Li-Min Zhu

List of Publications by Year in Descending Order

234 papers	4,949 citations	35 h-index	61 g-index
257 ext. papers	6,176 ext. citations	4.4 avg, IF	6.43 L-index

#	Paper	IF	Citations
234	Design and Development of a New Piezoelectric-Actuated Biaxial Compliant Microgripper With Long Strokes. *IEEE Transactions on Automation Science and Engineering*, **2022**, 1-12	4.9	1
233	Robust Repetitive Control of Nanopositioning Stages Using the Spectrum-Selection Filter With Narrow Passbands. *IEEE/ASME Transactions on Mechatronics*, **2022**, 1-6	5.5	0
232	A single-pose series sphere-based calibration method for camera-projector structured light system. *Optics Communications*, **2022**, 507, 127659	2	
231	Phase-to-coordinates Calibration for Fringe Projection Profilometry Using Gaussian Process Regression. *IEEE Transactions on Instrumentation and Measurement*, **2022**, 1-1	5.2	
230	Brain-Computer Interface Using Brain Power Map and Cognition Detection Network During Flight. *IEEE/ASME Transactions on Mechatronics*, **2022**, 1-11	5.5	6
229	Simultaneous damping and tracking control of a normal-stressed electromagnetic actuated nano-positioning stage. *Sensors and Actuators A: Physical*, **2022**, 338, 113467	3.9	2
228	High-performance control of fast tool servos with robust disturbance observer and modified H control. *Mechatronics*, **2022**, 84, 102781	3	1
227	High performance raster scanning of atomic force microscopy using Model-free Repetitive Control. *Mechanical Systems and Signal Processing*, **2022**, 173, 109027	7.8	0
226	Dual-Notch Based Repetitive Control for Tracking Lissajous Scan Trajectories with Piezo-Actuated Nano-Scanners. *IEEE Transactions on Instrumentation and Measurement*, **2022**, 1-1	5.2	2
225	An iterative contouring error compensation scheme for five-axis precision motion systems. *Mechanical Systems and Signal Processing*, **2022**, 178, 109226	7.8	0
224	Modeling, design and control of normal-stressed electromagnetic actuated fast tool servos. *Mechanical Systems and Signal Processing*, **2022**, 178, 109304	7.8	1
223	A Transfer Learning-Based Method for Personalized State of Health Estimation of Lithium-Ion Batteries. *IEEE Transactions on Neural Networks and Learning Systems*, **2022**, 1-11	10.3	2
222	Nonparametric Bayesian Prior Inducing Deep Network for Automatic Detection of Cognitive Status. *IEEE Transactions on Cybernetics*, **2021**, 51, 5483-5496	10.2	28
221	Redistributing Controller Orders to Increase Positioning Bandwidth in Nanopositioners. *IFAC-PapersOnLine*, **2021**, 54, 97-102	0.7	
220	Robot line structured light vision measurement system: light strip center extraction and system calibration. *Optical Engineering*, **2021**, 60,	1.1	1
219	Design and Control of a Normal-Stressed Electromagnetic Actuated Nano-positioning Stage. *Lecture Notes in Computer Science*, **2021**, 324-334	0.9	0
218	High-bandwidth nanopositioning via active control of system resonance. *Frontiers of Mechanical Engineering*, **2021**, 16, 331-339	3.3	3

217	On the mechanisms of surface microdischarge plasma treatment of onychomycosis: Penetration, uptake, and chemical reactions. *Plasma Processes and Polymers*, **2021**, 18, 2000204	3.4	2
216	Investigation of NH4NO3 formation by air plasma and wasted ammonia. *Plasma Processes and Polymers*, **2021**, 18, 2000223	3.4	2
215	Extraction and segmentation method of laser stripe in linear structured light scanner. *Optical Engineering*, **2021**, 60,	1.1	1
214	Analytical model and experimental verification of an elliptical bridge-type compliant displacement amplification mechanism. *Review of Scientific Instruments*, **2021**, 92, 055109	1.7	3
213	Robust high-bandwidth control of nano-positioning stages with Kalman filter based extended state observer and H control. *Review of Scientific Instruments*, **2021**, 92, 065003	1.7	1
212	Erratum to A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy[Feb 21 24-32]. *IEEE/ASME Transactions on Mechatronics*, **2021**, 26, 1700-1700	5.5	
211	. *IEEE Transactions on Aerospace and Electronic Systems*, **2021**, 57, 1753-1767	3.7	0
