-1655	3.2	7
515	Precision contouring control of machine tools. <i>International Journal of Advanced Manufacturing Technology</i> , 2013 , 64, 319-333	3.2	54
514	Pre-compensation of contour errors in five-axis CNC machine tools. 2013 , 74, 1-11		71

513	Lift Force Control of Flapping-Wing Microrobots Using Adaptive Feedforward Schemes. <i>IEEE/ASME Transactions on Mechatronics</i> , 2013 , 18, 155-168	5.5	24
512	Periodic motion control of a heavy duty pneumatic actuating table using low-cost position sensors and hybrid repetitive control. 2013 ,		2
511	Multiaxis Contour Control: The State of the Art. <i>IEEE Transactions on Control Systems Technology</i> , 2013 , 21, 1997-2010	4.8	74
510	Estimation of tool orientation contour errors for five-axis machining. 2013 , 29, 271-277		21
509	Design of decentralized repetitive control of linear MIMO system. 2013 ,		3
508	Hybrid proportional derivative/repetitive control for active vibration control of smart piezoelectric structures. 2013 , 19, 992-1003		15
507	Rolling bearing-suspended spindle run-out control using repetitive control and adaptive feedforward cancellation. 2013 , 14, 2171-2178		12
506	Receding horizon based trajectory planning for biaxial systems. 2013 ,		3
505	High speed motion control system based on predictive observer. 2013 ,		
504	Receding horizon based trajectory planning and two-degree-of-freedom tracking control for fast sampling constrained systems. 2013 ,		2
503	Command-based iterative learning control with TCP function for five-axis contouring. 2013 ,		2
502	Vibration suppression feedback control on angular transmission error of cycloid gear for industrial robot. 2013 ,		2
501	Reference governor based model predictive contouring control for biaxial systems. 2013 ,		2
500	Sliding mode contouring control design using nonlinear sliding surface for three-dimensional machining. 2013 , 65, 8-14		18
499	A New Optimal Control System Design for Chemical Processes. 2013 , 21, 1341-1346		1
498	Estimation method for unobservable settling vibration of head-positioning control in hard disk drives. 2013 , 23, 37-45		11
497	Accurate control of ball screw drives using pole-placement vibration damping and a novel trajectory prefilter. 2013 , 37, 308-322		41
496	Phase Compensation Resonant Controller for PWM Converters. 2013 , 9, 957-964		37

495	Causal inversion of non-minimum-phase systems for hardware-in-the-loop transmission testing. 2013 , 227, 298-307			1
494	Contouring accuracy improvement of parametric free-form curves [A Fuzzy Logic-based Disturbance Compensation approach. 2013 ,			
493	Adaptive Control With Internal Model for High-Performance Precision Motion Control and Its Application to a Fast-Acting Piezoelectric Actuator. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2013 , 135,	1.6		3
492	Adaptive Error Control Algorithm for High Speed Two-Axis CNC Contouring. 2013 , 584, 149-153			
491	Application of Speed Observer for XY-Stage of Wire Bonder. 2013 , 655-657, 1342-1347			
490	Double Feedforward Control System Based on Precise Disturbance Modeling for Optical Disk. 2013 , 52, 09LF01			3
489	Precision motion control of permanent magnet linear synchronous motor servo system based on an integrated controller with inertia variation compensation. 2013 , 227, 1481-1494			7
488	Model-based piecewise affine variable-gain controller synthesis. 2013 ,			1
487	A spline-based technique for optimal set point regulation through pseudo-inversion of nonminimum phase linear systems. 2013 ,			3
486	A robust two degree-of-freedom controller for systems with delay. 2013 ,			
485	. 2013 ,			0
484	Intersample ripple resulting from discrete-time feedforward control. 2013 ,			
483	Improvement of Settling Performance by Mode-Switching Control With Split Initial-Value Compensation Based on Input Shaper. <i>IEEE Transactions on Industrial Electronics</i> , 2013 , 60, 979-987	8.9		16
482	Model-following controller design based on a stabilized digital inverse system. 2013 ,			
481	A new stabilizer for ltv internal model based system and its application to camless engine valve actuation. 2013 ,			1
480	An efficient fixed-point realization of inversion based repetitive control. 2013 ,			
479	Minimum trajectory control of focusing and tracking of optical disk systems by two-dimensional feedforward compensator. 2013 ,			
478	Inverse-Based Local Loop Shaping and IIR-Filter Design For Precision Motion Control. 2013 , 46, 490-497			2

477	Contouring Controller for Precise Motion Control Systems. 2013 , 54, 19-27		8
476	Trajectory Generation for CNC Machine Tools. 2013 , 79, 631-638		2
475	Longitudinal Slip Ratio Control of Electric Powertrains Using a Controller Output Observer for Disturbance Rejection. 2014 , 7, 65-72		7
474	Mechanical design and optimal control of humanoid robot (TPinokio). 2014 , 2014, 161-172		0
473	Control of Magnetic Bearings with plug-in time-varying harmonic resonators. 2014 ,		2
472	. <i>IEEE Transactions on Control Systems Technology</i> , 2014 , 22, 1581-1588	4.8	18
471	Hybrid current control of three-phase grid-connected converter for marine current power generation system. 2014 ,		2
470	Two-stage feedforward tracking control system with error-based disturbance observer for optical discs. 2014 , 21, 578-584		0
469	A sensorless physiological control algorithm for left ventricular assist device for heart failure patients. 2014 ,		1
468	Contour following control of two-axis servomechanism using CMAC and ILC. 2014 ,		1
467	Digital design of adaptive repetitive control of linear systems with time-varying periodic disturbances. 2014 , 8, 1995-2003		14
466	Synchronous Controller for Dual Servo Motor in Servo Press. 2014 , 494-495, 1175-1181		0
465	Unified output tracking control of non-minimum phase PWM systems using output redefinition. 2014 ,		1
464	Parameter-based contour error estimation for contour following accuracy improvements. 2014 ,		1
463	Aspects in inferential Iterative Learning Control: A 2D systems analysis. 2014 ,		2
462	Improving scanning speed of the AFMs with inversion-based feedforward control. 2014 ,		1
461	Free-form curves contour error estimation using the backward arc length approach. 2014 ,		1
460	MIMO FIR feedforward design for zero error tracking control. 2014 ,		7

459	Robust double feedforward tracking control system using error based disturbance observer for optical disk systems. 2014,		
458	Adaptive zero phase based internal model control for direct drive XY table. 2014,		
457	Trajectory tracking controller of high precise positioning system based on iterative learning control with wavelet filtering method. 2014,		
456	Optimal feedforward control with a parametric structure applied to a wafer stage. 2014, 228, 97-106		8
455	High-Speed CNC Grinding Process Optimization of Non-Circular Rotary Parts Based on Particle Swarm Optimization. 2014, 528, 237-246		
454	Reference redesigned perfect tracking control, with application to servo control system. 2014,		3
453	Real-Time Walking Pattern Generation Method for Humanoid Robots by Combining Feedback and Feedforward Controller. <i>IEEE Transactions on Industrial Electronics</i> , 2014, 61, 355-364	8.9	26
452	Multiobjective Optimization of an Observer-Based Controller: Theory and Experiments on an Underwater Grinding Robot. <i>IEEE Transactions on Control Systems Technology</i> , 2014, 22, 1875-1882	4.8	7
451	Feedforward tracking control for lower-limb robot with antagonistic driven mechanism. 2014,		
450	Three-dimensional contour tracking control of a parallel manipulator: Comparison of two control techniques. 2014,		1
449	A new repetitive control scheme based on non-causal FIR filters. 2014,		8
448	High-Sampling Rate Dynamic Inversion Filter Realization and Applications in Digital Control. <i>IEEE/ASME Transactions on Mechatronics</i> , 2014, 19, 238-248	5.5	6
447	Design of Robust Repetitive Control With Time-Varying Sampling Periods. <i>IEEE Transactions on Industrial Electronics</i> , 2014, 61, 2834-2841	8.9	56
446	Minimum tracking & focusing trajectory control based on two-dimensional equivalent PTC for optical disk. 2014,		
445	Compensating for ZOH-Induced Residual Vibrations in Head-Positioning Control of Hard Disk Drives. <i>IEEE/ASME Transactions on Mechatronics</i> , 2014, 19, 258-268	5.5	17
444	New Repetitive Control With Improved Steady-State Performance and Accelerated Transient. <i>IEEE Transactions on Control Systems Technology</i> , 2014, 22, 664-675	4.8	77
443	Modeling of a linear motor feed drive including pre-rolling friction and aperiodic cogging and ripple. <i>International Journal of Advanced Manufacturing Technology</i> , 2014, 73, 267-277	3.2	18
442	A Neural-Repetitive Control Approach for High-Performance Motion Control of Piezo-Actuated Systems. 2014, 39, 4131-4140		7

