Zheng Yuan Li

List of Publications by Year in descending order

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3311381 2917675 6 3 1 2 citations h-index g-index papers 6 6 6 1 citing authors all docs docs citations times ranked

| # | Article | IF | CITATIONS |
|---|---|-----|-----------|
| 1 | Parallel micro manipulator for optical spot array alignment of maskless lithography. Microsystem Technologies, 2015, 21, 2663-2668. | 2.0 | 1 |
| 2 | Design of flexible joint using in soft robot hand. , 2016, , . | | 1 |
| 3 | A flexible self-recovery finger joint for a tendon-driven robot hand. Review of Scientific Instruments, 2020, 91, 115002. | 1.3 | 1 |
| 4 | An automated focusing method for a parallel micro-manipulator alignment. Microsystem Technologies, 2016, 22, 1501-1509. | 2.0 | 0 |
| 5 | A real time cost effective geometry calibration method for isocenter tracking of a rotating gantry using optical vision sensors. Microsystem Technologies, 2017, 23, 5171-5183. | 2.0 | O |
| 6 | WeD-1-3 A DEVELOPMENT OF AN AUTOMATED FOCUSING METHOD FOR A PARALLEL MICRO-MANIPULATOR ALIGNMENT. Proceedings of JSME-IIP/ASME-ISPS Joint Conference on Micromechatronics for Information and Precision Equipment IIP/ISPS Joint MIPE, 2015, 2015, _WeD-1-3-1WeD-1-3-3. | 0.0 | 0 |