## $\mathbf{D} - \mathbf{D}^{\circ} \mathbf{D}^{1} / 4 \tilde{\mathbf{N}}^{\circ} \mathbf{D}_{s} \mathbf{D}'$

## List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/9792899/publications.pdf

Version: 2024-02-01

2 papers

0 citations

2 all docs 2 docs citations

times ranked

2

0 citing authors

#	Article	IF	CITATIONS
1	Global Position Feedback Tracking Control of a Serial Robot Manipulator with Revolute Joints. System Theory, Control and Computing Journal, 2022, 2, 8-12.	0.5	O
2	On stability with respect to the part of variables of a non-autonomous system in a cylindrical phase space. Zhurnal Srednevolzhskogo Matematicheskogo Obshchestva, 2021, 23, 273-284.	0.2	0