441	Discrete-time repetitive control with model-less FIR filter inversion for high performance nanopositioning. 2014,		6
440	PID saturation function sliding mode control for piezoelectric actuators. 2014,		1
439	Hierarchical optimal contour control of motion systems. 2014, 24, 98-107		14
438	Performance optimization of piecewise affine variable-gain controllers for linear motion systems. 2014, 24, 648-660		13
437	Smooth feedrate planning for continuous short line tool path with contour error constraint. 2014, 76, 1-12		56
436	A robust two degree-of-freedom controller for systems with both model and measurement uncertainty. <i>Control Engineering Practice</i> , 2014, 25, 55-65	3.9	6
435	Position and Velocity Profile Tracking Control for New Generation Servo Track Writing. 2014, 47, 5902-5907		
434	Transient Enhancement in Add-on Feedforward Algorithms for High-performance Mechatronic Systems. 2014, 47, 7214-7220		
433	Repetitive model based predictive controller to reject periodic disturbances.. 2014, 47, 11494-11499		2
432	Load current feedforward control of boost converter for downsizing output filter capacitor. 2014,		6
431	A comparison of inversion based Iterative Learning Control Algorithms. 2015,		4
430	Design of a new phase lead repetitive compensator for fast transient response. 2015,		1
429	Predictive Functional Control of a Table Drive System Using Disturbance Observer and Preview Feedforward Controller. 2015, 789-790, 995-1004		
428	Low-order feedforward control schemes for flexible motion systems with different rigid-body damping. 2015,		3
427	An approach to model-following controller design based on a stabilized digital inverse system. 2015, 229, 829-837		1
426	Tracking Control of Non-Minimum Phase Systems Using Filtered Basis Functions: A NURBS-Based Approach. 2015,		2
425	Second-Order Iterative Learning Control for Scaled Setpoints. <i>IEEE Transactions on Control Systems Technology</i> , 2015, 23, 805-812	4.8	3
424	A speed optimization algorithm based on the contour error model of lag synchronization for CNC cam grinding. <i>International Journal of Advanced Manufacturing Technology</i> , 2015, 80, 1421-1432	3.2	9

423	A novel cross-coupled synchronizing control method of industrial robot for trajectory tracking. 2015,		
422	Unified ILC framework for repeating and varying tasks: A frequency domain approach with application to a wire-bonder. 2015,		2
421	Distributed Component Friction Model for Precision Control of a Feed Drive System. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 1966-1974	5.5	26
420	Disturbance observer-based robust perfect tracking control for servo system and its application. 2015,		
419	The cam grinding contour error compensation based on cycle to cycle control. 2015,		
418	Contouring control of biaxial systems with optimal and adaptive cross coupling controller. 2015,		1
417	Smooth polynomial interpolation for point-to-point trajectories with vibration avoidance. 2015,		2
416	Low-Order Stabilizer Design for Discrete Linear Time-Varying Internal Model-Based System. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 2666-2677	5.5	4
415	Trying to keep it real: 25 Years of trying to get the stuff I learned in grad school to work on mechatronic systems. 2015,		8
414	Matrix factorization for design of Q-filter in iterative learning control. 2015,		1
413	Disturbance observer-based predictive functional control using zero phase error tracking controller. 2015,		0
412	Trajectory Tracking Control and Contouring Performance of Three-Dimensional CNC. <i>IEEE Transactions on Industrial Electronics</i> , 2015 , 1-1	8.9	24
411	Robust principal component analysis for iterative learning control of precision motion systems with non-repetitive disturbances. 2015,		6
410	Discrete sliding mode control for a non-minimum phase electro-hydraulic actuator system. 2015,		4
409	Experiment on trajectory tracking control of high precise positioning system based on iterative learning controller with wavelet filtering. 2015 , 32, 88-95		8
408	Time-delay pre-filter design for vibration free tracking of periodic reference signals. 2015,		1
407	A Control Strategy of a Two Degrees-of-Freedom Heavy Duty Parallel Manipulator. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2015 , 137,	1.6	41
406	Dynamic modeling and control of a novel XY positioning stage for semiconductor packaging. 2015, 37, 177-189		16

405	Spline Based Pseudo-Inversion of Sampled Data Non-Minimum Phase Systems for an Almost Exact Output Tracking. 2015 , 17, 1866-1879		8
404	Rational Basis Functions in Iterative Learning Control With Experimental Verification on a Motion System. <i>IEEE Transactions on Control Systems Technology</i> , 2015 , 23, 722-729	4.8	68
403	Robust repetitive control design and its application on linear servo systems. 2015 , 16, 21-29		2
402	Common zeros in synchronization of high-precision stage systems. 2015 ,		6
401	Study on the Control Strategy and Algorithm for Head-Box. 2015 , 738-739, 1086-1089		
400	Zero-phase velocity tracking of vibratory systems. <i>Control Engineering Practice</i> , 2015 , 40, 93-101	3.9	6
399	Precision control and compensation of helical gear hobbing via electronic gearbox Cross-Coupling controller. 2015 , 16, 797-805		12
398	Robust \dot{u} control and repetitive control for precision motion control of a pneumatic actuating table. 2015 , 229, 625-638		
397	Positive Position Feedback Based High-Speed Tracking Control of Piezo-actuated Nanopositioning Stages. 2015 , 689-700		0
396	Pre-compensation of servo contour errors using a model predictive control framework. 2015 , 98, 50-60		45
395	A Data-Driven Variable-Gain Control Strategy for an Ultra-Precision Wafer Stage With Accelerated Iterative Parameter Tuning. 2015 , 11, 1179-1189		33
394	A mixed numerical-analytical stable pseudo-inversion method aimed at attaining an almost exact tracking. 2015 , 25, 809-823		18
393	Robust adaptive feedforward control and achievable tracking for systems with time delays. 2015 , 88, 768-782		2
392	Controller Design for Mechanical Impedance Reduction. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 845-854	5.5	14
391	Energy Saving in Feed Drive Systems Using Sliding-Mode-Based Contouring Control With a Nonlinear Sliding Surface. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015 , 20, 572-579	5.5	28
390	Precise piston trajectory control for a free piston engine. <i>Control Engineering Practice</i> , 2015 , 34, 30-38	3.9	39
389	Improving CNC contouring accuracy by robust digital integral sliding mode control. 2015 , 88, 51-61		32
388	A generalized on-line estimation and control of five-axis contouring errors of CNC machine tools. 2015 , 88, 9-23		98

387	Rejecting multiple-period disturbances: active vibration control of a two degree-of-freedom piezoelectric flexible structure system. 2015 , 21, 3368-3382		3
386	A new approach to contour error control in high speed machining. 2015 , 88, 42-50		41
385	Vibration Suppression Control Method for Trochoidal Reduction Gears under Load Conditions. <i>IEEJ Journal of Industry Applications</i> , 2016 , 5, 267-275	0.7	0
384	Composite Motion Design Procedure for Vibration Assisted Small-Hole EDM Using One Voice Coil Motor. <i>Shock and Vibration</i> , 2016 , 2016, 1-7	1.1	5
383	Internal-Model-Principle-Based Specific Harmonics Repetitive Controller for Grid-Connected PWM Inverters. 2016 , 2016, 1-10		0
382	Optimal Design and Hybrid Control for the Electro-Hydraulic Dual-Shaking Table System. 2016 , 6, 220		8
381	Adaptive vibration suppression perfect tracking control for linear time-varying systems with application to ball-screw feed drives. 2016 ,		2
380	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2016 , 21, 2453-2465	5.5	1
379	Frequency-Domain ILC Approach for Repeating and Varying Tasks: With Application to Semiconductor Bonding Equipment. <i>IEEE/ASME Transactions on Mechatronics</i> , 2016 , 21, 2716-2727	5.5	35
378	Robust two-degree-of-freedom iterative learning control for flexibility compensation of industrial robot manipulators. 2016 ,		10
377	Design of higher order repetitive controller for non minimum phase plants. 2016 ,		2
376	Multirate iterative learning control for enhanced motion performance with application to wafer scanner systems. 2016 ,		1
375	. 2016 , 1-1		
374	A Simplified Method for Discrete-Time Repetitive Control Using Model-Less Finite Impulse Response Filter Inversion. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2016 , 138,	1.6	15
373	. 2016 ,		1
372	Regularized Filtered Basis Functions Approach for Accurate Tracking of Discrete-Time Linear Time Invariant Systems With Bounded Random Uncertainties. 2016 ,		0
371	Tracking control method for a plant with continuous time unstable zeros: Finite preactuation based on state trajectory regeneration by using redundant order polynomial. 2016 ,		2
370	An asymmetric cable-driven mechanism for force control of exoskeleton systems. 2016 ,		1

