Andreas A Malikopoulos

List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	Enhanced Mobility With Connectivity and Automation: A Review of Shared Autonomous Vehicle Systems. IEEE Intelligent Transportation Systems Magazine, 2022, 14, 87-102.	2.6	46
2	Social Media and Misleading Information in a Democracy: A Mechanism Design Approach. IEEE Transactions on Automatic Control, 2022, 67, 2633-2639.	3.6	8
3	Optimal Control of Connected and Automated Vehicles at Multiple Adjacent Intersections. IEEE Transactions on Control Systems Technology, 2022, 30, 972-984.	3.2	29
4	A Platoon Formation Framework in a Mixed Traffic Environment. , 2022, 6, 1370-1375.		22
5	Optimal Coordination of Platoons of Connected and Automated Vehicles at Signal-Free Intersections. IEEE Transactions on Intelligent Vehicles, 2022, 7, 186-197.	9.4	31
6	Time-Optimal Coordination for Connected and Automated Vehicles at Adjacent Intersections. IEEE Transactions on Intelligent Transportation Systems, 2022, 23, 13330-13345.	4.7	15
7	A Priority-Aware Replanning and Resequencing Framework for Coordination of Connected and Automated Vehicles. , 2022, 6, 1772-1777.		11
8	Constraint-Driven Optimal Control of Multiagent Systems: A Highway Platooning Case Study. , 2022, 6, 1754-1759.		10
9	Combined Optimal Routing and Coordination of Connected and Automated Vehicles. , 2022, 6, 2749-2754.		6
10	Impact of Connectivity on Energy Consumption andÂBattery Life for Electric Vehicles. IEEE Transactions on Intelligent Vehicles, 2021, 6, 14-23.	9.4	32
11	An overview on optimal flocking. Annual Reviews in Control, 2021, 51, 88-99.	4.4	32
12	Optimal time trajectory and coordination for connected and automated vehicles. Automatica, 2021, 125, 109469.	3.0	61
13	Energy-Optimal Motion Planning for Agents: Barycentric Motion and Collision Avoidance Constraints. , 2021, , .		5
14	Decentralized Cooperative Merging of Platoons of Connected and Automated Vehicles at Highway On-Ramps. , 2021, , .		9
15	Energy-Optimal Goal Assignment of Multi-Agent System with Goal Trajectories in Polynomials. , 2021, , .		1
16	Conditions to provable system-wide optimal coordination of connected and automated vehicles. Automatica, 2021, 131, 109751.	3.0	11
17	A Hysteretic Q-learning Coordination Framework for Emerging Mobility Systems in Smart Cities. , 2021, , .		4

18 Design and Stability Analysis of a Shared Mobility Market. , 2021, , .

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19	Guest Editorial Special Issue on Big Data and AI for Computational Transportation in the Cyber–Physical–Social Space. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 7887-7890.	4.7	0
20	A Dynamic Program for a Team of Two Agents with Nested Information. , 2021, , .		3
21	Impact of Connected and Automated Vehicles in a Corridor. , 2020, , .		1
22	An Optimal Control Approach to Flocking. , 2020, , .		6
23	Conditions for State and Control Constraint Activation in Coordination of Connected and Automated Vehicles. , 2020, , .		5
24	Structural Results for Decentralized Stochastic Control with a Word-of-Mouth Communication. , 2020, , .		4
25	Demonstration of a time-efficient mobility system using a scaled smart city. Vehicle System Dynamics, 2020, 58, 787-804.	2.2	25
26	An energy-optimal framework for assignment and trajectory generation in teams of autonomous agents. Systems and Control Letters, 2020, 138, 104670.	1.3	6
27	Decentralized optimal coordination of connected and automated vehicles for multiple traffic scenarios. Automatica, 2020, 117, 108958.	3.0	39
28	Zero-Shot Autonomous Vehicle Policy Transfer: From Simulation to Real-World via Adversarial Learning. , 2020, , .		19
29	Social Resource Allocation in a Mobility System with Connected and Automated Vehicles: A Mechanism Design Problem. , 2020, , .		5
30	Beyond Reynolds: A Constraint-Driven Approach to Cluster Flocking. , 2020, , .		4
31	A Game-Theoretic Analysis of the Social Impact of Connected and Automated Vehicles. , 2020, , .		6
32	Experimental Validation of a Real-Time Optimal Controller for Coordination of CAVs in a Multi-Lane Roundabout. , 2020, , .		16
33	Simulation to scaled city. , 2019, , .		29
34	A Decentralized Control Framework for Energy-Optimal Goal Assignment and Trajectory Generation. , 2019, , .		4
35	An Optimal Coordination Framework for Connected and Automated Vehicles in two Interconnected Intersections. , 2019, , .		11
36	Optimal Vehicle Dynamics and Powertrain Control for Connected and Automated Vehicles. , 2019, , .		11

