

# Hiroto Sato

## List of Publications by Year in descending order

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3  
papers

5  
citations

3311381

1  
h-index

3475538

1  
g-index

3  
all docs

3  
docs citations

3  
times ranked

0  
citing authors

#	ARTICLE	IF	CITATIONS
1	Development of a Compact Pneumatic Valve Using Rotational Motion for a Pneumatically Driven Mobile Robot With Periodic Motion in a Pipe. IEEE Access, 2021, 9, 165271-165285.	4.2	4
2	Distributed Deployment With Multiple Moving Robots for Long Distance Complex Pipe Inspection. IEEE Robotics and Automation Letters, 2022, 7, 11252-11259.	5.1	1
3	Two-degree-of-freedom pipe selection mechanism using contraction and extension unit composed of single tube and its application to a gas pipe inspection robot. Transactions of the JSME (in Japanese), 2020, 86, 20-00052-20-00052.	0.2	0