

Keunwoo Jang

List of Publications by Year in descending order

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Version: 2024-02-01

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papers

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1937685

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docs citations

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times ranked

68
citing authors

#	ARTICLE	IF	CITATIONS
1	Contact State Estimation for Peg-in-Hole Assembly Using Gaussian Mixture Model. IEEE Robotics and Automation Letters, 2022, 7, 3349-3356.	5.1	8
2	Robotic furniture assembly: task abstraction, motion planning, and control. Intelligent Service Robotics, 2022, 15, 441-457.	2.6	4
3	Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. IEEE/ASME Transactions on Mechatronics, 2021, 26, 2115-2126.	5.8	5
4	Reactive Self-Collision Avoidance for a Differentially Driven Mobile Manipulator. Sensors, 2021, 21, 890.	3.8	9
5	Continuous Task Transition Approach for Robot Controller Based on Hierarchical Quadratic Programming. IEEE Robotics and Automation Letters, 2019, 4, 1603-1610.	5.1	28