Dong Sun

List of Publications by Citations

334 papers	7,712 citations	46 h-index	73 g-index
404 ext. papers	9,645 ext. citations	4.7 avg, IF	6.42 L-index

#	Paper	IF	Citations
334	Enhanced cell sorting and manipulation with combined optical tweezer and microfluidic chip technologies. *Lab on A Chip*, **2011**, 11, 3656-62	7.2	283
333	Position synchronization of multiple motion axes with adaptive coupling control. *Automatica*, **2003**, 39, 997-1005	5.7	188
332	Superhydrophobic-like tunable droplet bouncing on slippery liquid interfaces. *Nature Communications*, **2015**, 6, 7986	17.4	164
331	Leader-Follower Formation Control of Multiple Non-holonomic Mobile Robots Incorporating a Receding-horizon Scheme. *International Journal of Robotics Research*, **2010**, 29, 727-747	5.7	157
330	A Synchronization Approach to Trajectory Tracking of Multiple Mobile Robots While Maintaining Time-Varying Formations. *IEEE Transactions on Robotics*, **2009**, 25, 1074-1086	6.5	146
329	Adaptive synchronized control for coordination of multirobot assembly tasks. *IEEE Transactions on Automation Science and Engineering*, **2002**, 18, 498-510		138
328	Robotic Cell Injection System With Position and Force Control: Toward Automatic Batch Biomanipulation. *IEEE Transactions on Robotics*, **2009**, 25, 727-737	6.5	137
327	Moving Groups of Microparticles Into Array With a Robot□tweezers Manipulation System. *IEEE Transactions on Robotics*, **2012**, 28, 1069-1080	6.5	131
326	A Model-Free Cross-Coupled Control for Position Synchronization of Multi-Axis Motions: Theory and Experiments. *IEEE Transactions on Control Systems Technology*, **2007**, 15, 306-314	4.8	126
325	Automatic transportation of biological cells with a robot-tweezer manipulation system. *International Journal of Robotics Research*, **2011**, 30, 1681-1694	5.7	121
324	Flexible Fiber-Shaped Supercapacitor Based on Nickel-Cobalt Double Hydroxide and Pen Ink Electrodes on Metallized Carbon Fiber. *ACS Applied Materials & Interfaces*, **2017**, 9, 5409-5418	9.5	120
323	Slewing and vibration control of a single-link flexible manipulator by positive position feedback (PPF). *Mechatronics*, **2005**, 15, 487-503	3	116
322	H/sub /spl infin// controller synthesis of fuzzy dynamic systems based on piecewise Lyapunov functions and bilinear matrix inequalities. *IEEE Transactions on Fuzzy Systems*, **2005**, 13, 94-103	8.3	113
321	Mechanical characterization of human red blood cells under different osmotic conditions by robotic manipulation with optical tweezers. *IEEE Transactions on Biomedical Engineering*, **2010**, 57, 1816-25	5	110
320	Enclosing a target by nonholonomic mobile robots with bearing-only measurements. *Automatica*, **2015**, 53, 400-407	5.7	108
319	. *IEEE Transactions on Industrial Electronics*, **2007**, 54, 3428-3429	8.9	108
318	Design of an enhanced nonlinear PID controller. *Mechatronics*, **2005**, 15, 1005-1024	3	106

