

Dissipative dynamical systems part I: General theory

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Citation Report

#	ARTICLE	IF	CITATIONS
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4	Application of passive velocity field control to robot contour following problems. , 0, , .		13
5	Analysis of energy shaping based controllers for elastic joint robots via passivity theory. , 0, , .		0
6	Well-posedness of linear complementarity systems. , 0, , .		9
7	On discrete time nonnegative storage functions and state functions. , 0, , .		1
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