

# Krzysztof Galkowski

## List of Publications by Citations

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215  
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2,139  
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298  
ext. papers

2,726  
ext. citations

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L-index

#	Paper	IF	Citations
215	Experimentally supported 2D systems based iterative learning control law design for error convergence and performance. <i>Control Engineering Practice</i> , <b>2010</b> , 18, 339-348	3.9	140
214	Robust stability and stabilisation of 2D discrete state-delayed systems. <i>Systems and Control Letters</i> , <b>2004</b> , 51, 277-291	2.4	130
213	LMIs - a fundamental tool in analysis and controller design for discrete linear repetitive processes. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , <b>2002</b> , 49, 768-778		66
212	Positive real control for uncertain two-dimensional systems. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , <b>2002</b> , 49, 1659-1666		59
211	Iterative learning fault-tolerant control for differential time-delay batch processes in finite frequency domains. <i>Journal of Process Control</i> , <b>2017</b> , 56, 112-128	3.9	57
210	Robust finite frequency range iterative learning control design and experimental verification. <i>Control Engineering Practice</i> , <b>2013</b> , 21, 1310-1320	3.9	56
209	Multidimensional control systems: case studies in design and evaluation. <i>Multidimensional Systems and Signal Processing</i> , <b>2015</b> , 26, 895-939	1.8	53
208	Experimentally verified generalized KYP Lemma based iterative learning control design. <i>Control Engineering Practice</i> , <b>2016</b> , 53, 57-67	3.9	53
207	Stability and control of differential linear repetitive processes using an LMI setting. <i>IEEE Transactions on Circuits and Systems Part 2: Express Briefs</i> , <b>2003</b> , 50, 662-666		53
206	Robust output feedback stabilization for two-dimensional continuous systems in roesser form. <i>Applied Mathematics Letters</i> , <b>2004</b> , 17, 1331-1341	3.5	51
205	LMI approach to state-feedback stabilization of multidimensional systems. <i>International Journal of Control</i> , <b>2003</b> , 76, 1428-1436	1.5	37
204	Positive real control of two-dimensional systems: Roesser models and linear repetitive processes. <i>International Journal of Control</i> , <b>2003</b> , 76, 1047-1058	1.5	35
203	Robust iterative learning control for batch processes with input delay subject to time-varying uncertainties. <i>IET Control Theory and Applications</i> , <b>2016</b> , 10, 1904-1915	2.5	35
202	2D systems based robust iterative learning control using noncausal finite-time interval data. <i>Systems and Control Letters</i> , <b>2014</b> , 64, 36-42	2.4	31
201	Iterative learning control for spatio-temporal dynamics using Crank-Nicholson discretization. <i>Multidimensional Systems and Signal Processing</i> , <b>2012</b> , 23, 185-208	1.8	29
200	LMI based stability analysis and robust controller design for discrete linear repetitive processes. <i>International Journal of Robust and Nonlinear Control</i> , <b>2003</b> , 13, 1195-1211	3.6	29
199	Performance-Enhanced Robust Iterative Learning Control With Experimental Application to PMSM Position Tracking. <i>IEEE Transactions on Control Systems Technology</i> , <b>2019</b> , 27, 1813-1819	4.8	26