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37	Optimal Path Planning for Connected and Automated Vehicles at Urban Intersections. , 2019, , .		10
38	A Closed-Form Analytical Solution for Optimal Coordination of Connected and Automated Vehicles. , 2019, , .		15
39	Energy-Optimal Coordination of Connected and Automated Vehicles at Multiple Intersections. , 2019, , .		14
40	Decentralized Stochastic Control in Partially Nested Information Structures. IFAC-PapersOnLine, 2019, 52, 97-102.	0.5	7
41	On the Traffic Impacts of Optimally Controlled Connected and Automated Vehicles. , 2019, , .		5
42	Optimal Control for Speed Harmonization of Automated Vehicles. IEEE Transactions on Intelligent Transportation Systems, 2019, 20, 2405-2417.	4.7	68
43	The Multi-objective Dynamic Traveling Salesman Problem: Last Mile Delivery with Unmanned Aerial Vehicles Assistance. , 2019, , .		9
44	A decentralized energy-optimal control framework for connected automated vehicles at signal-free intersections. Automatica, 2018, 93, 244-256.	3.0	255
45	Optimal Control of Connected and Automated Vehicles at Roundabouts: An Investigation in a Mixed-Traffic Environment. IFAC-PapersOnLine, 2018, 51, 73-78.	0.5	61
46	A Scaled Smart City for Experimental Validation of Connected and Automated Vehicles. IFAC-PapersOnLine, 2018, 51, 130-135.	0.5	27
47	Characterization of the New Class of Driving Cycles for Connected and Automated Vehicles. , 2018, , .		2
48	Decentralized Optimal Control of Connected and Automated Vehicles in a Corridor. , 2018, , .		23
49	Impact of Partial Penetrations of Connected and Automated Vehicles on Fuel Consumption and Traffic Flow. IEEE Transactions on Intelligent Vehicles, 2018, 3, 453-462.	9.4	80
50	The average cost of Markov chains subject to total variation distance uncertainty. Systems and Control Letters, 2018, 120, 29-35.	1.3	5
51	Optimal control of Connected Automated Vehicles at urban traffic intersections: A feasibility enforcement analysis. , 2017, , .		23
52	Home energy management based on optimal production control scheduling with unknown regime switching. , 2017, , .		2
53	Automated and Cooperative Vehicle Merging at Highway On-Ramps. IEEE Transactions on Intelligent Transportation Systems, 2017, 18, 780-789.	4.7	304
54	A Survey on the Coordination of Connected and Automated Vehicles at Intersections and Merging at Highway On-Ramps. IEEE Transactions on Intelligent Transportation Systems, 2017, 18, 1066-1077.	4.7	564