369	An asymmetric cable-driven mechanism for force control of exoskeleton systems. 2016 , 40, 41-50		10
368	Contouring Accuracy Improvement Using an Adaptive Feedrate Planning Method for CNC Machine Tools. 2016 , 56, 299-305		6
367	Fast servo control and vibration suppression based on optical ZPETC and ZPNF. 2016 ,		
366	U-model based control system formulisation and design for wind energy conversion systems. 2016 ,		1
365	Design Techniques for Multivariable ILC: Application to an Industrial Flatbed Printer. <i>IFAC-PapersOnLine</i> , 2016 , 49, 213-221	0.7	4
364	Resource Efficient ILC: Enabling Large Tasks on an Industrial Position-Dependent Flatbed Printer. <i>IFAC-PapersOnLine</i> , 2016 , 49, 567-574	0.7	
363	U-model enhanced control of nonminimum-phase dynamic systems. 2016 ,		1
362	Design and modeling aspects in multivariable iterative learning control. 2016 ,		5
361	Simulation Study of Motion Control for X-Y Table with a Novel Direct Contour Controller. 2016 , 693, 1618-1623		
360	A novel analysis and design method of phase lead filters in repetitive controllers for pulse-width modulated inverters. 2016 ,		
359	Design and analysis of a modular learning based cross-coupled control algorithm for multi-axis precision positioning systems. 2016 , 14, 272-281		5
358	Odd-harmonic repetitive control for high-speed raster scanning of piezo-actuated nanopositioning stages with hysteresis nonlinearity. 2016 , 244, 95-105		20
357	Digital LQR steady-state optimal control with feedforward for nonminimum phase boost DC-DC converter. 2016 ,		1
356	Data-based feedforward controller reconstruction from iterative learning control algorithm. 2016 ,		4
355	Multirate feedforward control with state trajectory generation based on time axis reversal for plant with continuous time unstable zeros. 2016 ,		5
354	Data-driven optimization of disturbance observer and feedforward controller in a composite control structure. 2016 ,		0
353	Cascaded proportionalIntegralDerivative controller parameters tuning for contour following improvement. 2016 , 230, 892-904		5
352	Tracking Control of Ball Screw Drives Using ADRC and Equivalent-Error-Model-Based Feedforward Control. <i>IEEE Transactions on Industrial Electronics</i> , 2016 , 63, 7682-7692	8.9	28

351	Integrating PLC theory and programming into advanced controls courses. 2016,		2
350	Resource-efficient ILC for LTI/LTV systems through LQ tracking and stable inversion: Enabling large feedforward tasks on a position-dependent printer. 2016, 38, 76-90		30
349	Design of decentralized multi-input multi-output repetitive control systems. 2016, 13, 615-623		8
348	Development of space-saving mechanism in shaking table systems for earthquake simulators. 2016,		0
347	Design of iterative learning control by the means of state space neural networks. 2016,		1
346	Fundamental study for a fractional order repetitive control using Generalized Repetitive Control for high precision motor control. 2016,		
345	Data-Based Motion Control of Wafer Scanners. <i>IFAC-PapersOnLine</i> , 2016, 49, 1-12	0.7	12
344	A novel hybrid contouring control method for 3-DOF robotic manipulators. 2016, 40, 178-193		14
343	Modeling and feedforward controller design in 2-dimensional shaking table systems. 2016, 744, 012072		
342	Practical iterative learning control considering robust stability for fast and precise positioning of galvano scanner. 2016,		0
341	A comparison of two methods for energy efficient tracking control using filtered basis functions. 2016,		
340	Robust adaptive cross-coupling position control of biaxial motion system. 2016, 59, 680-688		19
339	Disturbance observer based pitch control of wind turbines for disturbance rejection. 2016,		
338	Dual sliding mode contouring control with high accuracy contour error estimation for five-axis CNC machine tools. 2016, 108, 74-82		41
337	A novel integrated dynamic acceleration/deceleration interpolation algorithm for a CNC controller. <i>International Journal of Advanced Manufacturing Technology</i> , 2016, 87, 279-292	3.2	17
336	Two-state GMS-based friction model for precise control applications. 2016, 17, 553-564		7
335	A zero phase error tracking based path precompensation method for high-speed machining. 2016, 230, 230-239		5
334	Synergetic repetitive control and plug-in hybrid control method for precision motion control. <i>International Journal of Advanced Manufacturing Technology</i> , 2016, 87, 19-24	3.2	2

333	Control of Magnetic Bearings for Rotor Unbalance With Plug-In Time-Varying Resonators. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2016 , 138, 0110011-1100111	1.6	5
332	Iterative learning control of high-acceleration positioning table via sensitivity identification. 2016 , 8, 168781401663341		1
331	Sample-and-Hold Inputs for Minimum-Phase Behavior of Nonminimum-Phase Systems. <i>IEEE Transactions on Control Systems Technology</i> , 2016 , 24, 2103-2111	4.8	6
330	Energy-Efficient Controller Design for a Redundantly Actuated Hybrid Feed Drive With Application to Machining. <i>IEEE/ASME Transactions on Mechatronics</i> , 2016 , 21, 1822-1834	5.5	14
329	High speed laser scanning microscopy by iterative learning control of a galvanometer scanner. <i>Control Engineering Practice</i> , 2016 , 50, 12-21	3.9	41
328	High-Speed Tracking of a Nanopositioning Stage Using Modified Repetitive Control. 2017 , 14, 1467-1477		41
327	Contouring error control of the tool center point function for five-axis machine tools based on model predictive control. <i>International Journal of Advanced Manufacturing Technology</i> , 2017 , 88, 2909-2919	3.3	18
326	A generalised optimal linear quadratic tracker with universal applications. Part 2: discrete-time systems. 2017 , 48, 397-416		8
325	An Integrated Model-Data-Based Zero-Phase Error Tracking Feedforward Control Strategy With Application to an Ultraprecision Wafer Stage. <i>IEEE Transactions on Industrial Electronics</i> , 2017 , 64, 4139-4149	8.9	33
324	Explicit Phase Lead Filter Design in Repetitive Control for Voltage Harmonic Mitigation of VSI-Based Islanded Microgrids. <i>IEEE Transactions on Industrial Electronics</i> , 2017 , 64, 817-826	8.9	51
323	Pre-compensation for continuous-path running trajectory error in high-speed machining of parts with varied curvature features. 2017 , 30, 37-45		10
322	Closed-loop identification of unstable systems using noncausal FIR models. 2017 , 90, 168-185		22
321	A Novel Contouring Error Estimation for Three-Dimensional Contouring Control. 2017 , 2, 128-134		9
320	Dual-mode LQR-feedforward optimal control for non-minimum phase boost converter. 2017 , 10, 92-102		13
319	Disturbance Observer-Based Pitch Control of Wind Turbines for Enhanced Speed Regulation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2017 , 139,	1.6	4
318	Tracking Control of Linear Time-Invariant Nonminimum Phase Systems Using Filtered Basis Functions. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2017 , 139,	1.6	10
317	Model generation and parameter identification of unknown environment using element description method. 2017 ,		3
316	Robust guaranteed cost ILC with dynamic feedforward and disturbance compensation for accurate PMSM position control. <i>Control Engineering Practice</i> , 2017 , 65, 36-47	3.9	18

315	Adaptive Loop Shaping for Wideband Disturbances Attenuation in Precision Information Storage Systems. 2017 , 53, 1-13		4
314	Contouring control of a 3-[P2(US)] parallel manipulator. 2017 , 31, 496-508		3
313	Periodic Signal Tracking for Lightly Damped Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2017 , 139,	1.6	1
312	Speed tracking control for the gimbal system with harmonic drive. <i>Control Engineering Practice</i> , 2017 , 58, 204-213	3.9	11
311	Modeling, identification and analysis of a novel two-axis differential micro-feed system. 2017 , 50, 320-327		10
310	Digital Deadbeat and Repetitive Combined Control for a Stand-Alone Four-Leg VSI. 2017 , 53, 5624-5633		14
309	Fractional-Order Integral Sliding Mode Controller for Biaxial Motion Control System. 2017 , 24-35		
308	High-bandwidth and flexible tracking control for precision motion with application to a piezo nanopositioner. 2017 , 88, 085107		10
307	Model-based framework for multi-axial real-time hybrid simulation testing. 2017 , 16, 671-691		28
306	Contouring compensation control based on high accuracy contour error estimation for multi-axis motion systems. <i>International Journal of Advanced Manufacturing Technology</i> , 2017 , 93, 2263-2273	3.2	11
305	A new approach to the pre-compensation of contour errors for three-axis machine tools using an adaptive cross-coupled controller. <i>International Journal of Advanced Manufacturing Technology</i> , 2017 , 90, 3711-3725	3.2	6
304	Estimation and compensation for continuous-path running trajectory error in high-feed-speed machining. <i>International Journal of Advanced Manufacturing Technology</i> , 2017 , 89, 1495-1508	3.2	12
303	Enhancing Flatbed Printer Accuracy and Throughput: Optimal Rational Feedforward Controller Tuning Via Iterative Learning Control. <i>IEEE Transactions on Industrial Electronics</i> , 2017 , 64, 4207-4216	8.9	25
302	Inverting Nonminimum-Phase Systems from the Perspectives of Feedforward and ILC * *This research is supported by the Dutch Technology Foundation STW, carried out as part of the Robust Cyber-Physical Systems (RCPS) project (no. 12694); and Innovative Research Incentives Scheme under the VENI grant Precision Motion: Beyond the Nanometer (no. 13673) awarded by NWO (The Netherlands Organization for Scientific Research). <i>IFAC-PapersOnLine</i> , 2017 , 50, 12101-12106	0.7	2
301	Different architectures to develop repetitive controllers. <i>IFAC-PapersOnLine</i> , 2017 , 50, 13408-13413	0.7	3
300	Synchronizing Decentralized Control Loops for Overall Performance Enhancement: A Youla Framework Applied to a Wafer Scanner. <i>IFAC-PapersOnLine</i> , 2017 , 50, 10845-10850	0.7	6
299	Preactuated multirate feedforward for a high-precision stage with continuous time unstable zeros. <i>IFAC-PapersOnLine</i> , 2017 , 50, 10907-10912	0.7	3
298	Data-Driven Progressive and Iterative Learning Control * *This work was supported in part by funds from UCLA Jules Stein Institute, Matech Industries, LTD. Taiwan, and the National Institute of Health, R21 Grant No. 5R21EY024065-02.. <i>IFAC-PapersOnLine</i> , 2017 , 50, 4825-4830	0.7	4