198	Output feedback control of discrete linear repetitive processes?. <i>Automatica</i> , <b>2004</b> , 40, 2167-2173	5.7	25
197	Stability and controllability of a class of 2-D linear systems with dynamic boundary conditions. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , <b>2002</b> , 49, 181-195		25
196	Elementary operation approach to state-space realizations of 2-D systems. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , <b>1997</b> , 44, 120-129		24
195	New 2D models and a transition matrix for discrete linear repetitive processes. <i>International Journal of Control</i> , <b>1999</b> , 72, 1365-1380	1.5	24
194	Dissipativity and stabilization of nonlinear repetitive processes. <i>Systems and Control Letters</i> , <b>2016</b> , 91, 14-20	2.4	24
193	Stability of nonlinear 2D systems described by the continuous-time Roesser model. <i>Automation and Remote Control</i> , <b>2014</b> , 75, 845-858	0.6	22
192	Output Information Based Iterative Learning Control Law Design With Experimental Verification. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , <b>2012</b> , 134,	1.6	22
191	Robust H <sub>∞</sub> Filtering for uncertain differential linear repetitive processes. <i>International Journal of Adaptive Control and Signal Processing</i> , <b>2008</b> , 22, 243-265	2.8	22
190	Guaranteed cost control of uncertain differential linear repetitive processes. <i>IEEE Transactions on Circuits and Systems Part 2: Express Briefs</i> , <b>2004</b> , 51, 629-634		22
189	A Constructive Approach to Stabilizability and Stabilization of a Class of nD Systems. <i>Multidimensional Systems and Signal Processing</i> , <b>2001</b> , 12, 329-343	1.8	21
188	LMI based stability analysis for 2D continuous systems		21
187	Matrix rank based conditions for reachability/controllability of discrete linear repetitive processes. <i>Linear Algebra and Its Applications</i> , <b>1998</b> , 275-276, 201-224	0.9	20
186	PI control of discrete linear repetitive processes. <i>Automatica</i> , <b>2006</b> , 42, 877-880	5.7	20
185	The Fornasini-Marchesini and the Roesser models: algebraic methods for recasting. <i>IEEE Transactions on Automatic Control</i> , <b>1996</b> , 41, 107-112	5.9	19
184	Robust guaranteed cost ILC with dynamic feedforward and disturbance compensation for accurate PMSM position control. <i>Control Engineering Practice</i> , <b>2017</b> , 65, 36-47	3.9	18
183	An approach to iterative learning control for spatio-temporal dynamics using nD discrete linear systems models. <i>Multidimensional Systems and Signal Processing</i> , <b>2011</b> , 22, 83-96	1.8	18
182	On the control of distributed parameter systems using a multidimensional systems setting. <i>Mechanical Systems and Signal Processing</i> , <b>2008</b> , 22, 1566-1581	7.8	18
181	Higher order discretization of 2-D systems. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , <b>2000</b> , 47, 713-722		18

180	The state-space realization of an n-dimensional transfer function. <i>International Journal of Circuit Theory and Applications</i> , <b>1981</b> , 9, 189-197	2	18
179	KYP lemma based stability and control law design for differential linear repetitive processes with applications. <i>Systems and Control Letters</i> , <b>2013</b> , 62, 560-566	2.4	17
178	H <sub>2</sub> /H <sub>∞</sub> output information-based disturbance attenuation for differential linear repetitive processes. <i>International Journal of Robust and Nonlinear Control</i> , <b>2011</b> , 21, 1981-1993	3.6	17
177	On the connection between discrete linear repetitive processes and 2-D discrete linear systems. <i>Multidimensional Systems and Signal Processing</i> , <b>2017</b> , 28, 341-351	1.8	16
176	Stability of nonlinear discrete repetitive processes with Markovian switching. <i>Systems and Control Letters</i> , <b>2015</b> , 75, 108-116	2.4	16
175	New results on strong practical stability and stabilization of discrete linear repetitive processes. <i>Systems and Control Letters</i> , <b>2015</b> , 77, 22-29	2.4	16
174	Stabilization of a class of uncertain "wave" discrete linear repetitive processes <b>2006</b> ,		16
173	Repetitive process based design and experimental verification of a dynamic iterative learning control law. <i>Control Engineering Practice</i> , <b>2016</b> , 46, 157-165	3.9	15
172	Control and filtering for discrete linear repetitive processes with $\mathcal{H}_\infty$ and $\mathcal{L}_2$ performance. <i>Multidimensional Systems and Signal Processing</i> , <b>2009</b> , 20, 235-264	1.8	15
171	A 2D systems approach to iterative learning control for discrete linear processes with zero Markov parameters. <i>International Journal of Control</i> , <b>2011</b> , 84, 1246-1262	1.5	14
170	Constrained Optimal Control Theory for Differential Linear Repetitive Processes. <i>SIAM Journal on Control and Optimization</i> , <b>2008</b> , 47, 396-420	1.9	14
169	Control theory for a class of 2D continuous-discrete linear systems. <i>International Journal of Control</i> , <b>2004</b> , 77, 847-860	1.5	14
168	Control law design for discrete linear repetitive processes with non-local updating structures. <i>Multidimensional Systems and Signal Processing</i> , <b>2013</b> , 24, 707-726	1.8	13
167	Strong practical stability and stabilization of discrete linear repetitive processes. <i>Multidimensional Systems and Signal Processing</i> , <b>2009</b> , 20, 311-331	1.8	13
166	LMI-BASED ANALYSIS FOR CONTINUOUS-DISCRETE LINEAR SHIFT-INVARIANT nD SYSTEMS. <i>Journal of Circuits, Systems and Computers</i> , <b>2005</b> , 14, 307-332	0.9	13
165	Multi-machine operations modelled and controlled as switched linear repetitive processes. <i>International Journal of Control</i> , <b>2008</b> , 81, 1549-1567	1.5	12
164	. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , <b>2008</b> , 55, 2813-2826	3.9	12
163	Proportional plus integral control of ladder circuits modeled in the form of two-dimensional (2D) systems. <i>Multidimensional Systems and Signal Processing</i> , <b>2015</b> , 26, 267-290	1.8	11

