

# Minghao Li

## List of Publications by Year in descending order

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2682572

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#	ARTICLE	IF	CITATIONS
1	Hand-Eye Calibration of EOD Robot by Solving the $AXB = YCZD$ Problem. IEEE Access, 2022, 10, 3415-3429.	4.2	5
2	Optimizing Kinematic Modeling and Self-Collision Detection of a Mobile Manipulator Robot by Considering the Actual Physical Structure. Applied Sciences (Switzerland), 2021, 11, 10591.	2.5	2
3	Design Hybrid Iterative Learning Controller for Directly Driving the Wheels of Mobile Platform against Uncertain Parameters and Initial Errors. Applied Sciences (Switzerland), 2021, 11, 8181.	2.5	0