297	Real-Time High Bandwidth Feedforward Position Control of Electro-Hydraulic Actuator Using Non-Minimum Phase Inverse Model. 2017 ,		
296	Set-point alteration scheme for improved disturbance compensation. 2017 ,		
295	A U-model based controller design for non-minimum phase systems: Application to Boeing 747 altitude-hold autopilot. 2017 ,		2
294	Robust repetitive control for time delay systems with application to nano manipulations. 2017 ,		0
293	ESO-based repetitive control for rejecting periodic and aperiodic disturbances in piezoelectric actuators. 2017 ,		1
292	Contouring error control for high-speed and high-precision five-axis CNC machine tools. 2017 ,		1
291	Design of cross-coupled CMAC for contour-following \bar{L} reinforcement-based ILC approach. 2017 , 58, 302-311		2
290	Large range tracking of an XY compliant nanomanipulator with nonlinear stiffness. 2017 ,		
289	Precision contouring control of 5 DOF dual-arm robot manipulators with holonomic constraints. 2017 ,		1
288	A set-membership approach to direct data-driven control design for SISO non-minimum phase plants. 2017 ,		0
287	Zero magnitude error tracking control for servo system with extremely low-resolution digital encoder. 2017 , 10, 355		3
286	An approach to stable inversion of LPTV systems with application to a position-dependent motion system. 2017 ,		2
285	Active Vibration Suppression of a Motor-Driven Piezoelectric Smart Structure Using Adaptive Fuzzy Sliding Mode Control and Repetitive Control. 2017 , 7, 240		9
284	Min-max model predictive control for biaxial feed drive system. 2017 ,		1
283	Improvement of accuracy of seismic waveforms using disturbance observer in multi-axis shaking table systems. 2017 ,		0
282	Internal Model-Based Disturbance Observer With Application to CVCF PWM Inverter. <i>IEEE Transactions on Industrial Electronics</i> , 2018 , 65, 5743-5753	8.9	38
281	Real-Time Contour-Error Estimation Methods for Three-Dimensional Free-Form Parametric Curves in Contour-Following Tasks. 2018 , 19, 173-182		8
280	Generalized Predictive Contour Control of the Biaxial Motion System. <i>IEEE Transactions on Industrial Electronics</i> , 2018 , 65, 8488-8497	8.9	15

279	Proxy-Based Optimal Control Allocation for Dual-Input Over-Actuated Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2018 , 23, 895-905	5.5	5
278	A high accuracy on-line estimation algorithm of five-axis contouring errors based on three-point arc approximation. 2018 , 130-131, 73-84		16
277	Continuous fractional-order Zero Phase Error Tracking Control. 2018 , 75, 226-235		19
276	Interpolation of a Clothoid Curve Based on Iterative True-Value Prediction Considering the Discretization Error. 2018 , 14, 5156-5166		2
275	Repetitive Controller of Capacitor-Less Current-Fed Dual-Half-Bridge Converter for Grid-Connected Fuel Cell System. <i>IEEE Transactions on Industrial Electronics</i> , 2018 , 65, 7841-7855	8.9	19
274	Design and Performance Evaluation of an Optimal Discrete-Time Feedforward Controller for Servo-Hydraulic Compensation. 2018 , 144, 04017163		6
273	Interpolation-based contour error estimation and component-based contouring control for five-axis CNC machine tools. 2018 , 61, 1666-1678		6
272	Feedforward Control for Wind Turbine Load Reduction with Pseudo-LIDAR Measurement. 2018 , 15, 142-155		7
271	Motion control of a two-axis linear motor-driven stage in the micro-milling process. 2018 , 232, 65-76		1
270	A Modified Feedback Scheme Suitable for Repetitive Control of Inverter With Nonlinear Load. 2018 , 33, 2588-2600		13
269	Phase compensation second-order repetitive control for CVCF PWM inverters. 2018 , 105, 324-336		4
268	Robust Iterative Learning Control for Vibration Suppression of Industrial Robot Manipulators. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2018 , 140,	1.6	22
267	A review of contouring-error reduction method in multi-axis CNC machining. 2018 , 125, 34-54		55
266	A limited-preview filtered B-spline approach to tracking control [With application to vibration-induced error compensation of a 3D printer. 2018 , 56, 287-296		27
265	Simple approximate phase cancellation for repetitive control of CVCF PWM inverters. 2018 , 46, 453-467		0
264	A model-data integrated iterative learning controller for flexible tracking with application to a piezo nanopositioner. 2018 , 40, 3201-3210		14
263	On inversion-based approaches for feedforward and ILC. 2018 , 50, 282-291		53
262	Model-Data Driven Learning Adaptive Robust Control of Precision Mechatronic Motion Systems With Comparative Experiments. 2018 , 6, 78286-78296		4

261	Cross-coupled intelligent control for a novel two-axis differential micro-feed system. 2018 , 10, 168781401877462		
260	Performance Enhancement of Predictive Functional Control Using Disturbance Observer and Zero Phase Error Tracking Controller. 2018 ,		
259	A Novel Robust Perfect Tracking Control Method for Nonlinear Servo Systems. 2018 ,		5
258	Comparison of Different Repetitive Control Architectures: Synthesis and Comparison. Application to VSI Converters. <i>Electronics (Switzerland)</i> , 2018 , 7, 446	2.6	2
257	Unified Digital Periodic Controller for Power Converter Systems. 2018 ,		
256	Studies on Robustness of Trajectory Adaptive ZPETC with Application to Electro-Hydraulic Actuator. 2018 ,		
255	Constrained Receding Horizon Contouring Error Control for a Feed Drive System. 2018 ,		1
254	Multirate Feedforward Control Based on Modal Form. 2018 ,		0
253	Sensorless Feedforward Current Control of Dual-Active-Bridge DC/DC Converter for Micro-Grid Applications. <i>IFAC-PapersOnLine</i> , 2018 , 51, 333-338	0.7	5
252	State Trajectory Generation of MIMO Multirate Feedforward for Perfect Tracking Control in High-Precision Stage. 2018 ,		
251	Design of a Robust Discrete-time Phase Lead Repetitive Control in Frequency Domain for a Linear Actuator with Multiple Phase Uncertainties. 2018 , 16, 2609-2620		2
250	Robust Filtered Basis Functions Approach for Feedforward Tracking Control. 2018 ,		0
249	An Optimization Model of High-Speed and High-Precision Machining Based on Model Predictive Control. 2018 ,		
248	Application of Iterative Learning Methods to Control of a LEGO Wheeled Mobile Robot. 2018 ,		
247	Perfect Tracking Control Method by Multirate Feedforward and State Trajectory Generation based on Time Axis Reversal. <i>IEEJ Journal of Industry Applications</i> , 2018 , 7, 93-101	0.7	0
246	Model-Based ILC with a Modified Q-Filter for Complex Motion Systems: Practical Considerations and Experimental Verification on a Wafer Stage. 2018 , 2018, 1-11		1
245	Motion Control of the Piezoelectric Tube Scanner for Lissajous Trajectories with Modified Repetitive Control. 2018 ,		1
244	Synergistic real-time compensation of tracking and contouring errors for precise parametric curved contour following systems. 2018 , 232, 3367-3383		5

