

# Wu, William

## List of Publications by Year in descending order

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6  
papers

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2258059

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379  
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| # | ARTICLE  | IF  | CITATIONS |
|---|--|-----|-----------|
| 1 | Temporal Scheduling and Optimization for Multi-MAV Planning. Springer Proceedings in Advanced Robotics, 2022, , 813-831.   | 1.3 | 2         |
| 2 | Optimal Trajectory Generation for Quadrotor Teach-and-Repeat. IEEE Robotics and Automation Letters, 2019, 4, 1493-1500.  | 5.1 | 18        |
| 3 | Flying on point clouds: Online trajectory generation and autonomous navigation for quadrotors in cluttered environments. Journal of Field Robotics, 2019, 36, 710-733. | 6.0 | 92        |
| 4 | Autonomous aerial navigation using monocular visual-inertial fusion. Journal of Field Robotics, 2018, 35, 23-51.   | 6.0 | 151       |
| 5 | Optimal Time Allocation for Quadrotor Trajectory Generation. , 2018, , .   |     | 29        |
| 6 | Online Safe Trajectory Generation for Quadrotors Using Fast Marching Method and Bernstein Basis Polynomial. , 2018, , .  |     | 151       |