210	Enhanced Odd-Harmonic Repetitive Control of Nanopositioning Stages Using Spectrum-Selection Filtering Scheme for High-Speed Raster Scanning. *IEEE Transactions on Automation Science and Engineering*, **2021**, 18, 1087-1096	4.9	2
209	Tracking Control of Nanopositioning Stages Using Parallel Resonant Controllers for High-Speed Nonraster Sequential Scanning. *IEEE Transactions on Automation Science and Engineering*, **2021**, 18, 1218-1228	4.9	7
208	GRU-Type LARC Strategy for Precision Motion Control With Accurate Tracking Error Prediction. *IEEE Transactions on Industrial Electronics*, **2021**, 68, 812-820	8.9	22
207	Rotated Sphere Haar Wavelet and Deep Contractive Auto-Encoder Network With Fuzzy Gaussian SVM for Pilot's Pupil Center Detection. *IEEE Transactions on Cybernetics*, **2021**, 51, 332-345	10.2	11
206	Intelligent Feedforward Compensation Motion Control of Maglev Planar Motor With Precise Reference Modification Prediction. *IEEE Transactions on Industrial Electronics*, **2021**, 68, 7768-7777	8.9	9
205	Local asymmetrical corner trajectory smoothing with bidirectional planning and adjusting algorithm for CNC machining. *Robotics and Computer-Integrated Manufacturing*, **2021**, 68, 102058	9.2	8
204	Generative Model-Driven Sampling Strategy for the High-Efficiency Measurement of Complex Surfaces on Coordinate Measuring Machines. *IEEE Transactions on Instrumentation and Measurement*, **2021**, 70, 1-11	5.2	3
203	Nonparametric Hierarchical Hidden Semi-Markov Model for Brain Fatigue Behavior Detection of Pilots During Flight. *IEEE Transactions on Intelligent Transportation Systems*, **2021**, 1-12	6.1	14
202	Detecting Dynamic Behavior of Brain Fatigue Through 3-D-CNN-LSTM. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, **2021**, 1-11	7.3	6
201	Accelerated Iteration Algorithm based Contouring Error Estimation for Multi-axis Motion Control. *IEEE/ASME Transactions on Mechatronics*, **2021**, 1-1	5.5	6
200	Dynamics Learning With Object-Centric Interaction Networks for Robot Manipulation. *IEEE Access*, **2021**, 9, 68277-68288	3.5	0

199	Development of a new compliant active-force support system. *IEEE/ASME Transactions on Mechatronics*, **2021**, 1-1	5.5	3
198	A Novel Compliant Nanopositioning Stage Driven by a Normal-Stressed Electromagnetic Actuator. *IEEE Transactions on Automation Science and Engineering*, **2021**, 1-10	4.9	0
197	Development of a High-Performance Force Sensing Fast Tool Servo. *IEEE Transactions on Industrial Informatics*, **2021**, 1-1	11.9	2
196	Tri-axial Fast Tool Servo Using Hybrid Electromagnetic-Piezoelectric Actuation for Diamond Turning. *IEEE Transactions on Industrial Electronics*, **2021**, 1-1	8.9	6
195	Fatigue Detection of Pilots' Brain Through Brains Cognitive Map and Multilayer Latent Incremental Learning Model. *IEEE Transactions on Cybernetics*, **2021**, PP,	10.2	8
194	Skeleton Curve-Guided Five-Axis Sweep Scanning for Surface With Multiple Holes. *IEEE Transactions on Automation Science and Engineering*, **2021**, 1-16	4.9	1
193	Human Exploratory Procedures based Hybrid Measurement Fusion for Material Recognition. *IEEE/ASME Transactions on Mechatronics*, **2021**, 1-1	5.5	5
192	ROpenPose: A Rapider OpenPose Model for Astronaut Operation Attitude Detection. *IEEE Transactions on Industrial Electronics*, **2021**, 1-1	8.9	7
191	Profile tracking for multi-axis ultrasonic inspection of model-unknown free-form surfaces based on energy concentration. *Measurement: Journal of the International Measurement Confederation*, **2021**, 172, 108867	4.6	3
190	Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage. *IEEE/ASME Transactions on Mechatronics*, **2021**, 26, 2186-2194	5.5	9
189	Fractional order zero phase error tracking control of a novel decoupled 2-DOF compliant micro-positioning stage. *Journal of Micromechanics and Microengineering*, **2021**, 31, 105006	2	1
188	Rate-dependent input curve shaping of the piezoelectric actuator based optical resonator cavity displacement characteristics for an external cavity diode laser. *Review of Scientific Instruments*, **2021**, 92, 095008	1.7	0
