Ning Cai

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484 41 11 21 h-index g-index citations papers 58 641 4.26 2.3 avg, IF L-index ext. citations ext. papers

| # | Paper | IF | Citations |
|----|---|-----|-----------|
| 41 | Consensus problems for high-order linear time-invariant swarm systems. <i>Physica A: Statistical Mechanics and Its Applications</i> , 2010 , 389, 5619-5627 | 3.3 | 71 |
| 40 | Swarm stability of high-order linear time-invariant swarm systems. <i>IET Control Theory and Applications</i> , 2011 , 5, 402-408 | 2.5 | 50 |
| 39 | Formation controllability of high-order linear time-invariant swarm systems. <i>IET Control Theory and Applications</i> , 2010 , 4, 646-654 | 2.5 | 48 |
| 38 | Dynamical Response of Electrical Activities in Digital Neuron Circuit Driven by Autapse. International Journal of Bifurcation and Chaos in Applied Sciences and Engineering, 2017, 27, 1750187 | 2 | 42 |
| 37 | Adaptive sliding mode dynamic controller with integrator in the loop for nonholonomic wheeled mobile robot trajectory tracking. <i>International Journal of Control</i> , 2014 , 87, 964-975 | 1.5 | 39 |
| 36 | A Novel Clustering Method Based on Quasi-Consensus Motions of Dynamical Multiagent Systems. <i>Complexity</i> , 2017 , 2017, 1-8 | 1.6 | 36 |
| 35 | On Performance of Peer Review for Academic Journals: Analysis Based on Distributed Parallel System. <i>IEEE Access</i> , 2019 , 7, 19024-19032 | 3.5 | 33 |
| 34 | On Almost Controllability of Dynamical Complex Networks with Noises. <i>Journal of Systems Science and Complexity</i> , 2019 , 32, 1125-1139 | 1 | 27 |
| 33 | Swarm Stability Analysis of Nonlinear Dynamical Multi-Agent Systems via Relative Lyapunov Function. <i>Arabian Journal for Science and Engineering</i> , 2014 , 39, 2427-2434 | | 21 |
| 32 | Field coupling-induced pattern formation in two-layer neuronal network. <i>Physica A: Statistical Mechanics and Its Applications</i> , 2018 , 501, 141-152 | 3.3 | 15 |
| 31 | Consensus of swarm systems with time delays and topology uncertainties. <i>IET Control Theory and Applications</i> , 2013 , 7, 1168-1178 | 2.5 | 11 |
| 30 | Adaptive Guaranteed-Performance Consensus Control for Multi-Agent Systems with an Adjustable Convergence Speed. <i>Discrete Dynamics in Nature and Society</i> , 2019 , 2019, 1-9 | 1.1 | 10 |
| 29 | Almost decouplability of any directed weighted network topology. <i>Physica A: Statistical Mechanics and Its Applications</i> , 2015 , 436, 637-645 | 3.3 | 9 |
| 28 | On quantitatively measuring controllability of complex networks. <i>Physica A: Statistical Mechanics and Its Applications</i> , 2017 , 474, 282-292 | 3.3 | 8 |
| 27 | A controllability synthesis problem for dynamic multi-agent systems with linear high-order protocol. <i>International Journal of Control, Automation and Systems</i> , 2014 , 12, 1366-1371 | 2.9 | 8 |
| 26 | Trajectory Planning with Pose Feedback for a Dual-Arm Space Robot. <i>Journal of Control Science and Engineering</i> , 2016 , 2016, 1-9 | 1.2 | 7 |
| 25 | Analysis of Effects to Journal Impact Factors Based on Citation Networks Generated via Social Computing. <i>IEEE Access</i> , 2019 , 7, 19775-19781 | 3.5 | 6 |

(2018-2015)