162	2011,			11
161	Finite frequency range iterative learning fault-tolerant control for discrete time-delay uncertain systems with actuator faults. <i>ISA Transactions</i> , <b>2019</b> , 95, 152-163	5.5		10
160	Vector Lyapunov functions for stability and stabilization of differential repetitive processes. <i>Journal of Computer and Systems Sciences International</i> , <b>2016</b> , 55, 503-514	1		10
159	H/sub /spl infin// control of differential linear repetitive processes. <i>IEEE Transactions on Circuits and Systems Part 2: Express Briefs</i> , <b>2006</b> , 53, 39-44			10
158	Modified Newton method based iterative learning control design for discrete nonlinear systems with constraints. <i>Systems and Control Letters</i> , <b>2018</b> , 118, 35-43	2.4		9
157	Vector Lyapunov Function based Stability of a Class of Applications Relevant 2D. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2014</b> , 47, 8247-8252			9
156	PI output feedback control of differential linear repetitive processes. <i>Automatica</i> , <b>2008</b> , 44, 1442-1445	5.7		9
155	Delay-dependent stability condition for uncertain linear 2-D state-delayed systems <b>2006</b> ,			9
154	Stabilization of Discrete Linear Repetitive Processes with Switched Dynamics. <i>Multidimensional Systems and Signal Processing</i> , <b>2006</b> , 17, 271-295	1.8		9
153	Exponential stability of discrete linear repetitive processes. <i>International Journal of Control</i> , <b>2002</b> , 75, 861-869	1.5		9
152	State-space realizations of MIMO 2D discrete linear systems Elementary operation and variable inversion approach. <i>International Journal of Control</i> , <b>2000</b> , 73, 242-253	1.5		9
151	Minimal state-space realization for a class of linear, discrete, nD, SISO systems. <i>International Journal of Control</i> , <b>2001</b> , 74, 1279-1294	1.5		9
150	Linear-quadratic parametrization of stabilizing controls in discrete-time 2D systems. <i>Automation and Remote Control</i> , <b>2011</b> , 72, 2364-2378	0.6		8
149	Using 2D systems theory to design output signal based iterative learning control laws with experimental verification <b>2008</b> ,			8
148	Transformation of the transfer function variables of the singular n-dimensional roesser model. <i>International Journal of Circuit Theory and Applications</i> , <b>1992</b> , 20, 63-74	2		8
147	Passivity based stabilization of repetitive processes and iterative learning control design. <i>Systems and Control Letters</i> , <b>2018</b> , 122, 101-108	2.4		8
146	Stabilization of Two-Dimensional Nonlinear Systems Described by Fornasini--Marchesini and Roesser Models. <i>SIAM Journal on Control and Optimization</i> , <b>2018</b> , 56, 3848-3866	1.9		8
145	Iterative Learning Control of an Electrostatic Microbridge Actuator With Polytopic Uncertainty Models. <i>IEEE Transactions on Control Systems Technology</i> , <b>2015</b> , 23, 2035-2043	4.8		7