187	Trajectory modification method based on frequency domain analysis for precision contouring motion control systems. *Mechanical Systems and Signal Processing*, **2021**, 158, 107646	7.8	4
186	CPG-Based Hierarchical Locomotion Control for Modular Quadrupedal Robots Using Deep Reinforcement Learning. *IEEE Robotics and Automation Letters*, **2021**, 6, 7193-7200	4.2	2
185	. *IEEE Transactions on Industrial Electronics*, **2021**, 68, 11266-11275	8.9	10
184	Complex Surface Reconstruction Based on Fusion of Surface Normals and Sparse Depth Measurement. *IEEE Transactions on Instrumentation and Measurement*, **2021**, 70, 1-13	5.2	3
183	Online Koopman Operator Learning to identify Cross-Coupling Effect of Piezoelectric Tube Scanners in Atomic Force Microscopes. *IEEE Transactions on Industrial Informatics*, **2021**, 1-1	11.9	3
182	Autonomous Profile Tracking for Multiaxis Ultrasonic Measurement of Deformed Surface in Mirror Milling. *IEEE Transactions on Instrumentation and Measurement*, **2021**, 70, 1-13	5.2	0

181	On-Machine Calibration Method for In Situ Stereo Deflectometry System. *IEEE Transactions on Instrumentation and Measurement*, **2021**, 70, 1-8	5.2	0
180	High-Bandwidth Tracking Control of Piezoactuated Nanopositioning Stages via Active Modal Control. *IEEE Transactions on Automation Science and Engineering*, **2021**, 1-9	4.9	2
179	Hysteresis modeling with frequency-separation-based Gaussian process and its application to sinusoidal scanning for fast imaging of atomic force microscope. *Sensors and Actuators A: Physical*, **2020**, 311, 112070	3.9	5
178	Operational-space wrench and acceleration capability analysis for multi-link cable-driven robots. *Science China Technological Sciences*, **2020**, 63, 2063-2072	3.5	3
177	. *IEEE/ASME Transactions on Mechatronics*, **2020**, 1-1	5.5	28
176	Command-shaping based on impulse response function for dynamic-mode control of internal and external cavities in external-cavity diode laser. *Review of Scientific Instruments*, **2020**, 91, 023101	1.7	0
175	Reconstruction of multi-frame semi-sparse scanning probe microscopy images using dependent Gaussian process. *Measurement Science and Technology*, **2020**, 31, 045013	2	1
174	A novel 3D radius compensation method of probe stylus tip in the free-form surface profile curve scanning measurement. *Measurement Science and Technology*, **2020**, 31, 085001	2	1
173	Development of a Novel Pile-Up Structure Based Nanopositioning Mechanism Driven by Piezoelectric Actuator. *IEEE/ASME Transactions on Mechatronics*, **2020**, 25, 502-512	5.5	5
172	. *IEEE/ASME Transactions on Mechatronics*, **2020**, 25, 547-557	5.5	6
171	An error-bounded B-spline curve approximation scheme using dominant points for CNC interpolation of micro-line toolpath. *Robotics and Computer-Integrated Manufacturing*, **2020**, 64, 101930	9.2	11
170	Deterioration of form accuracy induced by servo dynamics errors and real-time compensation for slow tool servo diamond turning of complex-shaped optics. *International Journal of Machine Tools and Manufacture*, **2020**, 154, 103556	9.4	8
169	Development of a piezoelectrically actuated dual-stage fast tool servo. *Mechanical Systems and Signal Processing*, **2020**, 144, 106873	7.8	21
168	. *IEEE/ASME Transactions on Mechatronics*, **2020**, 1-1	5.5	6
167	Prediction Model based Contouring Error Iterative Pre-Compensation Scheme for Precision Multi-axis Motion Systems. *IEEE/ASME Transactions on Mechatronics*, **2020**, 1-1	5.5	9
166	Experimental validation of the simultaneous damping and tracking controller design strategy for high-bandwidth nanopositioning ▯a PAVPF approach. *IET Control Theory and Applications*, **2020**, 14, 3506-3514	2.5	4
165	Confined spaces path following for cable-driven snake robots with prediction lookup and interpolation algorithms. *Science China Technological Sciences*, **2020**, 63, 255-264	3.5	9
164	Detecting Fatigue Status of Pilots Based on Deep Learning Network Using EEG Signals. *IEEE Transactions on Cognitive and Developmental Systems*, **2020**, 1-1	3	24

163	Integration of optimized feedrate into an online adaptive force controller for robot milling. *International Journal of Advanced Manufacturing Technology*, **2020**, 106, 1533-1542	3.2	4