317	Integration of saturated PI synchronous control and PD feedback for control of parallel manipulators **2006**, 22, 202-207		103
316	A PZT actuator control of a single-link flexible manipulator based on linear velocity feedback and actuator placement. *Mechatronics*, **2004**, 14, 381-401	3	91
315	. *IEEE Transactions on Vehicular Technology*, **2011**, 60, 4238-4248	6.8	88
314	Coordinated Motion Planning for Multiple Mobile Robots Along Designed Paths With Formation Requirement. *IEEE/ASME Transactions on Mechatronics*, **2011**, 16, 1021-1031	5.5	78
313	. *IEEE Transactions on Vehicular Technology*, **2012**, 61, 498-508	6.8	77
312	Development of a Tracked Climbing Robot. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2002**, 35, 427-443	2.9	76
311	Minimizing Energy Consumption of Wheeled Mobile Robots via Optimal Motion Planning. *IEEE/ASME Transactions on Mechatronics*, **2014**, 19, 401-411	5.5	75
310	Visual-Based Impedance Control of Out-of-Plane Cell Injection Systems. *IEEE Transactions on Automation Science and Engineering*, **2009**, 6, 565-571	4.9	75
309	Mechanical force characterization in manipulating live cells with optical tweezers. *Journal of Biomechanics*, **2011**, 44, 741-6	2.9	74
308	Microfluidic Single-Cell Manipulation and Analysis: Methods and Applications. *Micromachines*, **2019**, 10,	3.3	73
307	Dynamic trapping and manipulation of biological cells with optical tweezers. *Automatica*, **2013**, 49, 1614-1625	5.5	67
306	Mechanical modeling of biological cells in microinjection. *IEEE Transactions on Nanobioscience*, **2008**, 7, 257-66	3.4	67
305	Modified input shaping for a rotating single-link flexible manipulator. *Journal of Sound and Vibration*, **2005**, 285, 187-207	3.9	67
304	Dynamics Analysis and Motion Planning for Automated Cell Transportation With Optical Tweezers. *IEEE/ASME Transactions on Mechatronics*, **2013**, 18, 706-713	5.5	65
303	Force Sensing and Manipulation Strategy in Robot-Assisted Microinjection on Zebrafish Embryos. *IEEE/ASME Transactions on Mechatronics*, **2011**, 16, 1002-1010	5.5	65
302	Development of a New Robot Controller Architecture with FPGA-Based IC Design for Improved High-Speed Performance. *IEEE Transactions on Industrial Informatics*, **2007**, 3, 312-321	11.9	64
301	Two-Stage Charging Strategy for Plug-In Electric Vehicles at the Residential Transformer Level. *IEEE Transactions on Smart Grid*, **2013**, 4, 1442-1452	10.7	63
300	A simple nonlinear velocity estimator for high-performance motion control. *IEEE Transactions on Industrial Electronics*, **2005**, 52, 1161-1169	8.9	61

299	Graphene-Bridged Multifunctional Flexible Fiber Supercapacitor with High Energy Density. *ACS Applied Materials & Interfaces*, **2018**, 10, 28597-28607	9.5	59
298	Hand motion classification using a multi-channel surface electromyography sensor. *Sensors*, **2012**, 12, 1130-47	3.8	59
297	Localization for Multirobot Formations in Indoor Environment. *IEEE/ASME Transactions on Mechatronics*, **2010**, 15, 561-574	5.5	58
296	Single Cell Transfection through Precise Microinjection with Quantitatively Controlled Injection Volumes. *Scientific Reports*, **2016**, 6, 24127	4.9	56
295	Probing the mechanobiological properties of human embryonic stem cells in cardiac differentiation by optical tweezers. *Journal of Biomechanics*, **2012**, 45, 123-8	2.9	52
294	Model identification of a micro air vehicle in loitering flight based on attitude performance evaluation. *Journal of the American College of Radiology*, **2004**, 20, 702-712	3.5	49
293	A bounded controller for multirobot navigation while maintaining network connectivity in the presence of obstacles. *Automatica*, **2013**, 49, 285-292	5.7	48
292	H/sub /spl infin// output feedback control of discrete-time fuzzy systems with application to chaos control. *IEEE Transactions on Fuzzy Systems*, **2005**, 13, 531-543	8.3	47
291	. *IEEE Transactions on Control Systems Technology*, **2007**, 15, 982-988	4.8	46
290	Modeling and performance evaluation of traveling-wave piezoelectric ultrasonic motors with analytical method. *Sensors and Actuators A: Physical*, **2002**, 100, 84-93	3.9	46
289	Out-of-Plane Rotation Control of Biological Cells With a Robot-Tweezers Manipulation System for Orientation-Based Cell Surgery. *IEEE Transactions on Biomedical Engineering*, **2019**, 66, 199-207	5	46
288	Asymptotic trajectory tracking of manipulators using uncalibrated visual feedback. *IEEE/ASME Transactions on Mechatronics*, **2003**, 8, 87-98	5.5	45
287	Distributed control for uniform circumnavigation of ring-coupled unicycles. *Automatica*, **2015**, 53, 23-29	5.7	44
286	Observer-Based Optical Manipulation of Biological Cells With Robotic Tweezers. *IEEE Transactions on Robotics*, **2014**, 30, 68-80	6.5	43
285	A High-Throughput Automated Microinjection System for Human Cells With Small Size. *IEEE/ASME Transactions on Mechatronics*, **2016**, 21, 838-850	5.5	42
284	Development of Magnet-Driven and Image-Guided Degradable Microrobots for the Precise Delivery of Engineered Stem Cells for Cancer Therapy. *Small*, **2020**, 16, e1906908	11	42
283	Rapidly Exploring Random Tree Algorithm-Based Path Planning for Robot-Aided Optical Manipulation of Biological Cells. *IEEE Transactions on Automation Science and Engineering*, **2014**, 11, 649-657	4.9	41
282	High-Entropy Alloy (HEA)-Coated Nanolattice Structures and Their Mechanical Properties. *Advanced Engineering Materials*, **2018**, 20, 1700625	3.5	40

