

Manuel Kudruss

List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

4

papers

28

citations

2

h-index

4

g-index

4

ext. papers

38

ext. citations

3.4

avg, IF

1.18

L-index

#	Paper	IF	Citations
4	Efficient Derivative Evaluation for Rigid-Body Dynamics Based on Recursive Algorithms Subject to Kinematic and Loop Constraints 2019 , 3, 619-624		2
3	Model-Plant Mismatch Compensation Using Reinforcement Learning. <i>IEEE Robotics and Automation Letters</i> , 2018 , 3, 2471-2477	4.2	12
2	Benchmarking model-free and model-based optimal control. <i>Robotics and Autonomous Systems</i> , 2017 , 92, 81-90	3.5	12
1	A computational method for key-performance-indicator-based parameter identification of industrial manipulators. <i>Journal of Mathematics in Industry</i> , 2017 , 7,	2.9	2