

Joon-Ha Kim

List of Publications by Year in descending order

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5
papers

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citations

2682572

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2550090

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6
docs citations

6
times ranked

27
citing authors

#	ARTICLE	IF	CITATIONS
1	STEP: State Estimator for Legged Robots Using a Preintegrated Foot Velocity Factor. IEEE Robotics and Automation Letters, 2022, 7, 4456-4463.	5.1	13
2	Design of KAIST HOUND, a Quadruped Robot Platform for Fast and Efficient Locomotion with Mixed-Integer Nonlinear Optimization of a Gear Train. , 2022, , .		7
3	Legged Robot State Estimation With Dynamic Contact Event Information. IEEE Robotics and Automation Letters, 2021, 6, 6733-6740.	5.1	17
4	Real-Time Constrained Nonlinear Model Predictive Control on SO(3) for Dynamic Legged Locomotion. , 2020, , .		24
5	Avoiding Obstacles during Push Recovery Using Real-Time Vision Feedback. , 2019, , .		7