144	Control of discrete linear repetitive processes using strong practical stability and disturbance attenuation. <i>Systems and Control Letters</i> , <b>2012</b> , 61, 1138-1144	2.4	7
143	Wave repetitive process approach to a class of ladder circuits <b>2012</b> ,		7
142	State-space realizations of multi-input multi-output systems-elementary operations approach. <i>International Journal of Control</i> , <b>1997</b> , 66, 119-144	1.5	7
141	Discrete linear repetitive processes with smoothing <b>2007</b> ,		7
140	Fractional polynomials and nD systems		7
139	Output feedback control of discrete linear repetitive processes. <i>Automatica</i> , <b>2004</b> , 40, 2167-2173	5.7	7
138	z - Transform and Volterra-Operator Based Approaches to Controllability and Observability Analysis for Discrete Linear Repetitive Processes. <i>Multidimensional Systems and Signal Processing</i> , <b>2003</b> , 14, 365-395	1.8	7
137	LMI based stability analysis and controller design for a class of 2D continuous-discrete linear systems		7
136	Optimization of the Directional Sensor Networks With Rotatable Sensors for Target-Barrier Coverage. <i>IEEE Sensors Journal</i> , <b>2021</b> , 21, 8276-8288	4	7
135	Finite frequency range robust iterative learning control of linear discrete system with multiple time-delays. <i>Journal of the Franklin Institute</i> , <b>2019</b> , 356, 2690-2708	4	7
134	Stochastic Stability of Some Classes of Nonlinear 2D Systems. <i>Automation and Remote Control</i> , <b>2018</b> , 79, 89-102	0.6	6
133	Parameter-dependent Lyapunov function-based robust iterative learning control for discrete systems with actuator faults. <i>International Journal of Adaptive Control and Signal Processing</i> , <b>2016</b> , 30, 1714-1732	2.8	6
132	An unconditionally stable finite difference scheme systems described by second order partial differential equations <b>2015</b> ,		6
131	Guaranteed cost iterative learning control [An application to control of Permanent Magnet Synchronous Motors <b>2015</b> ,		6
130	Fractional and nD systems: a continuous case. <i>Multidimensional Systems and Signal Processing</i> , <b>2012</b> , 23, 329-347	1.8	6
129	Iterative learning control method for a single-phase inverter with sinusoidal output voltage <b>2011</b> ,		6
128	Control and Disturbance Rejection for Discrete Linear Repetitive Processes. <i>Multidimensional Systems and Signal Processing</i> , <b>2005</b> , 16, 199-216	1.8	6
127	LMI based stability analysis and controller design for a class of 2D discrete linear systems		6

126	Higher order discretisation methods for a class of 2-D continuous-discrete linear systems. <i>IET Circuits, Devices and Systems</i> , <b>1999</b> , 146, 315		6
125	Control systems analysis for the Fornasini-Marchesini 2D systems model [progress after four decades. <i>International Journal of Control</i> , <b>2018</b> , 91, 2801-2822	1.5	6
124	Robust fault-tolerant iterative learning control for discrete systems via linear repetitive processes theory. <i>International Journal of Automation and Computing</i> , <b>2015</b> , 12, 254-265	3.5	5
123	Strong practical stability and stabilization of uncertain discrete linear repetitive processes. <i>Numerical Linear Algebra With Applications</i> , <b>2013</b> , 20, 220-233	1.6	5
122	Stabilization of nonlinear 2D Fornasini-Marchesini and Roesser systems <b>2015</b> ,		5
121	Modeling and control of a sorption process using 2D systems theory <b>2011</b> ,		5
120	Repetitive process based iterative learning control design using frequency domain analysis <b>2012</b> ,		5
119	LMI based stability and stabilization of second-order linear repetitive processes. <i>Asian Journal of Control</i> , <b>2010</b> , 12, 136-145	1.7	5
118	Optimal Control of Non-stationary Differential Linear Repetitive Processes. <i>Integral Equations and Operator Theory</i> , <b>2008</b> , 60, 201-216	0.5	5
117	$H_{\infty}$ control of discrete linear repetitive processes		5
116	Stability and dynamic boundary condition decoupling analysis for a class of 2-D discrete linear systems. <i>IET Circuits, Devices and Systems</i> , <b>2001</b> , 148, 126		5
115	Elementary operations and equivalence of two-dimensional systems. <i>International Journal of Control</i> , <b>1996</b> , 63, 1129-1148	1.5	5
114	Linear transformation of transfer function variables of an m-D system. <i>International Journal of Circuit Theory and Applications</i> , <b>1993</b> , 21, 351-360	2	5
113	Characterization of a class of spatially interconnected systems (ladder circuits) using two-dimensional systems theory. <i>Multidimensional Systems and Signal Processing</i> , <b>2019</b> , 30, 2185-2197	1.8	4
112	Dissipativity of Nonlinear 2D Systems. <i>IFAC-PapersOnLine</i> , <b>2015</b> , 48, 784-789	0.7	4
111	Stability and Stabilization of Differential Nonlinear Repetitive Processes with Applications. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2014</b> , 47, 5467-5472		4
110	Stabilization of differential repetitive processes. <i>Automation and Remote Control</i> , <b>2015</b> , 76, 786-800	0.6	4
109	Modelling and Control of Bi-Directional Discrete Linear Repetitive Processes. <i>IEEE Transactions on Automatic Control</i> , <b>2010</b> , 55, 230-235	5.9	4

