## Raffaele Romagnoli

List of Publications by Year in descending order

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#	Article	IF	CITATIONS
1	A Linear Programming Approach to Computing Safe Sets for Software Rejuvenation. , 2022, 6, 1214-1219.		6
2	Faster and Healthier Charging of Lithium-Ion Batteries via Constrained Feedback Control. IEEE Transactions on Control Systems Technology, 2022, 30, 1990-2001.	3.2	7
3	A New Approach to Model Predictive Control Based on Two Degrees of Freedom Control and B-Splines Input Shaping. IEEE Transactions on Automatic Control, 2021, 66, 2770-2777.	3.6	Ο
4	Low-Complexity Fast Charging Strategies Based on Explicit Reference Governors for Li-Ion Battery Cells. IEEE Transactions on Control Systems Technology, 2021, 29, 1597-1608.	3.2	4
5	Resilient Control in the Presence of Man-in-the-Middle Attacks. , 2021, , .		2
6	Secure Networked Control for Decentralized Systems via Software Rejuvenation. , 2020, , .		2
7	Robust Software Rejuvenation for CPS with State Estimation and Disturbances. , 2020, , .		4
8	MPC strategies based on the equivalent hydraulic model for the fast charge of commercial Li-ion batteries. Computers and Chemical Engineering, 2020, 141, 107010.	2.0	9
9	A New Reference Governor Strategy For Union of Linear Constraints. IFAC-PapersOnLine, 2020, 53, 5499-5504.	0.5	1
10	Software Rejuvenation Under Persistent Attacks in Constrained Environments. IFAC-PapersOnLine, 2020, 53, 4088-4094.	0.5	9
11	Safety and Liveness of Software Rejuvenation for Secure Tracking Control. , 2019, , .		7
12	A feedback charge strategy for Li-ion battery cells based on Reference Governor. Journal of Process Control, 2019, 83, 164-176.	1.7	18
13	Secure Networked Control via Software Rejuvenation. , 2019, , .		11
14	A Model Inversion Based Watermark for Replay Attack Detection with Output Tracking. , 2019, , .		14
15	A general framework for approximated model stable inversion. Automatica, 2019, 101, 182-189.	3.0	15
16	Simultaneous Achievement of Open and Closed Loop Diagonal Dominance Through Constant Feedback. Asian Journal of Control, 2019, 21, 686-701.	1.9	2
17	Design of Software Rejuvenation for CPS Security Using Invariant Sets. , 2019, , .		24
18	A B-spline-based pseudo-inversion approach for constrained optimal output transition. International Journal of Control, 2018, 91, 2332-2344.	1.2	1

#	Article	IF	CITATIONS
19	Constrained Optimal End-Effector Positioning Using Pseudo-Inversion and B-Splines: Numerical Simulation on the One Link Flexible Manipulator Linearized Model. , 2018, , .		0
20	Constrained Transient Optimization Using B-Splines Functions as Control Inputs. , 2018, , .		0
21	Modeling and quadratic stabilization of a class of linear uncertain timeâ€varying systems. International Journal of Robust and Nonlinear Control, 2017, 27, 1810-1825.	2.1	3
22	A B-splines based feedforward action for constrained optimization of PID controllers performance. IFAC-PapersOnLine, 2017, 50, 1811-1816.	0.5	1
23	Gain margin based conditions for easy simultaneous achievement of open and closed loop diagonal dominance under unstructured uncertainties. IFAC-PapersOnLine, 2017, 50, 3660-3667.	0.5	1
24	Computationally-efficient constrained control of the state-of-charge of a Li-ion battery cell. , 2017, , .		12
25	Reference-tracking feedforward control design for linear dynamical systems through signal decomposition. , 2017, , .		9
26	performed in the framework of the BATWAL project financed by the Walloon region (Belgium).This research has been funded by the Mandats d'Impulsion Scientific "Optimization-free Control of Nonlinear Systems subject to Constraints" of the Fonds de la Recherche Scientifique (FNRS), Ref. F452617E This research has been funded by Fonds pour la Formation Šla Recherche dans l候Industrie et	0.5	7
27	dans l'Agriculture (FRIA) of th. IFAC-PapersOnLine, 2017, 50, 13747-13753. B-splines and pseudo-inversion as tools for handling saturation constraints in the optimal set-point regulation. , 2017, , .		1
28	Optimal transient performance under output setâ€point reset. International Journal of Robust and Nonlinear Control, 2016, 26, 2788-2806.	2.1	15
29	The quadratic stabilization problem for LTV plants with arbitrary mode-switch dynamics and non uniformly bounded parametric uncertainties. , 2015, , .		1
30	Spline Based Pseudoâ€Inversion of Sampled Data Nonâ€Minimum Phase Systems for an Almost Exact Output Tracking. Asian Journal of Control, 2015, 17, 1866-1879.	1.9	10
31	BMI-Based Stabilization of Linear Uncertain Plants With Polynomially Time Varying Parameters. IEEE Transactions on Automatic Control, 2015, 60, 2283-2288.	3.6	4
32	A mixed numerical–analytical stable pseudoâ€inversion method aimed at attaining an almost exact tracking. International Journal of Robust and Nonlinear Control, 2015, 25, 809-823.	2.1	28
33	Output-transition optimization through a multi-objective least square procedure. , 2014, , .		4
34	Accurate output tracking for nonminimum phase nonhyperbolic and near nonhyperbolic systems. European Journal of Control, 2014, 20, 292-300.	1.6	21
35	Robust stabilization of linear uncertain plants with polynomially time varying parameters. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 11734-11739.	0.4	2
36	A least-squares based pseudoinversion approach for non hyperbolic linear systems. , 2014, , .		0

A least-squares based pseudoinversion approach for non hyperbolic linear systems. , 2014, , . 36

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37	A spline-based technique for optimal set point regulation through pseudo-inversion of nonminimum phase linear systems. , 2013, , .		4
38	Almost perfect tracking through mixed numerical-analytical stable pseudo-inversion of non minimum phase plants. , 2013, , .		10
39	An iterative LMI scheme for output regulation of continuous-time LPV systems with inexactly measured parameters. , 2012, , .		0