Keunwoo Jang

List of Publications by Year
in descending order

5 papers	54 citations	1937685 4 h-index	2053705 5 g-index
5 all docs	5 docs citations	5 times ranked	68 citing authors

#	Article	IF	Citations
1	Continuous Task Transition Approach for Robot Controller Based on Hierarchical Quadratic Programming. IEEE Robotics and Automation Letters, 2019, 4, 1603-1610.	5.1	28
2	Reactive Self-Collision Avoidance for a Differentially Driven Mobile Manipulator. Sensors, 2021, 21, 890.	3.8	9
3	Contact State Estimation for Peg-in-Hole Assembly Using Gaussian Mixture Model. IEEE Robotics and Automation Letters, 2022, 7, 3349-3356.	5.1	8
4	Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. IEEE/ASME Transactions on Mechatronics, 2021, 26, 2115-2126.	5.8	5
5	Robotic furniture assembly: task abstraction, motion planning, and control. Intelligent Service Robotics, 2022, 15, 441-457.	2.6	4