243	Optimal State Trajectory Regeneration for Nonminimum Phase Systems: No Preaction Approach. 2018 ,		
242	Estimation Error Based Disturbance Observer Design for Flexible Loop Shaping. <i>Electronics (Switzerland)</i> , 2018 , 7, 358	2.6	3
241	A Scalable Model-Based Learning Algorithm With Application to UAVs. 2018 , 2, 839-844		12
240	Second-order RC: analysis, augmentation, and anti-frequency-variation for single-phase grid-tied inverter. 2018 , 11, 1128-1134		2
239	Development of a Cross-Coupled Robust Controller for a Multi-Axis Micromachining System. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2018 , 140,	1.6	1
238	Sensorless Control of Dual-Active-Bridge Converter with Reduced-Order Proportional-Integral Observer. 2018 , 11, 931		7
237	Fractional Order Zero Phase Error Tracking Control for Continuous Time Non-minimum Phase Processes. 2018 ,		0
236	Achieving Perfect Causal Feedforward Control in Presence of Nonminimum-Phase Behavior - Exploiting Additional Actuators and Squaring Down. 2018 ,		5
235	Reference Modulation for Performance Enhancement in Motion Control Systems. 2018 ,		1
234	Design of disturbance observer using composite filter in two-dimensional shaking table systems. 2018 ,		0
233	Optimal high-bandwidth control of ball-screw drives with acceleration and jerk feedback. 2018 , 54, 254-268		15
232	Modeling and adaptive compensation of tooth surface contour error for internal gearing power honing. 2019 , 233, 1500-1514		2
231	Feedforward model-inverse position control of three-stage servo-valve using zero magnitude error tracking control. 2019 , 233, 2340-2348		3
230	Finite-Time Learning Control Using Frequency Response Data With Application to a Nanopositioning Stage. <i>IEEE/ASME Transactions on Mechatronics</i> , 2019 , 24, 2085-2096	5.5	12
229	A model-based approach to enhance performance in high-end laser-positioning systems. 2019 ,		
228	DOB-Based Generalized Predictive Cross-Coupling Position Control for Biaxial System. 2019 ,		0
227	Online estimate and compensation of the gear machining error based on electronic gearbox cross-coupling controller. 2019 , 83, 691-705		2
226	Data-driven tuning of feedforward controller structured with infinite impulse response filter via iterative learning control. 2019 , 13, 1062-1070		4

225	Data-driven iterative feedforward control with rational parametrization: Achieving optimality for varying tasks. 2019 , 356, 6352-6372		3
224	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2019 , 24, 863-871	5.5	7
223	Application of model-based compensation methods to real-time hybrid simulation benchmark. <i>Mechanical Systems and Signal Processing</i> , 2019 , 131, 394-416	7.8	10
222	Iterative learning control in high-performance motion systems: from theory to implementation. 2019 ,		2
221	Precise Flowrate Control of Fluid Gear Pumps in Automated Painting Systems Using a Repetitive Controller. 2019 , 9, 3413		1
220	Friction compensation control of a feed drive system operated in a vacuum. 2019 , 33, 5353-5360		
219	Motion Control of Piezoelectric Actuator for High-Speed AFM Systems. 2019 ,		
218	Perfect tracking control of discrete-time quadratic TS fuzzy systems via feedback linearisation. 2019 , 50, 2316-2332		2
217	Weighted sum of vector norms based contouring control method for five-axis CNC machine tools. 2019 , 60, 93-103		3
216	. <i>IEEE Transactions on Industrial Electronics</i> , 2019 , 66, 8172-8180	8.9	11
215	Disturbance Compensation by Reference Profile Alteration With Application to Tray Indexing. <i>IEEE Transactions on Industrial Electronics</i> , 2019 , 66, 9406-9416	8.9	6
214	Optimal design of robust feedforward compensator with gain and phase specifications. 2019 , 40, 448-459		
213	Fractional repetitive control of nanopositioning stages for tracking high-frequency periodic inputs with nonsynchronized sampling. 2019 , 90, 055108		4
212	Feedforward control for oscillatory signal tracking using Hilbert transform. 2019 , 50, 41-50		3
211	Perfect Tracking Control Considering Generalized Controllability Indices and Application for High-Precision Stage in Translation and Pitching. <i>IEEJ Journal of Industry Applications</i> , 2019 , 8, 263-270	0.7	4
210	. 2019 , 10, 6898-6911		2
209	Data-Based Switching Feedforward Control for Repeating and Varying Tasks: With Application to an Ultraprecision Wafer Stage. <i>IEEE Transactions on Industrial Electronics</i> , 2019 , 66, 8670-8680	8.9	10
208	Contour errorBounded parametric interpolator with minimum feedrate fluctuation for five-axis CNC machine tools. <i>International Journal of Advanced Manufacturing Technology</i> , 2019 , 103, 567-584	3.2	17

207	Analysis of friction error in CNC machine tools based on electromechanical characteristics. 2019 , 233, 4934-4946		5
206	Integrated Modified Repetitive Control With Disturbance Observer of Piezoelectric Nanopositioning Stages for High-Speed and Precision Motion. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2019 , 141,	1.6	9
205	A Generalized Input-output-based Digital Sliding-mode Control for Piezoelectric Actuators with Non-minimum Phase Property. 2019 , 17, 773-782		5
204	Design and wide-bandwidth control of large aperture fast steering mirror with integrated-sensing unit. <i>Mechanical Systems and Signal Processing</i> , 2019 , 126, 211-226	7.8	15
203	Iterative NC program modification and energy saving for a CNC machine tool feed drive system with linear motors. <i>International Journal of Advanced Manufacturing Technology</i> , 2019 , 102, 3543-3562	3.2	7
202	Data-driven multi-inverter cooperative control for voltage tracking and current sharing in islanded AC microgrids. 2019 , 41, 3145-3157		7
201	Analysis and Control of Non-Minimum Phase Behavior in Nonlinear AC Grids Equipped with HVDC Links. 2019 ,		
200	Predictive Contour Control for Multi-axis Motion System with Unified Model. 2019 ,		0
199	Multivariable Model-less Feedforward Control of a Monolithic Nanopositioning Stage with FIR Filter Inversion. 2019 ,		6
198	Projection-based Iterative Learning Control for Ball-screw-driven Stage Using Basis Function and Data-based Friction Model. 2019 ,		0
197	Intersample Behavior Analysis of MIMO Multirate Feedforward Control depending on Selection of Input Multiplicities. <i>IFAC-PapersOnLine</i> , 2019 , 52, 163-168	0.7	
196	Design of a Cooperative Voltage Harmonic Compensation Strategy for Islanded Microgrids Combining Virtual Admittance and Repetitive Controller. 2019 , 55, 680-688		22
195	The Generation Mechanism of Tracking Error During Acceleration or Deceleration Phase in Ultraprecision Motion Systems. <i>IEEE Transactions on Industrial Electronics</i> , 2019 , 66, 7109-7119	8.9	8
194	An Equivalent-Plane Cross-Coupling Position Control for Contour-Accuracy Improvement in Three-Axis Free-Form Contour Following Tasks. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2019 , 141,	1.6	
193	A new contouring error estimation for the high form accuracy of a multi-axis CNC machine tool. <i>International Journal of Advanced Manufacturing Technology</i> , 2019 , 101, 1403-1421	3.2	9
192	Enhanced DFT-Based Controller for Selective Harmonic Compensation in Active Power Filters. 2019 , 34, 8017-8030		13
191	Beyond decentralized wafer/reticle stage control design: A double-Youla approach for enhancing synchronized motion. <i>Control Engineering Practice</i> , 2019 , 83, 21-32	3.9	10
190	Industrial feedforward control technology: a review. 2019 , 30, 2819-2833		15