281	Approaches to Robust Filtering Design of Discrete Time Fuzzy Dynamic Systems. *IEEE Transactions on Fuzzy Systems*, **2008**, 16, 331-340	8.3	40
280	Force Modeling, Identification, and Feedback Control of Robot-Assisted Needle Insertion: A Survey of the Literature. *Sensors*, **2018**, 18,	3.8	39
279	Activation of multiple signaling pathways during the differentiation of mesenchymal stem cells cultured in a silicon nanowire microenvironment. *Nanomedicine: Nanotechnology, Biology, and Medicine*, **2014**, 10, 1153-63	6	39
278	Reorganization of cytoskeleton and transient activation of Ca2+ channels in mesenchymal stem cells cultured on silicon nanowire arrays. *ACS Applied Materials & Interfaces*, **2013**, 5, 13295-304	9.5	39
277	A universal piezo-driven ultrasonic cell microinjection system. *Biomedical Microdevices*, **2011**, 13, 743-52	3.7	38
276	A Synchronization Approach for the Minimization of Contouring Errors of CNC Machine Tools. *IEEE Transactions on Automation Science and Engineering*, **2009**, 6, 720-729	4.9	38
275	Control of a rotating cantilever beam using a torque actuator and a distributed piezoelectric polymer actuator. *Applied Acoustics*, **2002**, 63, 885-899	3.1	37
274	Micro air vehicle: configuration, analysis, fabrication, and test. *IEEE/ASME Transactions on Mechatronics*, **2004**, 9, 108-117	5.5	37
273	A dynamic priority based path planning for cooperation of multiple mobile robots in formation forming. *Robotics and Computer-Integrated Manufacturing*, **2014**, 30, 589-596	9.2	36
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267	Vision-Based 2-D Automatic Micrograsping Using Coarse-to-Fine Grasping Strategy. *IEEE Transactions on Industrial Electronics*, **2008**, 55, 3324-3331	8.9	35
266	Design for robust component synthesis vibration suppression of flexible structures with on-off actuators. *IEEE Transactions on Automation Science and Engineering*, **2004**, 20, 512-525		35
265	Design of a robust unified controller for cell manipulation with a robot-aided optical tweezers system. *Automatica*, **2015**, 55, 279-286	5.7	34
264	Three-dimensional cell manipulation and patterning using dielectrophoresis via a multi-layer scaffold structure. *Lab on A Chip*, **2015**, 15, 920-30	7.2	34