| 24 | Agent-based model for rural Urban migration: A dynamic consideration. <i>Physica A: Statistical Mechanics and Its Applications</i> , 2015 , 436, 806-813 | 3.3 | 6 |
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| 23 | Energy efficient EDF-VD-based mixed-criticality scheduling with shared resources. <i>Journal of Systems Architecture</i> , 2021 , 119, 102246 | 5.5 | 6 |
| 22 | Output formation tracking for networked systems with limited energy and aperiodic silence. <i>Chinese Journal of Aeronautics</i> , 2021 , | 3.7 | 4 |
| 21 | Swarm stability of linear time-invariant descriptor compartmental networks. <i>IET Control Theory and Applications</i> , 2015 , 9, 793-800 | 2.5 | 3 |
| 20 | Analysis of journal evaluation indicators: an experimental study based on unsupervised Laplacian score. <i>Scientometrics</i> , 2020 , 124, 233-254 | 3 | 3 |
| 19 | On Controllability Problems of High-Order Dynamical Multi-Agent Systems. <i>Arabian Journal for Science and Engineering</i> , 2014 , 39, 4261-4267 | | 3 |
| 18 | On generalized controllability canonical form with multiple input variables. <i>International Journal of Control, Automation and Systems</i> , 2017 , 15, 169-177 | 2.9 | 2 |
| 17 | Clustering by group consensus of unstable dynamic linear high-order multi-agent systems 2015, | | 2 |
| 16 | Modeling and Simulation Analysis of Journal Impact Factor Dynamics Based on Submission and Citation Rules. <i>Complexity</i> , 2020 , 2020, 1-17 | 1.6 | 2 |
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| 15 | 2010, | | 2 |
| 15 | 2010, Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011, | | 2 |
| | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical | | |
| 14 | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011 , ASYMPTOTIC SWARM STABILITY OF HIGH-ORDER MULTI-AGENT SYSTEMS: CONDITION AND | 2.6 | 2 |
| 14 | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011, ASYMPTOTIC SWARM STABILITY OF HIGH-ORDER MULTI-AGENT SYSTEMS: CONDITION AND APPLICATION. Control and Intelligent Systems, 2012, 40, Data Fusion of Multivariate Time Series: Application to Noisy 12-Lead ECG Signals. Applied Sciences | 2.6 | 2 |
| 14 13 | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011, ASYMPTOTIC SWARM STABILITY OF HIGH-ORDER MULTI-AGENT SYSTEMS: CONDITION AND APPLICATION. Control and Intelligent Systems, 2012, 40, Data Fusion of Multivariate Time Series: Application to Noisy 12-Lead ECG Signals. Applied Sciences (Switzerland), 2019, 9, 105 A neural networkBased sliding mode controller of folding-boom aerial work platform. Advances in | | 2 2 1 |
| 14 13 12 | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011, ASYMPTOTIC SWARM STABILITY OF HIGH-ORDER MULTI-AGENT SYSTEMS: CONDITION AND APPLICATION. Control and Intelligent Systems, 2012, 40, Data Fusion of Multivariate Time Series: Application to Noisy 12-Lead ECG Signals. Applied Sciences (Switzerland), 2019, 9, 105 A neural networkBased sliding mode controller of folding-boom aerial work platform. Advances in Mechanical Engineering, 2017, 9, 168781401772087 | | 2 2 1 |
| 14 13 12 11 | Swarm Stability of Compartmental Networks with Linear Time-Invariant High-Order Dynamical Protocol 2011, ASYMPTOTIC SWARM STABILITY OF HIGH-ORDER MULTI-AGENT SYSTEMS: CONDITION AND APPLICATION. Control and Intelligent Systems, 2012, 40, Data Fusion of Multivariate Time Series: Application to Noisy 12-Lead ECG Signals. Applied Sciences (Switzerland), 2019, 9, 105 A neural networkBased sliding mode controller of folding-boom aerial work platform. Advances in Mechanical Engineering, 2017, 9, 168781401772087 | 1.2 | 2 2 1 1 |

| 6 | Drive Control of a Class of Scan Systems. <i>Applied Mechanics and Materials</i> , 2013 , 397-400, 1184-1187 | 0.3 |
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| 5 | Consensus Analysis of Nonlinear Dynamical Multi-Agent Systems by Relative Lyapunov Function Method. <i>Advanced Materials Research</i> , 2012 , 482-484, 1969-1972 | 0.5 |
| 4 | Weighted P-Rank: al Weighted Article Ranking Algorithm Based on Lal Heterogeneous Scholarly Network. Lecture Notes in Computer Science, 2021, 537-548 | 0.9 |
| 3 | On Time Effect of Preschool Education: Social Analysis Based on CUCDS. <i>Complexity</i> , 2021 , 2021, 1-10 | 1.6 |
| 2 | Decentralized Modeling, Analysis, Control, and Application of Distributed Dynamic Systems. <i>Journal of Control Science and Engineering</i> , 2016 , 2016, 1-2 | 1.2 |
| 1 | Energy-Constraint Output Formation for Networked Systems With Random Communication Silence and Switching Topologies. <i>IEEE Access</i> , 2021 , 9, 8312-8323 | 3.5 |