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55	Impact of connected and automated vehicles on traffic flow. , 2017, , .		19
56	Decentralized optimal control for connected automated vehicles at intersections including left and right turns. , 2017, , .		43
57	An overview of driver feedback systems for efficiency and safety. , 2016, , .		3
58	Optimal control and coordination of connected and automated vehicles at urban traffic intersections. , 2016, , .		135
59	A modeling framework for optimal energy management of a residential building. Energy and Buildings, 2016, 130, 55-63.	3.1	84
60	Application of optimal production control theory for home energy management in a micro grid. , 2016, , \cdot		9
61	A Duality Framework for Stochastic Optimal Control of Complex Systems. IEEE Transactions on Automatic Control, 2016, 61, 2756-2765.	3.6	21
62	A Multiobjective Optimization Framework for Online Stochastic Optimal Control in Hybrid Electric Vehicles. IEEE Transactions on Control Systems Technology, 2016, 24, 440-450.	3.2	37
63	Energy impact of different penetrations of connected and automated vehicles. , 2016, , .		9
64	A multiobjective optimization framework for stochastic control of complex systems. , 2015, , .		12
65	Pareto Efficient Policy for Supervisory Power Management Control. , 2015, , .		3
66	Centralized stochastic optimal control of complex systems. , 2015, , .		11
67	Online Optimal Control of Connected Vehicles for Efficient Traffic Flow at Merging Roads. , 2015, , .		66
68	A Consumer-Oriented Control Framework for Performance Analysis in Hybrid Electric Vehicles. IEEE Transactions on Control Systems Technology, 2015, 23, 1451-1464.	3.2	12
69	Optimal routing of electric vehicles in networks with charging nodes: A dynamic programming approach. , 2014, , .		24
70	Multi-disciplinary decision making and optimization for hybrid electric propulsion systems. , 2014, , .		5
71	Supervisory Power Management Control Algorithms for Hybrid Electric Vehicles: A Survey. IEEE Transactions on Intelligent Transportation Systems, 2014, 15, 1869-1885.	4.7	184
72	Online Identification of Power Required for Self-Sustainability of the Battery in Hybrid Electric		0

Vehicles., 2014,,.

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73	Impact of Component Sizing in Plug-In Hybrid Electric Vehicles for Energy Resource and Greenhouse Emissions Reduction1. Journal of Energy Resources Technology, Transactions of the ASME, 2013, 135, .	1.4	26
74	An Optimization Framework for Driver Feedback Systems. IEEE Transactions on Intelligent Transportation Systems, 2013, 14, 955-964.	4.7	51
75	Stochastic optimal control for series hybrid electric vehicles. , 2013, , .		19
76	Optimization of driving styles for fuel economy improvement. , 2012, , .		24
77	An Optimization Model for Plug-In Hybrid Electric Vehicles. , 2011, , .		7
78	Thermal management system modelling and component sizing for heavy duty series hybrid electric vehicles. International Journal of Heavy Vehicle Systems, 2011, 18, 272.	0.1	5
79	Equilibrium control policies for Markov chains. , 2011, , .		8
80	A Rollout Control Algorithm for Discrete-Time Stochastic Systems. , 2010, , .		1
81	Online Identification and Stochastic Control for Autonomous Internal Combustion Engines. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2010, 132, .	0.9	30
82	Convergence Properties of a Computational Learning Model for Unknown Markov Chains. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2009, 131, .	0.9	11
83	Real-Time Self-Learning Optimization of Diesel Engine Calibration. Journal of Engineering for Gas Turbines and Power, 2009, 131, .	0.5	34
84	A Real-Time Computational Learning Model for Sequential Decision-Making Problems Under Uncertainty. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2009, 131, .	0.9	14
85	Convergence Properties of a Computational Learning Model for Unknown Markov Chains. , 2008, , .		1
86	Optimal Engine Calibration for Individual Driving Styles. , 2008, , .		16
87	A Learning Algorithm for Optimal Internal Combustion Engine Calibration in Real Time. , 2007, , 91.		15
88	Real-Time, Self-Learning Optimization of Diesel Engine Calibration. , 2007, , .		6
89	A State-Space Representation Model and Learning Algorithm for Real-Time Decision-Making Under Uncertainty. , 2007, , .		6
90	Simulation of an Integrated Starter Alternator (ISA) System for the HMMWV. , 0, , .		13

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91	A Decentralized Time- and Energy-Optimal Control Framework for Connected Automated Vehicles: From Simulation to Field Test. , 0, , .		15
92	Concurrent Optimization of Vehicle Dynamics and Powertrain Operation Using Connectivity and Automation. , 0, , .		5