

# Mm Alam

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/9705365/publications.pdf>

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9  
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#	ARTICLE	IF	CITATIONS
1	Inclusion of Bidirectional Angular Positioning Deviations in the Kinematic Model of a Six-DOF Articulated Robot for Static Volumetric Error Compensation. IEEE/ASME Transactions on Mechatronics, 2022, 27, 4339-4349.	5.8	9
2	Energy-Efficient Robot Configuration and Motion Planning Using Genetic Algorithm and Particle Swarm Optimization. Energies, 2022, 15, 2074.	3.1	27
3	Novel six-axis robot kinematic model with axis-to-axis crosstalk. CIRP Annals - Manufacturing Technology, 2021, 70, 411-414.	3.6	11
4	Kinematic Modeling of Six-Axis Industrial Robot and its Parameter Identification: A Tutorial. International Journal of Automation Technology, 2021, 15, 599-610.	1.0	10
5	Evaluation of Kinematic and Compliance Calibration of Serial Articulated Industrial Manipulators. International Journal of Automation Technology, 2021, 15, 567-580.	1.0	13
6	Identification of a Kinematic Model of a 6DOF Industrial Manipulator With Angular Positioning Deviation "Error Map" of Rotary Axes. , 2020, , .		3
7	PD-FLC with admittance control for hexapod robot's leg positioning on seabed. , 2015, , .		8
8	CENTER OF MASS-BASED ADMITTANCE CONTROL FOR MULTI-LEGGED ROBOT WALKING ON THE BOTTOM OF OCEAN. Jurnal Teknologi (Sciences and Engineering), 2015, 74, .	0.4	0
9	Control input converter for robot's leg joint with parallel actuation configuration. , 2014, , .		2