

Zheng Yuan Li

List of Publications by Year in descending order

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6
papers

3
citations

3311381

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2917675

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g-index

6
all docs

6
docs citations

6
times ranked

1
citing authors

#	ARTICLE	IF	CITATIONS
1	A flexible self-recovery finger joint for a tendon-driven robot hand. Review of Scientific Instruments, 2020, 91, 115002.	1.3	1
2	A real time cost effective geometry calibration method for isocenter tracking of a rotating gantry using optical vision sensors. Microsystem Technologies, 2017, 23, 5171-5183.	2.0	0
3	An automated focusing method for a parallel micro-manipulator alignment. Microsystem Technologies, 2016, 22, 1501-1509.	2.0	0
4	Design of flexible joint using in soft robot hand. , 2016, , .		1
5	Parallel micro manipulator for optical spot array alignment of maskless lithography. Microsystem Technologies, 2015, 21, 2663-2668.	2.0	1
6	WeD-1-3 A DEVELOPMENT OF AN AUTOMATED FOCUSING METHOD FOR A PARALLEL MICRO-MANIPULATOR ALIGNMENT. Proceedings of JSME-IIP/ASME-ISPS Joint Conference on Micromechatronics for Information and Precision Equipment IIP/ISPS Joint MIPE, 2015, 2015, _WeD-1-3-1-_WeD-1-3-3.	0.0	0