A framework and method for Human-Robot cooperative safe control based on digital twin

#	Paper	IF	Citations
4	A System of Remote Duty Expressway Toll Station based on Multi Queue Digital Twin and Edge Decision. **2022**,		0
3	An attention-based deep learning approach for inertial motion recognition and estimation in human-robot collaboration. **2023**, 67, 97-110		0
2	HumanRobot collaboration for on-site construction. **2023**, 150, 104812		0
1	Thermal image-based hand gesture recognition for worker-robot collaboration in the construction industry: A feasible study. **2023**, 56, 101939		0