263	Microstructure, Mechanical and Corrosion Behaviors of CoCrFeNiAl0.3 High Entropy Alloy (HEA) Films. *Coatings*, **2017**, 7, 156	2.9	34
262	A Novel Arch-Shape Nanogenerator Based on Piezoelectric and Triboelectric Mechanism for Mechanical Energy Harvesting. *Nanomaterials*, **2014**, 5, 36-46	5.4	33
261	Coalition-Based Approach to Task Allocation of Multiple Robots With Resource Constraints. *IEEE Transactions on Automation Science and Engineering*, **2012**, 9, 516-528	4.9	33
260	Trajectory Tracking Control for a 3-DOF Planar Parallel Manipulator Using the Convex Synchronized Control Method. *IEEE Transactions on Control Systems Technology*, **2008**, 16, 613-623	4.8	33
259	Combined power management/design optimization for a fuel cell/battery plug-in hybrid electric vehicle using multi-objective particle swarm optimization. *International Journal of Automotive Technology*, **2014**, 15, 645-654	1.6	32
258	In Vivo Manipulation of Single Biological Cells With an Optical Tweezers-Based Manipulator and a Disturbance Compensation Controller. *IEEE Transactions on Robotics*, **2017**, 33, 1200-1212	6.5	32
257	Cell migration microfluidics for electrotaxis-based heterogeneity study of lung cancer cells. *Biosensors and Bioelectronics*, **2017**, 89, 837-845	11.8	31
256	Resource constrained multirobot task allocation based on leader–follower coalition methodology. *International Journal of Robotics Research*, **2011**, 30, 1423-1434	5.7	31
255	Global Stability of a Saturated Nonlinear PID Controller for Robot Manipulators. *IEEE Transactions on Control Systems Technology*, **2009**, 17, 892-899	4.8	31
254	Modeling and Impedance Control of a Two-Manipulator System Handling a Flexible Beam. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **1997**, 119, 736-742	1.6	31
253	Adaptive Synchronization Control of Multiple Spacecraft Formation Flying. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2007**, 129, 337-342	1.6	31
252	A fluorescent microbead-based microfluidic immunoassay chip for immune cell cytokine secretion quantification. *Lab on A Chip*, **2018**, 18, 522-531	7.2	30
251	An approach to quantized consensus of continuous-time linear multi-agent systems. *Automatica*, **2018**, 91, 98-104	5.7	30
250	Cell manipulation tool with combined microwell array and optical tweezers for cell isolation and deposition. *Journal of Micromechanics and Microengineering*, **2013**, 23, 075006	2	30
249	Liquid metal droplet robot. *Applied Materials Today*, **2020**, 19, 100597	6.6	29
248	A simplified sheathless cell separation approach using combined gravitational-sedimentation-based prefocusing and dielectrophoretic separation. *Lab on A Chip*, **2018**, 18, 1521-1532	7.2	29
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245	Multilevel-Based Topology Design and Cell Patterning With Robotically Controlled Optical Tweezers. *IEEE Transactions on Control Systems Technology*, **2015**, 23, 176-185	4.8	28
244	A visual sensing application to a climbing cleaning robot on the glass surface. *Mechatronics*, **2004**, 14, 1089-1104	3	28
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242	A dynamic model of chemoattractant-induced cell migration. *Biophysical Journal*, **2015**, 108, 1645-1651	2.9	27
241	Influence of semiflexible structural features of actin cytoskeleton on cell stiffness based on actin microstructural modeling. *Journal of Biomechanics*, **2012**, 45, 1900-8	2.9	27
240	Applying combined optical tweezers and fluorescence microscopy technologies to manipulate cell adhesions for cell-to-cell interaction study. *IEEE Transactions on Biomedical Engineering*, **2013**, 60, 2308-15	5	27
239	Rationally designed nickel oxide ravines@iron cobalt-hydroxides with largely enhanced capacitive performance for asymmetric supercapacitors. *Journal of Materials Chemistry A*, **2017**, 5, 16944-16952	13	26
238	Rendezvous of unicycles: A bearings-only and perimeter shortening approach. *Systems and Control Letters*, **2013**, 62, 401-407	2.4	26
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236	Adaptive Synchronized Control for a Planar Parallel Manipulator: Theory and Experiments. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2006**, 128, 976-979	1.6	26
235	Development of a MEMS based colloid thruster with sandwich structure. *Sensors and Actuators A: Physical*, **2005**, 117, 168-172	3.9	26
234	Robust Control to Manipulate a Microparticle with Electromagnetic Coil System. *IEEE Transactions on Industrial Electronics*, **2017**, 64, 8566-8577	8.9	25
233	Fusion with stem cell makes the hepatocellular carcinoma cells similar to liver tumor-initiating cells. *BMC Cancer*, **2016**, 16, 56	4.8	25
232	Laser-induced fusion of human embryonic stem cells with optical tweezers. *Applied Physics Letters*, **2013**, 103, 033701	3.4	25
231	Application of a Service Climbing Robot with Motion Planning and Visual Sensing. *Journal of Field Robotics*, **2003**, 20, 189-199		25
230	Stabilizing a flexible beam handled by two manipulators via PD feedback. *IEEE Transactions on Automatic Control*, **2000**, 45, 2159-2164	5.9	25
229	Achieving Automated Organelle Biopsy on Small Single Cells Using a Cell Surgery Robotic System. *IEEE Transactions on Biomedical Engineering*, **2019**, 66, 2210-2222	5	25
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227	Automated Pairing Manipulation of Biological Cells With a Robot-Tweezers Manipulation System. *IEEE/ASME Transactions on Mechatronics*, **2015**, 20, 2242-2251	5.5	22
226	Mechanically stable ternary heterogeneous electrodes for energy storage and conversion. *Nanoscale*, **2018**, 10, 2613-2622	7.7	22
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224	Hybrid control of a rotational flexible beam using enhanced PD feedback with a nonlinear differentiator and PZT actuators. *Smart Materials and Structures*, **2005**, 14, 69-78	3.4	22
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222	Design and characterization of a conductive nanostructured polypyrrole-polycaprolactone coated magnesium/PLGA composite for tissue engineering scaffolds. *Journal of Biomedical Materials Research - Part A*, **2015**, 103, 2966-73	5.4	21
221	Development and application of ultrasonic surgical instruments. *IEEE Transactions on Biomedical Engineering*, **1997**, 44, 462-7	5	21
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218	Gradient-Enhanced Electromagnetic Actuation System With a New Core Shape Design for Microrobot Manipulation. *IEEE Transactions on Industrial Electronics*, **2020**, 67, 4700-4710	8.9	21
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216	Saturated PID Control for the Optical Manipulation of Biological Cells. *IEEE Transactions on Control Systems Technology*, **2018**, 26, 1909-1916	4.8	19
215	Preserving Multirobot Connectivity in Rendezvous Tasks in the Presence of Obstacles With Bounded Control Input. *IEEE Transactions on Control Systems Technology*, **2013**, 21, 2306-2314	4.8	19
214	Characterization of biomechanical properties of cells through dielectrophoresis-based cell stretching and actin cytoskeleton modeling. *BioMedical Engineering OnLine*, **2017**, 16, 41	4.1	19
213	Manipulating cell adhesions with optical tweezers for study of cell-to-cell interactions. *Journal of Biomedical Nanotechnology*, **2013**, 9, 281-5	4	19
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211	Integrated design of trajectory planning and control for micro air vehicles. *Mechatronics*, **2007**, 17, 245-253	3	19
210	Visual-based Impedance Force Control of Three-dimensional Cell Injection System. *Proceedings - IEEE International Conference on Robotics and Automation*, **2007**,		19