162	A closed-loop error compensation method for robotic flank milling. *Robotics and Computer-Integrated Manufacturing*, **2020**, 63, 101928	9.2	11
161	. *IEEE Access*, **2020**, 8, 8520-8532	3.5	9
160	Chatter detection in milling processes using frequency-domain Rényi entropy. *International Journal of Advanced Manufacturing Technology*, **2020**, 106, 877-890	3.2	12
159	Learning Semantic Keypoint Representations for Door Opening Manipulation. *IEEE Robotics and Automation Letters*, **2020**, 5, 6980-6987	4.2	2
158	Wall thickness error prediction and compensation in end milling of thin-plate parts. *Precision Engineering*, **2020**, 66, 550-563	2.9	1
157	Sliding mode control with third-order contour error estimation for free-form contour following. *Precision Engineering*, **2020**, 66, 282-294	2.9	5
156	Inverse Rate-Dependent Rayleigh Model Based Feedforward Control for Piezoelectric-Driven Mechanism. *IEEE Access*, **2020**, 8, 194808-194819	3.5	0
155	The modular design of trajectory compensation based on ATCF for precision motion control. *Mechanical Systems and Signal Processing*, **2020**, 135, 106393	7.8	5
154	Novel Nonlinear Approach for Real-Time Fatigue EEG Data: An Infinitely Warped Model of Weighted Permutation Entropy. *IEEE Transactions on Intelligent Transportation Systems*, **2020**, 21, 2437-2448	6.1	10
153	Self-Paced Dynamic Infinite Mixture Model for Fatigue Evaluation of Pilots' Brains. *IEEE Transactions on Cybernetics*, **2020**, PP,	10.2	24
152	Modified Repetitive Control Based Cross-Coupling Compensation Approach for the Piezoelectric Tube Scanner of Atomic Force Microscopes. *IEEE/ASME Transactions on Mechatronics*, **2019**, 24, 666-676	5.5	24
151	Fractional repetitive control of nanopositioning stages for tracking high-frequency periodic inputs with nonsynchronized sampling. *Review of Scientific Instruments*, **2019**, 90, 055108	1.7	4
150	Rate-dependent hysteresis modeling and compensation of piezoelectric actuators using Gaussian process. *Sensors and Actuators A: Physical*, **2019**, 295, 357-365	3.9	20
149	Path Tracking of a Cable-Driven Snake Robot With a Two-Level Motion Planning Method. *IEEE/ASME Transactions on Mechatronics*, **2019**, 24, 935-946	5.5	14
148	An accelerated convergence approach for real-time deformation compensation in large thin-walled parts machining. *International Journal of Machine Tools and Manufacture*, **2019**, 142, 98-106	9.4	25
147	Enhancing the metrological performance of non-raster scanning probe microscopy using Gaussian process regression. *Measurement Science and Technology*, **2019**, 30, 095004	2	4
146	Model-driven photometric stereo for in-process inspection of non-diffuse curved surfaces. *CIRP Annals - Manufacturing Technology*, **2019**, 68, 563-566	4.9	4

145	Double Taylor Expansion-Based Real-Time Contouring Error Estimation for Multiaxis Motion Systems. *IEEE Transactions on Industrial Electronics*, **2019**, 66, 9490-9499	8.9	17
144	Modified Robust Dynamic Control for a Diamond Parallel Robot. *IEEE/ASME Transactions on Mechatronics*, **2019**, 24, 959-968	5.5	9
143	Fv-SVM-Based Wall-Thickness Error Decomposition for Adaptive Machining of Large Skin Parts. *IEEE Transactions on Industrial Informatics*, **2019**, 15, 2426-2434	11.9	13
142	Tool path generation for five-axis machining of blisks with barrel cutters. *International Journal of Production Research*, **2019**, 57, 1300-1314	7.8	5
141	Stiffness-based pose optimization of an industrial robot for five-axis milling. *Robotics and Computer-Integrated Manufacturing*, **2019**, 55, 19-28	9.2	57
140	Dynamic mode matching of internal and external cavities for enhancing the mode-hop-free synchronous tuning characteristics of an external-cavity diode laser. *Applied Physics B: Lasers and Optics*, **2019**, 125, 1	1.9	2
139	Extended unified wrench model suitable for the end effect of the ironless permanent magnet planar motor. *IET Electric Power Applications*, **2019**, 13, 402-409	1.8	2
138	Compensation of deformation errors in five-axis flank milling of thin-walled parts via tool path optimization. *Precision Engineering*, **2019**, 55, 77-87	2.9	35