189	Performance-Enhanced Robust Iterative Learning Control With Experimental Application to PMSM Position Tracking. <i>IEEE Transactions on Control Systems Technology</i> , 2019 , 27, 1813-1819	4.8	26
188	High-Speed AFM Imaging of Nanopositioning Stages Using H _∞ and Iterative Learning Control. <i>IEEE Transactions on Industrial Electronics</i> , 2020 , 67, 2430-2439	8.9	23
187	MPC Inspired Dynamical Output Feedback and Adaptive Feedforward Control Applied to Piezo-Actuated Positioning Systems. <i>IEEE Transactions on Industrial Electronics</i> , 2020 , 67, 3921-3931	8.9	6
186	Local Loop Shaping for Rejecting Band-Limited Disturbances in Nonminimum-Phase Systems With Application to Laser Beam Steering for Additive Manufacturing. <i>IEEE Transactions on Control Systems Technology</i> , 2020 , 28, 2249-2262	4.8	2
185	Improving Intersample Behavior in Discrete-Time System Inversion: With Application to LTI and LPTV Systems. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 55-65	5.5	3
184	Dynamic error of CNC machine tools: a state-of-the-art review. <i>International Journal of Advanced Manufacturing Technology</i> , 2020 , 106, 1869-1891	3.2	20
183	Iterative Learning of Dynamic Inverse Filters for Feedforward Tracking Control. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 349-359	5.5	10
182	Gain-phase information based robust control theory. 2020 , 30, 7970-7990		
181	Sliding mode control with third-order contour error estimation for free-form contour following. 2020 , 66, 282-294		5
180	Simultaneous servo error pre-compensation and feedrate optimization with tolerance constraints using linear programming. <i>International Journal of Advanced Manufacturing Technology</i> , 2020 , 109, 809-821	3.2	6
179	Optimal Selection of Basis Functions for Robust Tracking Control of Linear Systems using Filtered Basis Functions. 2020 ,		
178	MIMO multirate feedforward controller design with selection of input multiplicities and intersample behavior analysis. 2020 , 71, 102442		1
177	Improvement of Response Speed Characteristics of Fast Steering Mirror based on Zero Phase Error Tracking Controller. 2020 ,		
176	MPC-based robust contouring control for a robotic machining system. 2020 , 23, 1212		2
175	U-model enhanced control of non-minimum phase systems. 2020 , 51, 3146-3162		0
174	Model Predictive Contouring Control for Biaxial Feed Drive System. 2020 ,		2
173	Effective Clamping Force Control for Electromechanical Brake System. 2020 ,		1
172	A Tutorial on PES Pareto Methods for Analysis of Noise Propagation in Feedback Loops. 2020 ,		1

171	A new decoupled tangential contouring control scheme for multi-dimensional motion. 2020 , 151, 103944		5
170	A novel curvature circle iterative algorithm for contour error control of multi-axis CNC machine tools. 2020 , 65, 23-31		5
169	Torque Control of a Series Elastic Tendon-Sheath Actuation Mechanism. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 2915-2926	5.5	5
168	Auto-tuning of model-based feedforward controller by feedback control signal in ultraprecision motion systems. <i>Mechanical Systems and Signal Processing</i> , 2020 , 142, 106764	7.8	3
167	Neuro-fuzzy iterative learning control for 4-poster test rig. 2020 , 42, 2262-2275		1
166	Parallel Implementation of Iterative Learning Controllers on Multi-core Platforms. 2020 ,		
165	Real-time exact contour error calculation of NURBS tool path for contour control. <i>International Journal of Advanced Manufacturing Technology</i> , 2020 , 108, 2803-2821	3.2	4
164	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 547-557	5.5	6
163	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020 , 25, 2556-2564	5.5	5
162	Quantitative Tracking Error Analysis and Feedforward Compensation Under Different Model-Based Feedforward Controllers in Different Control Architectures. <i>IEEE Transactions on Industrial Electronics</i> , 2021 , 68, 381-390	8.9	4
161	Enhanced Odd-Harmonic Repetitive Control of Nanopositioning Stages Using Spectrum-Selection Filtering Scheme for High-Speed Raster Scanning. 2021 , 18, 1087-1096		2
160	Constrained Model Predictive Contour Error Control for Feed Drive Systems with Uncertainties. 2021 , 19, 209-220		1
159	A digital charge control strategy for reducing the hysteresis in piezoelectric actuators: Analysis, design, and implementation. 2021 , 67, 370-382		3
158	. <i>IEEE Transactions on Industrial Electronics</i> , 2021 , 68, 8412-8421	8.9	4
157	. <i>IEEE/ASME Transactions on Mechatronics</i> , 2021 , 1-1	5.5	0
156	A linear hybrid model for enhanced servo error pre-compensation of feed drives with unmodeled nonlinear dynamics. 2021 , 70, 301-304		1
155	Intelligent Learning Control Strategies for Speed Control of DC Motor. 2021 , 937-951		
154	Improved Odd-Harmonic Repetitive Control Scheme for Cuk-derived Inverter. 2021 , 1-1		3

153	Simplified Realization of Zero Phase Error Tracking. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2021 , 143,	1.6	3
152	Data-driven parameter tuning for rational feedforward controller: Achieving optimal estimation via instrumental variable. 2021 , 15, 937-948		3
151	Multirate Feedforward Control based on Modal Form with Mode Selection Applied to Multi-Modal High-Precision Positioning Stage. 2021 ,		
150	Suppression of harmonic positioning errors in ball-screw drives using Adaptive Feedforward Cancellation. 2021 , 68, 235-255		2
149	Torque Ripple Reduction for PMSM based on PWM Pulse Merging Method for High Speed Range. 2021 ,		
148	On Digital Periodic Controllers. 2021 ,		
147	Vibration Control of Flexible Joint Robots Using a Discrete-Time Two-Stage Controller Based on Time-Varying Input Shaping and Delay Compensation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2021 , 143,	1.6	1
146	Iterative Learning Control for a Class of Multivariable Distributed Systems With Experimental Validation. <i>IEEE Transactions on Control Systems Technology</i> , 2021 , 29, 949-960	4.8	3
145	Accurate and computationally efficient approach for simultaneous feedrate optimization and servo error pre-compensation of long toolpaths with application to a 3D printer. <i>International Journal of Advanced Manufacturing Technology</i> , 2021 , 115, 2069-2082	3.2	
144	Optimal Selection of Basis Functions for Robust Tracking Control of Uncertain Linear Systems With Application to Three-Dimensional Printing. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2021 , 143,	1.6	1
143	Variable-parameter-model-based iterative pre-compensation method of the tracking error. <i>Mechanical Systems and Signal Processing</i> , 2021 , 156, 107687	7.8	3
142	Contour Error Control of X-Y Motion Platform Based on Robust Predictive. 2021 ,		1
141	Quasi Multirate Feedforward Current Control toward Nyquist Frequency of PWM for SPMSM. <i>IEEJ Journal of Industry Applications</i> , 2021 , 10, 428-435	0.7	0
140	Iterative learning control with discrete-time nonlinear nonminimum phase models via stable inversion.		0
139	Control System Design for Electromechanical Brake System Using Novel Clamping Force Model and Estimator. 2021 , 70, 8653-8668		1
138	A large range compliant XY nano-manipulator with active parasitic rotation rejection. 2021 , 72, 640-652		4
137	Design and precision tracking control of a high-bandwidth fast steering mirror for laser beam machining. 2022 , 73, 128-139		3
136	. 2021 , 1-1		2

135	Prediction and Compensation of Contour Error of CNC Systems Based on LSTM Neural-Network. <i>IEEE/ASME Transactions on Mechatronics</i> , 2021 , 1-1	5.5	4
134	Microactuators for Dual-Stage Servo Systems in Magnetic Disk Files. 2004 , 951-981		2
133	Dynamic Issues in Robot Visual-Servo Systems. 1996 , 488-498		5
132	Auto-Tuning and Adaptive Control. <i>Advances in Industrial Control</i> , 2014 , 87-107	0.3	1
131	Adaptive Notch Filter Control for the Torsion Vibration in Lead-Screw Feed Drive System Based on Neural Network. 2008 , 803-812		3
130	Optimal Preview Controllers Based upon Explicit Trajectory Models. 1990 , 35, 273-294		2
129	Improving mechanical ventilation for patient care through repetitive control. <i>IFAC-PapersOnLine</i> , 2020 , 53, 1415-1420	0.7	4
128	Integrated terminal sliding with enhanced repetitive control for nono-positioning stage. 2016 ,		2
127	The Impact of Nonminimum-Phase Zeros on Human-in-the-Loop Control Systems. 2020 , PP,		2
126	Concurrent Design of Continuous Zero Phase Error Tracking Controller and Sinusoidal Trajectory for Improved Tracking Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 127-129	1.6	13
125	Multi-Rate Feedforward Tracking Control for Plants With Nonminimum Phase Discrete Time Models. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 556-560	1.6	5
124	Optimal Selection of Basis Functions for Minimum-Effort Tracking Control of Nonminimum Phase Systems Using Filtered Basis Functions. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2019 , 141,	1.6	2
123	A New Analytical Path-Reshaping Model and Solution Algorithm for Contour Error Pre-Compensation in Multi-Axis Computer Numerical Control Machining. 2020 , 142,		7
122	A Review of Manufacturing Process Control. 2020 , 142,		4
121	Feedforward actuator controller development using the backward-difference method for real-time hybrid simulation. 2014 , 14, 1081-1103		13
120	Achievement Method of High-Speed Response of Error Prediction Tracking Control for Optical Disk System. <i>IEEJ Transactions on Industry Applications</i> , 2007 , 127, 942-949	0.2	1
119	Load Current Feedforward Control of Boost Converter for Downsizing the Output Filter Capacitor. <i>IEEJ Transactions on Industry Applications</i> , 2015 , 135, 457-466	0.2	3
118	Integral Sliding Mode Control for Fast Tool Servo Diamond Turning of Micro-Structured Surfaces. 2011 , 5, 4-10		18

