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Impedance Control: An Approach to Manipulation: Part I Theory

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#	Paper	IF	Citations
2359	Diagonalization of telerobotic hand controller impedance for accurate force and velocity transmission.		
2358	Non-contact impedance control for redundant manipulators using visual information.		9
2357	Control of physical interaction between a deformable finger-tip and a rigid object.		
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2355	Parallel coupled actuators for high performance force control: a micro-macro concept.		10
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