137	A general, fast and robust B-spline fitting scheme for micro-line tool path under chord error constraint. *Science China Technological Sciences*, **2019**, 62, 321-332	3.5	16
136	Third-order chord error estimation for freeform contour in computer-aided manufacturing and computer numerical control systems. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2019**, 233, 863-874	2.4	6
135	Parallel acceleration/deceleration feedrate scheduling for computer numerical control machine tools based on bi-directional scanning technique. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2019**, 233, 937-947	2.4	5
134	Surface form error prediction in five-axis flank milling of thin-walled parts. *International Journal of Machine Tools and Manufacture*, **2018**, 128, 21-32	9.4	74
133	Accurate three-dimensional contouring error estimation and compensation scheme with zero-phase filter. *International Journal of Machine Tools and Manufacture*, **2018**, 128, 33-40	9.4	25
132	Non-Normal Dynamic Analysis for Predicting Transient Milling Stability. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2018**, 140,	1.6	2
131	Improved forecasting compensatory control to guarantee the remaining wall thickness for pocket milling of a large thin-walled part. *International Journal of Advanced Manufacturing Technology*, **2018**, 94, 1677-1688	3.2	18
130	A locally optimal transition method with analytical calculation of transition length for computer numerical control machining of short line segments. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2018**, 232, 2409-2419	2.4	11
129	An Accurate Method for Determining Cutter-Workpiece Engagements in Five-Axis Milling With a General Tool Considering Cutter Runout. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2018**, 140,	3.3	12
128	Real-time local smoothing for five-axis linear toolpath considering smoothing error constraints. *International Journal of Machine Tools and Manufacture*, **2018**, 124, 67-79	9.4	45

127	Unified wrench model of an ironless permanent magnet planar motor with 2D periodic magnetic field. *IET Electric Power Applications*, **2018**, 12, 423-430	1.8	9
126	Patterns of Regenerative Milling Chatter Under Joint Influences of Cutting Parameters, Tool Geometries, and Runout. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2018**, 140,	3.3	22
125	Newton-ILC Contouring Error Estimation and Coordinated Motion Control for Precision Multiaxis Systems With Comparative Experiments. *IEEE Transactions on Industrial Electronics*, **2018**, 65, 1470-1480	8.9	42
124	Model-Data Driven Learning Adaptive Robust Control of Precision Mechatronic Motion Systems With Comparative Experiments. *IEEE Access*, **2018**, 6, 78286-78296	3.5	4
123	Micro-Grinding Performance of Hard-Brittle Chip Materials in Precision Micro-Grinding Microgroove. *Journal of Shanghai Jiaotong University (Science)*, **2018**, 23, 70-76	0.6	2
122	Motion Control of the Piezoelectric Tube Scanner for Lissajous Trajectories with Modified Repetitive Control **2018**,		1
121	Real-time feedrate scheduling for five-axis machining by simultaneously planning linear and angular trajectories. *International Journal of Machine Tools and Manufacture*, **2018**, 135, 78-96	9.4	18
120	Feedrate scheduling for interpolation of parametric tool path using the sine series representation of jerk profile. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2017**, 231, 2359-2371	2.4	28
119	High-Speed Tracking of a Nanopositioning Stage Using Modified Repetitive Control. *IEEE Transactions on Automation Science and Engineering*, **2017**, 14, 1467-1477	4.9	41
118	An Integrated Model-Data-Based Zero-Phase Error Tracking Feedforward Control Strategy With Application to an Ultraprecision Wafer Stage. *IEEE Transactions on Industrial Electronics*, **2017**, 64, 4139-4149	8.9	33
117	Dynamics and Stability Prediction of Five-Axis Flat-End Milling. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2017**, 139,	3.3	20
116	A survey on dielectric elastomer actuators for soft robots. *Bioinspiration and Biomimetics*, **2017**, 12, 011003	2.8	210