209	Lgr5-overexpressing mesenchymal stem cells augment fracture healing through regulation of Wnt/ERK signaling pathways and mitochondrial dynamics. *FASEB Journal*, **2019**, 33, 8565-8577	0.9	18
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207	Magnetically Driven Undulatory Microswimmers Integrating Multiple Rigid Segments. *Small*, **2019**, 15, e1901197	11	18
206	Dynamic Path Planning for Inserting a Steerable Needle Into a Soft Tissue. *IEEE/ASME Transactions on Mechatronics*, **2014**, 19, 549-558	5.5	18
205	Automated Transportation of Multiple Cell Types Using a Robot-Aided Cell Manipulation System With Holographic Optical Tweezers. *IEEE/ASME Transactions on Mechatronics*, **2017**, 22, 804-814	5.5	18
204	A simple hybrid fuzzy PD controller. *Mechatronics*, **2004**, 14, 877-890	3	18
203	Integrated Design and Control under Uncertainty: A Fuzzy Modeling Approach. *Industrial & Engineering Chemistry Research*, **2010**, 49, 1312-1324	3.9	17
202	Automated transportation of single cells using robot-tweezer manipulation system. *Journal of the Association for Laboratory Automation*, **2011**, 16, 263-70		17
201	Nonlinear PD Synchronized Control for Parallel Manipulators		17
200	Design of an Interactive Control System for a Multisection Continuum Robot. *IEEE/ASME Transactions on Mechatronics*, **2018**, 23, 2379-2389	5.5	16
199	An Inverse-Kinematics Table-Based Solution of a Humanoid Robot Finger With Nonlinearly Coupled Joints. *IEEE/ASME Transactions on Mechatronics*, **2009**, 14, 273-281	5.5	16
198	Automated In Vivo Navigation of Magnetic-Driven Microrobots Using OCT Imaging Feedback. *IEEE Transactions on Biomedical Engineering*, **2020**, 67, 2349-2358	5	16
197	Characterization of a Honeycomb-Like Scaffold With Dielectrophoresis-Based Patterning for Tissue Engineering. *IEEE Transactions on Biomedical Engineering*, **2017**, 64, 755-764	5	15
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190	Probing cell biophysical behavior based on actin cytoskeleton modeling and stretching manipulation with optical tweezers. *Applied Physics Letters*, **2013**, 103, 083706	3.4	14
189	A switching controller for high speed cell transportation by using a robot-aided optical tweezers system. *Automatica*, **2018**, 89, 308-315	5.7	13
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187	Development of an FPGA-Based Motion Control ASIC for Robotic Manipulators **2006**,		13
186	Synchronization and Control of Multiagent Systems		13
185	Force Sensing and Control in Robot-Assisted Suspended Cell Injection System. *Intelligent Systems Reference Library*, **2012**, 61-88	0.8	13
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177	Microfluidic platform for probing cancer cells migration property under periodic mechanical confinement. *Biomicrofluidics*, **2018**, 12, 024118	3.2	11
176	A new piezo-driven ultrasonic cell microinjection system **2010**,		11
175	Position and force tracking of a two-manipulator system manipulating a flexible beam. *Journal of Field Robotics*, **2001**, 18, 197-212		11
174	Electrotaxis of tumor-initiating cells of H1975 lung adenocarcinoma cells is associated with both activation of stretch-activated cation channels (SACCs) and internal calcium release. *Bioelectrochemistry*, **2018**, 124, 80-92	5.6	10