108	Repetitive process based iterative learning control designed by LMIs and experimentally verified on a gantry robot <b>2009</b> ,		4
107	Delay-dependent stability of 2D state-delayed linear systems		4
106	Matrix description of multivariable polynomials. <i>Linear Algebra and Its Applications</i> , <b>1996</b> , 234, 209-226	0.9	4
105	Iterative learning control design based on feedback linearization and nonlinear repetitive process stability theory <b>2016</b> ,		4
104	3-D modelling of rectangular circuits as the particular class of spatially interconnected systems on the plane. <i>Multidimensional Systems and Signal Processing</i> , <b>2019</b> , 30, 1583-1608	1.8	4
103	Two-dimensional (2D) systems approach to feedforward/feedback control of a class of spatially interconnected systems. <i>International Journal of Control</i> , <b>2018</b> , 91, 2780-2791	1.5	4
102	Equivalent 2-D nonsingular Roesser models for discrete linear repetitive processes. <i>International Journal of Control</i> , <b>2018</b> , 91, 2673-2681	1.5	3
101	Parameter-Dependent Lyapunov Functions in the Robust Control of Discrete Linear Repetitive Processes Using Previous Pass-Windowed Information. <i>ASCE-ASME Journal of Risk and Uncertainty in Engineering Systems, Part B: Mechanical Engineering</i> , <b>2015</b> , 1,	1.4	3
100	Iterative learning control under parameter uncertainty and failures <b>2012</b> ,		3
99	Control of differential linear repetitive processes using strong practical stability and $H_\infty$ disturbance attenuation. <i>International Journal of Control</i> , <b>2013</b> , 86, 636-649	1.5	3
98	Particle swarm optimization of an iterative learning controller for the single-phase inverter with sinusoidal output voltage waveform. <i>Bulletin of the Polish Academy of Sciences: Technical Sciences</i> , <b>2013</b> , 61, 649-660		3
97	Robust control of distributed parameter mechanical systems using a multidimensional systems approach. <i>Bulletin of the Polish Academy of Sciences: Technical Sciences</i> , <b>2010</b> , 58, 67-75		3
96	Relaxed pass profile controllability of discrete linear repetitive processes. <i>International Journal of Control</i> , <b>2006</b> , 79, 938-958	1.5	3
95	One-Dimensional Equivalent Model and Related Approaches to the Analysis of Discrete Nonunit Memory Linear Repetitive Processes. <i>Circuits, Systems, and Signal Processing</i> , <b>2002</b> , 21, 525-534	2.2	3
94	A Perspective on Singularity in 2D Linear Systems. <i>Multidimensional Systems and Signal Processing</i> , <b>2000</b> , 11, 83-108	1.8	3
93	Spectral transformations of an n-D roesser model. <i>International Journal of Circuit Theory and Applications</i> , <b>1993</b> , 21, 481-485	2	3
92	Iterative Learning Control of the electrostatic microbridge actuator <b>2013</b> ,		3
91	Derivation and reduction of the singular Fornasini-Marchesini state-space model for a class of multidimensional systems. <i>IET Control Theory and Applications</i> , <b>2020</b> , 14, 634-645	2.5	3



90	Iterative Learning Control for a Class of Multivariable Distributed Systems With Experimental Validation. <i>IEEE Transactions on Control Systems Technology</i> , <b>2021</b> , 29, 949-960	4.8	3
89	An unconditionally stable approximation of a circular flexible plate described by a fourth order partial differential equation <b>2016</b> ,		3
88	Repetitive process based stochastic iterative learning control design for linear dynamics. <i>Systems and Control Letters</i> , <b>2020</b> , 137, 104625	2.4	2
87	Addenda to the papers Stability of nonlinear 2D systems described by the continuous-time Roeser model and Stabilization of differential repetitive processes <i>Automation and Remote Control</i> , <b>2016</b> , 77, 130-132	0.6	2
86	Passivity based stabilization of nonlinear 2D systems with application to iterative learning control <b>2014</b> ,		2
85	Special issue on: advances in multidimensional systems and signal processing. <i>Multidimensional Systems and Signal Processing</i> , <b>2012</b> , 23, 1-3	1.8	2
84	Robust stability of ladder circuits from the 2D systems point of view <b>2013</b> ,		2
83	<b>2017</b> ,		2
82	Reduction of discrete linear repetitive processes to nonsingular Roeser models via elementary operations * *The authors wish to express their thanks to Sultan Qaboos University (Oman) for their support in carrying out this research work. Also, this work is partially supported by National Science Centre in Poland, grant No. 2015/17/B/ST7/03703.. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 1865-1870	0.7	2
81	Reduction of wave linear repetitive processes to singular Roeser model form <b>2017</b> ,		2
80	Design of iterative learning control schemes for a class of spatially interconnected systems <b>2017</b> ,		2
79	Stability and stabilisation of active ladder circuits modeled in the form of two-dimensional (2D) systems <b>2015</b> ,		2
78	Exponential stability and stabilization of nD systems <b>2015</b> ,		2
77	H <sub>∞</sub> based stabilization and disturbance attenuation for nonlinear differential repetitive processes with an iterative learning control application <b>2014</b> ,		2
76	2D systems based iterative learning control design for multiple-input multiple-output systems <b>2014</b> ,		2
75	Repetitive Process Control Theory Applied to the Modeling and Control of Ladder Circuits. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , <b>2013</b> , 46, 689-694		2
74	On the design of ILC schemes for finite frequency range tracking specifications <b>2010</b> ,		2
73	2D systems theory applied to iterative learning control of spatio-temporal dynamics <b>2010</b> ,		2