115	Accurate cutting force prediction of helical milling operations considering the cutter runout effect. *International Journal of Advanced Manufacturing Technology*, **2017**, 92, 4133-4144	3.2	6
114	A spline-based method for stability analysis of milling processes. *International Journal of Advanced Manufacturing Technology*, **2017**, 89, 2571-2586	3.2	11
113	Neural Network Learning Adaptive Robust Control of an Industrial Linear Motor-Driven Stage With Disturbance Rejection Ability. *IEEE Transactions on Industrial Informatics*, **2017**, 13, 2172-2183	11.9	84
112	Damping Control of Piezo-Actuated Nanopositioning Stages With Recursive Delayed Position Feedback. *IEEE/ASME Transactions on Mechatronics*, **2017**, 22, 855-864	5.5	35
111	Positive acceleration, velocity and position feedback based damping control approach for piezo-actuated nanopositioning stages. *Mechatronics*, **2017**, 47, 97-104	3	34
110	Design and performance testing of a dielectric elastomer strain sensor. *International Journal of Intelligent Robotics and Applications*, **2017**, 1, 451-458	1.7	7

109	Design of a cable-driven hyper-redundant robot with experimental validation. *International Journal of Advanced Robotic Systems*, **2017**, 14, 172988141773445	1.4	33
108	A highly efficient and convergent optimization method for multipoint tool orientation in five-axis machining. *International Journal of Advanced Manufacturing Technology*, **2017**, 93, 2711-2722	3.2	5
107	Tool path generation via the multi-criteria optimisation for flat-end milling of sculptured surfaces. *International Journal of Production Research*, **2017**, 55, 4261-4282	7.8	12
106	A product-of-exponential-based robot calibration method with optimal measurement configurations. *International Journal of Advanced Robotic Systems*, **2017**, 14, 172988141774355	1.4	15
105	Integral force feedback control with input shaping: Application to piezo-based scanning systems in ECDLs. *Review of Scientific Instruments*, **2017**, 88, 075006	1.7	11
104	Feasibility of the Bi-Directional Scanning Method in Acceleration/deceleration Feedrate Scheduling for CNC Machining. *Lecture Notes in Computer Science*, **2017**, 171-183	0.9	3
103	Modeling and Control of Piezo-Actuated Nanopositioning Stages: A Survey. *IEEE Transactions on Automation Science and Engineering*, **2016**, 13, 313-332	4.9	306
102	A fractional-order active damping control approach for piezo-actuated nanopositioning stages **2016**,		1
101	Five-axis flank milling of impellers: Optimal geometry of a conical tool considering stiffness and geometric constraints. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2016**, 230, 38-52	2.4	10
100	Fabrication of microlens array on silicon surface using electrochemical wet stamping technique. *Applied Surface Science*, **2016**, 364, 442-445	6.7	16
99	Simultaneous optimization of the feed direction and tool orientation in five-axis flat-end milling. *International Journal of Production Research*, **2016**, 54, 4537-4546	7.8	9
98	Arc□urface intersection method to calculate cutter□workpiece engagements for generic cutter in five-axis milling. *CAD Computer Aided Design*, **2016**, 73, 1-10	2.9	16
97	Modeling and Identification of Piezoelectric-Actuated Stages Cascading Hysteresis Nonlinearity With Linear Dynamics. *IEEE/ASME Transactions on Mechatronics*, **2016**, 21, 1792-1797	5.5	69
96	Modeling of Piezoelectric-Actuated Nanopositioning Stages Involving with the Hysteresis **2016**, 183-212		2
95	Smooth Tool Path Optimization for Flank Milling Based on the Gradient-Based Differential Evolution Method. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2016**, 138,	3.3	21
94	Five-axis Flank Milling Tool Path Generation with Smooth Rotary Motions. *Procedia CIRP*, **2016**, 56, 161-166	1.8	4
93	An Analytical Transition Algorithm for Real-time CNC Machining of Linear Tool Path. *Procedia CIRP*, **2016**, 56, 344-348	1.8	4
92	Improved Forecasting Compensatory Control through Kalman Filtering. *Procedia CIRP*, **2016**, 56, 349-353	1.8	1

