

Tim Landgraf

List of Publications by Year in descending order

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Version: 2024-02-01

36
papers

933
citations

516681

16
h-index

501174

28
g-index

44
all docs

44
docs citations

44
times ranked

713
citing authors

#	ARTICLE	IF	CITATIONS
1	Fish waves as emergent collective antipredator behavior. <i>Current Biology</i> , 2022, 32, 708-714.e4.	3.9	25
2	Biomimetic robots promote the 3Rs Principle in animal testing. , 2021, , .		2
3	Social networks predict the life and death of honey bees. <i>Nature Communications</i> , 2021, 12, 1110.	12.8	60
4	Animal-in-the-Loop: Using Interactive Robotic Conspecifics to Study Social Behavior in Animal Groups. <i>Annual Review of Control, Robotics, and Autonomous Systems</i> , 2021, 4, 487-507.	11.8	18
5	A Flying Platform to Investigate Neuronal Correlates of Navigation in the Honey Bee (<i>Apis mellifera</i>). <i>Frontiers in Behavioral Neuroscience</i> , 2021, 15, 690571.	2.0	5
6	Electric signal synchronization as a behavioural strategy to generate social attention in small groups of mormyrid weakly electric fish and a mobile fish robot. <i>Biological Cybernetics</i> , 2021, 115, 599-613.	1.3	9
7	Impact of Variable Speed on Collective Movement of Animal Groups. <i>Frontiers in Physics</i> , 2021, 9, .	2.1	13
8	Consistent Behavioral Syndrome Across Seasons in an Invasive Freshwater Fish. <i>Frontiers in Ecology and Evolution</i> , 2021, 8, .	2.2	14
9	Group-level patterns emerge from individual speed as revealed by an extremely social robotic fish. <i>Biology Letters</i> , 2020, 16, 20200436.	2.3	18
10	Guppies Prefer to Follow Large (Robot) Leaders Irrespective of Own Size. <i>Frontiers in Bioengineering and Biotechnology</i> , 2020, 8, 441.	4.1	15
11	Robofish as Social Partner for Live Guppies. <i>Lecture Notes in Computer Science</i> , 2020, , 270-274.	1.3	0
12	Motion Dynamics of Foragers in Honey Bee Colonies. <i>Lecture Notes in Computer Science</i> , 2020, , 203-215.	1.3	0
13	A neural network model for familiarity and context learning during honeybee foraging flights. <i>Biological Cybernetics</i> , 2018, 112, 113-126.	1.3	39
14	Using a robotic fish to investigate individual differences in social responsiveness in the guppy. <i>Royal Society Open Science</i> , 2018, 5, 181026.	2.4	58
15	Insights into the Social Behavior of Surface and Cave-Dwelling Fish (<i>Poecilia mexicana</i>) in Light and Darkness through the Use of a Biomimetic Robot. <i>Frontiers in Robotics and AI</i> , 2018, 5, 3.	3.2	42
16	Tracking All Members of a Honey Bee Colony Over Their Lifetime Using Learned Models of Correspondence. <i>Frontiers in Robotics and AI</i> , 2018, 5, 35.	3.2	38
17	RenderGAN: Generating Realistic Labeled Data. <i>Frontiers in Robotics and AI</i> , 2018, 5, 66.	3.2	79
18	Evidence for mutual allocation of social attention through interactive signaling in a mormyrid weakly electric fish. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , 2018, 115, 6852-6857.	7.1	22

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19	Guidance of Navigating Honeybees by Learned Elongated Ground Structures. <i>Frontiers in Behavioral Neuroscience</i> , 2018, 12, 322.	2.0	21
20	Dancing attraction: followers of honey bee tremble and waggle dances exhibit similar behaviors. <i>Biology Open</i> , 2017, 6, 810-817.	1.2	6
21	Automatic detection and decoding of honey bee waggle dances. <i>PLoS ONE</i> , 2017, 12, e0188626.	2.5	29
22	K�nstliche Mini-Gehirne f�r Roboter. , 2017, , 135-150.		0
23	RoboFish: increased acceptance of interactive robotic fish with realistic eyes and natural motion patterns by live Trinidadian guppies. <i>Bioinspiration and Biomimetics</i> , 2016, 11, 015001.	2.9	92
24	Automatic methods for long-term tracking and the detection and decoding of communication dances in honeybees. <i>Frontiers in Ecology and Evolution</i> , 2015, 3, .	2.2	49
25	Walking bumblebees memorize panorama and local cues in a laboratory test of navigation. <i>Animal Behaviour</i> , 2014, 97, 13-23.	1.9	28
26	Blending in with the Shoal: Robotic Fish Swarms for Investigating Strategies of Group Formation in Guppies. <i>Lecture Notes in Computer Science</i> , 2014, , 178-189.	1.3	31
27	Electro-communicating Dummy Fish Initiate Group Behavior in the Weakly Electric Fish <i>Mormyrus rume</i> . <i>Lecture Notes in Computer Science</i> , 2014, , 446-448.	1.3	7
28	Conditioned behavior in a robot controlled by a spiking neural network. , 2013, , .		19
29	Interactive Robotic Fish for the Analysis of Swarm Behavior. <i>Lecture Notes in Computer Science</i> , 2013, , 1-10.	1.3	20
30	Imitation of the Honeybee Dance Communication System by Means of a Biomimetic Robot. <i>Lecture Notes in Computer Science</i> , 2012, , 132-143.	1.3	12
31	A Multi-agent Platform for Biomimetic Fish. <i>Lecture Notes in Computer Science</i> , 2012, , 365-366.	1.3	4
32	Analysis of the Waggle Dance Motion of Honeybees for the Design of a Biomimetic Honeybee Robot. <i>PLoS ONE</i> , 2011, 6, e21354.	2.5	40
33	A biomimetic honeybee robot for the analysis of the honeybee dance communication system. , 2010, , .		22
34	Sleep deprivation affects extinction but not acquisition memory in honeybees. <i>Learning and Memory</i> , 2009, 16, 698-705.	1.3	56
35	Design and Development of a Robotic Bee for the Analysis of Honeybee Dance Communication. <i>Applied Bionics and Biomechanics</i> , 2008, 5, 157-164.	1.1	15
36	Collective Predator Perception Advertisement in Fish. <i>SSRN Electronic Journal</i> , 0, , .	0.4	0