117	Synchronisation of Feed Axes with Differing Bandwidths Using Set Point Delay. 2017 , 11, 155-164		2
116	Motion Accuracy Enhancement of Five-Axis Machine Tools by Modified CL-Data. 2018 , 12, 699-706		8
115	Improvement of Simultaneous 5-Axis Controlled Machining Accuracy by CL-Data Modification. 2019 , 13, 583-592		3
114	Use of Cranes in Education and International Collaborations. 2011 , 23, 881-892		5
113	Reducción de la impedancia de salida en inversores monofásicos para UPS con multi-lazo convencional y plug-in repetitivo. 2019 , 16, 391		4
112	Development of Zero-Phase-Tracking Man-Machine Interface with Electro-Mechanical Delay of Electromyogram. 2012 , 30, 767-778		3
111	A Design Method of a Full Closed Loop Sampled Servo Control for Hard Disk Drive. <i>SICE Journal of Control Measurement and System Integration</i> , 2008 , 1, 242-250	0.3	2
110	Adaptive Repetitive Control with On-line Estimation of Multiple Periods. <i>Transactions of the Society of Instrument and Control Engineers</i> , 2009 , 45, 243-250	0.1	2
109	Quadratic Optimality of the Zero-Phase Repetitive Control. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 554-555	1.6	1
108	Robust Feedforward Control System considering Sudden Disturbance for Optical Disk Recording System. <i>IEEJ Transactions on Industry Applications</i> , 2004 , 124, 1197-1204	0.2	5
107	Microactuators for Dual-Stage Servo Systems in Magnetic Disk Files. 2004 , 951-981		
106	Energy Factor Application in AC and DC Motor Drives. 2005 , 314-347		0
105	Short-Span Seeking Control of Hard Disk Drive with Vibration Suppression PTC. <i>IEEJ Transactions on Industry Applications</i> , 2006 , 126, 706-712	0.2	7
104	Force Sensor-less Robust Tracking Servo System Suppressing Periodic Disturbance and Sudden Disturbance for Optical Disk System. <i>IEEJ Transactions on Industry Applications</i> , 2006 , 126, 1374-1381	0.2	2
103	Monitoring and Control of Machining. 2006 , 1-32		4
102	Microactuators for Dual-Stage Servo Systems in Magnetic Disk Files. 2007 , 1509-1544		
101	Real-Time Synthesis and Control by Corrected Inverse Transfer Function of NC Tables. 2008 , 74, 72-76		6
100	Real-time Compensation of Circular Interpolation Motion Error by Inverse Transfer Function Based on Friction Analysis. 2008 , 74, 616-621		

99	High-Performance Error Prediction Robust Tracking Control System for High Speed Optical Disk Recording Equipment. <i>IEEJ Transactions on Industry Applications</i> , 2008 , 128, 785-792	0.2	4
98	Kalman Estimator-Based State-Feedback High-Precision Positioning Control for a Micro-scale Air-Bearing Stage. 2009 , 765-775		
97	. 2009 , 27, 410-413		2
96	Advances in Data-driven Optimization of Parametric and Non-parametric Feedforward Control Designs with Industrial Applications. 2009 , 167-184		
95	Adaptive Control for Feed Drives Considering Coupling Effects Among Multiple Axes. 2010 , 4, 45-52		1
94	Compensation of Harmonic Disturbances within Nyquist Frequency in Hard Disk Drives. 2010 , 16, 872-875		
93	Analysis of Filter Designed on the Basis of Short-Span Seeking Control of Hard Disk Drives with Learning-Based PTC. <i>IEEJ Transactions on Industry Applications</i> , 2011 , 131, 350-356	0.2	
92	PERFECT TRACKING CONTROL WITH DISCRETE-TIME LQR FOR A NON-MINIMUM PHASE ELECTRO-HYDRAULIC ACTUATOR SYSTEM. <i>International Journal on Smart Sensing and Intelligent Systems</i> , 2011 , 4, 424-439	0.4	10
91	A Study on the Motion Analysis and Lead-Filter Design for High Speed/Accuracy Movement of Gantry Robot. 2011 , 17, 31-37		2
90	Tracking Control of an XY Stage by Considering Suppression of Machine-Stand Vibration. <i>IEEJ Transactions on Industry Applications</i> , 2011 , 131, 237-243	0.2	
89	NON-MINIMUM PHASE MODEL OF VERTICAL POSITION ELECTRO-HYDRAULIC CYLINDER FOR TRAJECTORY ZPETC. <i>International Journal on Smart Sensing and Intelligent Systems</i> , 2012 , 5, 504-520	0.4	2
88	Tracking Control System with Equivalent Perfect Tracking Control for Optical Disks. <i>IEEJ Transactions on Industry Applications</i> , 2012 , 132, 1121-1130	0.2	0
87	Energy-Efficient Power Assist Control Methods for Periodic Motions. <i>Transactions of the Institute of Systems Control and Information Engineers</i> , 2012 , 25, 28-38	0.1	1
86	Control System for Suppressing Tracking Error Offset and Multiharmonic Disturbance in High-Speed Optical Disk Systems. <i>IEEJ Transactions on Industry Applications</i> , 2012 , 132, 347-356	0.2	1
85	TRAJECTORY ADAPTIVE ZPET CONTROLLER WITHOUT FACTORIZATION OF ZEROS FOR NON-MINIMUM PHASE SYSTEM IN APPLICATION TO REAL-TIME DIGITAL TRACKING CONTROL OF ELECTRO-HYDRAULIC ACTUATOR. <i>International Journal on Smart Sensing and Intelligent Systems</i> , 2013 , 6, 383-402	0.4	
84	Direct and Indirect Adaptive Process Control. <i>Advances in Industrial Control</i> , 2014 , 109-131	0.3	
83	Wavelet Transform Based Frequency Tuning ILC. <i>Advances in Industrial Control</i> , 2014 , 103-126	0.3	
82	Adaptive Discrete Sliding Mode Control for a Non-minimum Phase Electro-Hydraulic Actuator System. <i>Lecture Notes in Electrical Engineering</i> , 2014 , 3-14	0.2	1

81	DISCRETE-TIME ADAPTIVE CONTROL FOR CONTINUOUS-TIME SYSTEMS USING LIMITING-ZERO MODEL AND ITS APPLICATION. 1990 , 113-118		
80	Theoretical Aspects of Lightweight Robot Control. 1993 , 8-38		
79	Motion control and identification techniques for machine tool axes. 1995 , 132-144		
78	Adaptive calibration of feedforward controllers for nonminimum-phase tracking systems. 1999 ,		1
77	Periodic, Multi-Step Tracking Control for a Weather Satellite Scanning Mirror1. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2001 , 123, 85-92	1.6	
76	Trajectory Tracking Control for Precision Servo Technology. <i>Journal of the Institute of Electrical Engineers of Japan</i> , 2017 , 137, 11-14	0	0
75	Perfect Tracking Control Method by Multirate Feedforward and State Trajectory Generation based on Time Axis Reversal. <i>IEEJ Transactions on Industry Applications</i> , 2017 , 137, 469-477	0.2	
74	Deadbeat Feedforward Compensation with Frequency Shaping of Position Feedforward Controller. <i>IEEJ Journal of Industry Applications</i> , 2017 , 6, 100-106	0.7	0
73	Model-based Control Techniques for Large-Scale High-Precision Stage. <i>IEEJ Transactions on Industry Applications</i> , 2020 , 140, 272-280	0.2	
72	Suppressing Position-Dependent Disturbances in Repetitive Control: With Application to a Substrate Carrier System. 2020 ,		2
71	Comprehensive Design Method of a High-Frequency-Response Fast Tool Servo System Based on a Full-Frequency Error Control Algorithm. <i>Micromachines</i> , 2021 , 12,	3.3	0
70	Gaussian Process Repetitive Control for Suppressing Spatial Disturbances. <i>IFAC-PapersOnLine</i> , 2020 , 53, 1487-1492	0.7	4
69	Output Perfect Tracking Control for a Plant with PWM-Type Input. <i>IFAC-PapersOnLine</i> , 2020 , 53, 8351-8356		
68	Frequency Response Data-based Disturbance Observer Design via Convex Optimization. <i>IFAC-PapersOnLine</i> , 2020 , 53, 8619-8624	0.7	0
67	Recent Results in Reference Prefiltering for Precision Motion Control. <i>IFAC-PapersOnLine</i> , 2020 , 53, 8656-8667	0.7	0
66	A Design Method of High Order Repetitive Controllers. <i>IFAC-PapersOnLine</i> , 2020 , 53, 4440-4445	0.7	0
65	Feedforward Tracking Controller Design Based on a Limited Bandwidth Desired Model. 2002 , 574-578		
64	Advanced Controls for New Machining Processes. 2009 , 159-218		