91	Mechanistic Modeling of Five-Axis Machining With a Flat End Mill Considering Bottom Edge Cutting Effect. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2016**, 138,	3.3	17
90	Odd-harmonic repetitive control for high-speed raster scanning of piezo-actuated nanopositioning stages with hysteresis nonlinearity. *Sensors and Actuators A: Physical*, **2016**, 244, 95-105	3.9	20
89	A rate-dependent Prandtl-Ishlinskii model for piezoelectric actuators using the dynamic envelope function based play operator. *Frontiers of Mechanical Engineering*, **2015**, 10, 37-42	3.3	7
88	Mechanistic modeling of five-axis machining with a general end mill considering cutter runout. *International Journal of Machine Tools and Manufacture*, **2015**, 96, 67-79	9.4	34
87	. *IEEE/ASME Transactions on Mechatronics*, **2015**, 20, 1956-1965	5.5	64
86	Cross-coupled controller design for triaxial motion systems based on second-order contour error estimation. *Science China Technological Sciences*, **2015**, 58, 1209-1217	3.5	17
85	Look-ahead interpolation of short line segments using B-spline curve fitting of dominant points. *Proceedings of the Institution of Mechanical Engineers, Part B: Journal of Engineering Manufacture*, **2015**, 229, 1131-1143	2.4	20
84	Geometric conditions for tangent continuity of swept tool envelopes with application to multi-pass flank milling. *CAD Computer Aided Design*, **2015**, 59, 43-49	2.9	11
83	Feedforward deformation control of a dielectric elastomer actuator based on a nonlinear dynamic model. *Applied Physics Letters*, **2015**, 107, 042907	3.4	38
82	Modeling and compensating the dynamic hysteresis of piezoelectric actuators via a modified rate-dependent Prandtl□shlinskii model. *Smart Materials and Structures*, **2015**, 24, 125006	3.4	30
81	High-Bandwidth Control of Nanopositioning Stages via an Inner-Loop Delayed Position Feedback. *IEEE Transactions on Automation Science and Engineering*, **2015**, 12, 1357-1368	4.9	19
80	A complete S-shape feed rate scheduling approach for NURBS interpolator. *Journal of Computational Design and Engineering*, **2015**, 2, 206-217	4.6	25
79	. *IEEE Transactions on Magnetics*, **2015**, 51, 1-10	2	7
78	Analytical curvature-continuous dual-B□ier corner transition for five-axis linear tool path. *International Journal of Machine Tools and Manufacture*, **2015**, 91, 96-108	9.4	58
77	A wavelet-based approach for stability analysis of periodic delay-differential systems with discrete delay. *Nonlinear Dynamics*, **2015**, 79, 1049-1059	5	8
76	Corner rounding of linear five-axis tool path by dual PH curves blending. *International Journal of Machine Tools and Manufacture*, **2015**, 88, 223-236	9.4	71
75	Modeling and Compensation of Asymmetric Hysteresis Nonlinearity for Piezoceramic Actuators With a Modified Prandtl□shlinskii Model. *IEEE Transactions on Industrial Electronics*, **2014**, 61, 1583-1595	8.9	232
74	Integral resonant damping for high-bandwidth control of piezoceramic stack actuators with asymmetric hysteresis nonlinearity. *Mechatronics*, **2014**, 24, 367-375	3	20

73	Envelope Surface Modeling and Tool Path Optimization for Five-Axis Flank Milling Considering Cutter Runout. *Journal of Manufacturing Science and Engineering, Transactions of the ASME*, **2014**, 136,	3.3	30
72	Development of an electrochemical micromachining instrument for the confined etching techniques. *Review of Scientific Instruments*, **2014**, 85, 045122	1.7	
71	High-precision control of piezoelectric nanopositioning stages using hysteresis compensator and disturbance observer. *Smart Materials and Structures*, **2014**, 23, 105007	3.4	29
70	Comparative experiments regarding approaches to feedforward hysteresis compensation for piezoceramic actuators. *Smart Materials and Structures*, **2014**, 23, 095029	3.4	10
69	A Modified Prandtl-Ishlinskii Model for Rate-dependent Hysteresis Nonlinearity Using mth-power Velocity Damping Mechanism. *International Journal of Advanced Robotic Systems*, **2014**, 11, 163	1.4	14
68	High-bandwidth tracking control of piezo-actuated nanopositioning stages using closed-loop input shaper. *Mechatronics*, **2014**, 24, 724-733	3	29
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