72	Design of robust iterative learning control schemes in a finite frequency range <b>2011</b> ,		2
71	Iterative Learning Control for wave linear repetitive processes <b>2009</b> ,		2
70	Absolute stability and stabilization of 2D Roesser systems with nonlinear output feedback <b>2011</b> ,		2
69	On the usability of practical stable n-D systems for signal processing applications <b>2009</b> ,		2
68	Stability of a class of 2D linear systems with smoothing <b>2009</b> ,		2
67	Strong practical stability and stabilization of differential linear repetitive processes. <i>Systems and Control Letters</i> , <b>2010</b> , 59, 639-644	2.4	2
66	Optimal control and optimization for a class of repetitive processes <b>2007</b> ,		2
65	Control Law Design for Switched Repetitive Processes with a Metal Rolling Example. <i>Control Applications (CCA), Proceedings of the IEEE International Conference on</i> , <b>2007</b> ,		2
64	Fractional Polynomials and nD Systems: A Continuous Case <b>2006</b> ,		2
63	Delay differential control theory applied to differential linear repetitive processes <b>2002</b> ,		2
62	An a priori nonminimal state-space realization of n-D systems. <i>Linear Algebra and Its Applications</i> , <b>1991</b> , 151, 185-198	0.9	2
61	Iterative Learning Control for a discretized sub-class of spatially interconnected systems. <i>Advances in Intelligent Systems and Computing</i> , <b>2017</b> , 744-753	0.4	2
60	Robust finite frequency design of iterative learning control schemes. <i>IFAC-PapersOnLine</i> , <b>2016</b> , 49, 169-174		2
59	Equivalence of wave linear repetitive processes and the singular 2-D Roesser state-space model. <i>Multidimensional Systems and Signal Processing</i> , <b>2020</b> , 31, 103-116	1.8	2
58	Minimal State-space Realization for a Class of nD Systems <b>2005</b> , 179-194		2
57	Control of discretised sub-class of 2D systems <b>2016</b> ,		1
56	A practically tractable iterative learning control scheme for a circular deformable mirror <b>2017</b> ,		1
55	Modeling and Iterative Learning Control of a Circular Deformable Mirror. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 3117-3122	0.7	1

54	Pass profile exponential and asymptotic stability of nonlinear repetitive processes * *This work was supported in part by Russian Foundation for Basic Research under grants 16-08-00916_a, 16-38-00304_mol_a and in part by National Science Center in Poland under grant 2015/17/B/ST7/03703.. <i>IFAC-PapersOnLine</i> , <b>2017</b> , 50, 4138-4143	0.7	1
53	Reducing conservativeness in robust iterative learning control (ILC) design using parameter-dependent Lyapunov functions <b>2015</b> ,		1
52	Design of iterative learning control algorithms by generalized KYP synthesis <b>2014</b> ,		1
51	Insufficiencies of practical BIBO stable n-D systems. <i>Multidimensional Systems and Signal Processing</i> , <b>2014</b> , 25, 3-15	1.8	1
50	New frequency domain based stability tests for 2D linear systems <b>2012</b> ,		1
49	Finite frequency domain design of dynamic controllers for differential linear repetitive processes <b>2013</b> ,		1
48	New KYP lemma based stability tests and control law design algorithms for differential linear repetitive processes <b>2013</b> ,		1
47	Stability and robustness of discrete linear repetitive processes in the finite frequency domain using the KYP lemma <b>2013</b> ,		1
46	Application specific stability of 2-D Roesser model realizations <b>2010</b> ,		1
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