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171	Translational and rotational manipulation of filamentous cells using optically driven microrobots. *Optics Express*, **2019**, 27, 16475-16482	3.3	10
170	Monitoring the intracellular calcium response to a dynamic hypertonic environment. *Scientific Reports*, **2016**, 6, 23591	4.9	10
169	Simultaneous Localization and Mapping-Based In Vivo Navigation Control of Microparticles. *IEEE Transactions on Industrial Informatics*, **2020**, 16, 2956-2964	11.9	10
168	Modeling and experimental study for minimization of energy consumption of a mobile robot **2012**,		9
167	A dynamic priority strategy in decentralized motion planning for formation forming of multiple mobile robots **2009**,		9
166	Penetration force measurement and control in robotic cell microinjection **2009**,		9
165	Controlling Swarms of Mobile Robots for Switching between Formations Using Synchronization Concept. *Proceedings - IEEE International Conference on Robotics and Automation*, **2007**,		9
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158	3-D Automatic Microassembly by Vision-Based Control **2007**,		8
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87	Design of an automated controller with collision-avoidance capability for in-vivo transportation of biological cells **2017**,		2
86	Dielectrophoresis-based automatic 3D cell manipulation and patterning through a micro-electrode integrated multi-layer scaffold **2014**,		2
85	Dynamics calibration of optically trapped cells with adaptive control technology **2013**,		2
84	Connectivity constrained multirobot navigation with considering physical size of robots **2011**,		2

83	Modeling and cooperation of two-arm robotic system manipulating a deformable object		2
82	Distributed neural network-based policy gradient reinforcement learning for multi-robot formations **2008**,		2
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56	An experimental study on leader-follower coalition method for solving multirobot task allocation problems **2010**,	1
55	Motion planning of multirobot formation **2010**,	1
54	An online coalition based approach to solving resource constrained multirobot task allocation problem **2010**,	1
53	Motion planning of multiple mobile robots with formation requirement **2010**,	1
52	Multilevel based topology design and formation control of robot swarms **2011**,	1
51	Mechanical characterization of human red blood cells by robotic manipulation with optical tweezers **2009**,	1
50	A decentralized local constraint path planner for multiple mobile robots **2009**,	1
49	Networked architecture for multi-robot task reallocation in dynamic environment **2009**,	1
48	Localization strategies for indoor multi-robot formations **2009**,	1

47	Pairing and moving swarm of micro particles into array with a robot-tweezer manipulation system **2011**,		1
46	Dynamic path planning in robot-aided optical manipulation of biological cells **2012**,		1
45	A mechanical model of biological cells in microinjection **2009**,		1
44	A synchronization control strategy for multiple robot systems using shape regulation technology **2008**,		1
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19	Laser-induced fusion of biological cells with cell positioning technique **2021**, 137-146		
18	Automated transportation of multiple types of cells with holographic optical tweezers **2021**, 61-74		
17	Cell biopsy using robot-aided optical manipulation of cell reorientation technique **2021**, 147-167		
16	Automated pairing manipulation of biological cells with a robot-tweezers manipulation system **2021**, 39-59		
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13	Cell rotation **2022**, 213-241		
12	Cell patterning **2022**, 347-382		

11 Cell adhesion **2022**, 383-403

10 Cell stretching and compression **2022**, 107-162

9 Three-dimensional image reconstruction and intracellular surgery **2022**, 243-274

8 Cell manipulation tools **2022**, 17-49

7 Cell navigation and delivery in vivo **2022**, 433-465

6 Robotic cell injection **2022**, 51-105

5 Cell stimulation and migration control **2022**, 311-345

4 Cell sorting and separation **2022**, 275-310

3 Cell fusion **2022**, 405-431

2 Cell transport with optical tweezers **2022**, 163-211

1 Organelle biopsy and gene editing of single cells **2022**, 467-510