63	Steady state feedforward compensation for discrete-time multivariable systems. 1991 , 310-334		
62	Positioning Vibration Suppression for Two-Axis Servo System based on Drive Control. 2020 ,		
61	Bandwidth Maximization of Disturbance Observer Based on Experimental Frequency Response Data. <i>SICE Journal of Control Measurement and System Integration</i> , 2020 , 13, 257-264	0.3	0
60	Velocity Control of Pneumatic Motor Attached to Retrofit-type Steering Handle for Autonomous Navigation of Conventional Six-wheeled Dump Truck. <i>Transactions of the Society of Instrument and Control Engineers</i> , 2021 , 57, 433-444	0.1	
59	E-Teaching High Accuracy Motion Control Techniques in Covid-19 time. 2021 ,		
58	. <i>IEEE Open Journal of Industry Applications</i> , 2021 , 1-1	4.7	0
57	Linear Matrix Inequality Based Data-driven Disturbance Observer Design: Application to a Non-Minimum Phase Motion Stage. <i>IEEJ Journal of Industry Applications</i> , 2021 ,	0.7	
56	Simulation-based optimization of CNC interpolator parameters for machining accuracy improvement. <i>International Journal of Advanced Manufacturing Technology</i> , 1	3.2	0
55	Local Path Planning Using Artificial Potential Field for Waypoint Tracking with Collision Avoidance. 2020 ,		5
54	Novel Cross-coupling Position Command Shaping Controller using H _∞ in Multi-axis Motion System. <i>IEEE Transactions on Industrial Electronics</i> , 2021 , 1-1	8.9	1
53	Robust tracking with FPGA for high-speed laser galvanometer scanning. 2021 ,		
52	Linear repetitive control for a nonlinear mechanical ventilation system using feedback linearization. 2021 ,		0
51	Robust Repetitive Control of Nanopositioning Stages Using the Spectrum-Selection Filter With Narrow Passbands. <i>IEEE/ASME Transactions on Mechatronics</i> , 2022 , 1-6	5.5	0
50	Development of a Grinding Tool with Contact-Force Control Capability. <i>Electronics (Switzerland)</i> , 2022 , 11, 685	2.6	0
49	A Gaussian Process Approach to Multiple Internal Models in Repetitive Control. 2022 ,		
48	Input shaping for travelling wave generation. <i>Smart Materials and Structures</i> , 2022 , 31, 055006	3.4	
47	Model-free repetitive control design and implementation for dynamical galvanometer-based raster scanning. <i>Control Engineering Practice</i> , 2022 , 122, 105124	3.9	
46	Gaussian process repetitive control: Beyond periodic internal models through kernels. <i>Automatica</i> , 2022 , 140, 110273	5.7	1

45	Mechanical design and determination of bandwidth for a two-axis inertial reference unit. <i>Mechanical Systems and Signal Processing</i> , 2022 , 172, 108962	7.8	0
44	Research on High Speed and High Precision Control Method Used in Semiconductor Packaging System. 2021 ,		1
43	Intermittent Sampling in Repetitive Control: Exploiting Time-Varying Measurements. 2021 ,		
42	Real-time tool path modification for machine tool contour error reduction. <i>International Journal of Advanced Manufacturing Technology</i> , 2022 , 120, 6969	3.2	
41	Shifting Zeros of Pulse Modulation Driven Systems via Exact Linearization Using Multi-Degree-of-Freedom Pulses. <i>IEEE Transactions on Control Systems Technology</i> , 2022 , 1-12	4.8	
40	Adaptive Friction Compensation for a Novel Two-Axis Differential Microfeed System. <i>Shock and Vibration</i> , 2022 , 2022, 1-10	1.1	
39	Robust Periodical Tracking for Fast Tool Servo Systems with Selective Disturbance Compensation. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2022 ,	1.6	
38	E-Teaching High Accuracy Motion Control Techniques in Covid-19 time. 2021 ,		
37	Line of sight control of an image-based tracking system using Youla-Kucera parameterization. <i>Optical Engineering</i> , 2022 , 61,	1.1	
36	Measurement-based two-layer optimization scheme for machining system with repetitive and batch characteristics. <i>International Journal of Advanced Manufacturing Technology</i> , 2022 , 121, 2553-2563 ^{3,2}		
35	Position Tracking for Multi-Channel Double-Crystal Monochromator Scanning Based on Iterative Learning Control. <i>Actuators</i> , 2022 , 11, 177	2.4	
34	Data-Driven Iterative Learning Control of Nonlinear Systems by Adaptive Model Matching. <i>IEEE/ASME Transactions on Mechatronics</i> , 2022 , 1-11	5.5	0
33	A survey of modeling and control in ball screw feed-drive system. <i>International Journal of Advanced Manufacturing Technology</i> , 2022 , 121, 2923-2946	3.2	1
32	Precision tracking control of a dual-stage measuring machine. <i>Automatisierungstechnik</i> , 2022 , 70, 646-660.8		
31	Real-Time Iterative Compensation Framework for Precision Mechatronic Motion Control Systems. <i>IEEE/CAA Journal of Automatica Sinica</i> , 2022 , 9, 1218-1232	7	2
30	High-Accuracy Oriented CILC Motion Control of Mechatronic Systems with Comparative Experiments. 2022 ,		1
29	Methods of Intelligent Control in Mechatronics and Robotic Engineering: A Survey. 2022 , 11, 2443		1
28	Design, modeling, and test of a normal-stressed electromagnetic actuated compliant nano-positioning stage. 2023 , 185, 109753		0

27	Robust Control of Dual-Linear-Motor-Driven Gantry Stage for Coordinated Contouring Tasks Based on Feed Velocity. 2022 , 1-10	1
26	Gaussian Process Repetitive Control With Application to an Industrial Substrate Carrier System With Spatial Disturbances. 2022 , 1-15	0
25	Comparative Study of Performance-Oriented Feedforward Compensation Strategies for Precision Mechatronic Motion Systems. 2022 , 10, 100812-100823	0
24	Physics-Guided Neural Networks for Feedforward Control: An Orthogonal Projection-Based Approach. 2022 ,	1
23	Adaptive Feedforward Reference Design for Active Vibration Rejection in Multi-Actuator Hard Disk Drives. 2022 ,	0
22	Using IIR Filter in Fractional Order Phase Lead Compensation PIMR-RC for Grid-Tied Inverters. 2022 , 1-10	2
21	Generalized Proportional Integral Observer Based Sliding Mode Control for Biaxial Motion Control System with Mismatched Disturbances. 2022 ,	0
20	Active Cross Pre-Compensation Decoupling Control of X-Y Linear Motor Platform Based on Contour Error Analysis Model. 2022 , 10, 118590-118600	0
19	Design of Fractional Order Odd-Harmonics Repetitive Controller for Discrete-Time Linear Systems with Experimental Validations. 2022 , 22, 8873	0
18	State-tracking iterative learning control in frequency domain design for improved intersample behavior.	0
17	Discrete-Time Design of Dual Internal Model-Based Repetitive Control Systems. 2022 , 12, 11746	0
16	Motion profile and control design of fast steering mirror for backscanning step and stare imaging. 2023 , 94, 014501	0
15	The optimal design of repetitive controllers based on inverse frequency response.	0
14	Gain-scheduling robust control with guaranteed stability for ball screw drives with uncertain load mass and varying resonant modes. 2023 , 80, 198-207	0
13	Advanced LARC Strategy of Maglev Planar Motor with GRU Neural Network Prediction. 2022 ,	0
12	A velocity planning algorithm of high speed dispensing based on wavelet transform optimization. 2022 ,	0
11	A Data-driven Feedforward Control Design Method for Nonlinear Systems. 2022 , 288-295	0
10	Global toolpath modulationBased contour error pre-compensation for multi-axis CNC machining.	1

9	Pre-compensation of contour errors for five-axis machine tools through constructing a model reference adaptive control. 2023 , 183, 105258	1
8	Low-order sliding mode repetitive control for uncertain linear systems perturbed by band-limited periodic disturbances. 095965182311655	0
7	Design of a Trajectory Tracking Controller for Precision Motion Platform. 2023 , 733-739	0
6	Digital Tracking Control of a Cylindrical Voice-Coil Actuator. 2022 ,	0
5	A Physics-Guided Data-Driven Feedforward Tracking Controller for Systems With Unmodeled Dynamics Applied to 3D Printing. 2023 , 11, 14563-14574	0
4	Solution method for time-frequency responds of servo control systems based on frequency domain characteristics. 002029402311583	0
3	A positioning method of permanent magnet synchronous linear motor based on fuzzy iterative learning control. 2022 ,	0
2	Cascaded iterative learning motion control of precision maglev planar motor with experimental investigation. 2023 ,	0
1	Surface form inspection with contact coordinate measurement: a review. 2023 , 5, 022006	0