Masaki Inoue

List of Publications by Year in descending order

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30	137	5	8
papers	citations	h-index	g-index
30	30	30	123
all docs	docs citations	times ranked	citing authors

#	Article	IF	CITATIONS
1	Data-Driven Human Modeling: Quantifying Personal Tendency Toward Laziness. , 2021, 5, 1219-1224.		3
2	Optimal Power Flow Design for Enhancing Dynamic Performance: Potentials of Reactive Power. IEEE Transactions on Smart Grid, 2021, 12, 599-611.	9.0	10
3	Safe-update of bi-layered controller and its application to power systems. SICE Journal of Control Measurement and System Integration, 2021, 14, 90-96.	0.7	O
4	Gain-Preserving Data-Driven Approximation of the Koopman Operator and Its Application in Robust Controller Design. Mathematics, 2021, 9, 949.	2.2	3
5	Grid Resilience Enhancement by Reference Shaping based on Gray-Box Model. IEEJ Transactions on Electronics, Information and Systems, 2021, 141, 694-703.	0.2	O
6	Modularity in Design of Dynamical Network Systems: Retrofit Control Approach. IEEE Transactions on Automatic Control, 2021, 66, 5205-5220.	5.7	12
7	Temperature and Humidity Control by Recommendation in Soil Cultivation Environment of Greenhouse. Transactions of the Society of Instrument and Control Engineers, 2021, 57, 456-462.	0.2	O
8	Control predictivo de sistemas ciberfÃsicos. RIAI - Revista Iberoamericana De Automatica E Informatica Industrial, 2021, 19, 1-12.	1.0	0
9	Performance Improvement via Iterative Connection of Passive Systems. IEEE Transactions on Automatic Control, 2020, 65, 1325-1332.	5.7	O
10	Instant Distributed Model Predictive Control for Constrained Linear Systems., 2020,,.		3
11	Weak Control Approach to Consumer-Preferred Energy Management. IFAC-PapersOnLine, 2020, 53, 17083-17088.	0.9	1
12	System identification method inheriting steady-state characteristics of existing model. International Journal of Control, 2019, 92, 2701-2711.	1.9	7
13	Instant MPC for Linear Systems and Dissipativity-Based Stability Analysis. , 2019, 3, 811-816.		16
14	Subspace identification with moment matching. Automatica, 2019, 99, 22-32.	5.0	18
15	"Weak―Control for Human-in-the-Loop Systems. , 2019, 3, 440-445.		20
16	Community Energy Management Reflecting Consumers' Preferences: Preference-Independent Control System Design., 2019,,.		0
17	Inhibiting Disturbance Propagation in Large-scale Systems and Its Application to Power System Control., 2018,,.		O
18	Observability Analysis for Simultaneous State and Physical Parameters Estimation of Rechargeable Batteries. , 2018, , .		0

#	Article	IF	CITATIONS
19	A Characterization of All Retrofit Controllers. , 2018, , .		5
20	Persistence in Control Systems., 2018, 2, 387-392.		1
21	Quantitative analysis of passive systems interconnected on graphs. Nonlinear Theory and Its Applications IEICE, 2018, 9, 185-195.	0.6	O
22	Model Matching Control for Binaural Reproduction over Loudspeakers. SICE Journal of Control Measurement and System Integration, 2018, 11, 249-255.	0.7	O
23	Parametrization of All Retrofit Controllers toward Open Control-Systems. , 2018, , .		9
24	Stable inversion design for binaural reproduction over loudspeakers. , 2017, , .		3
25	System identification and state estimation under lebesgue sampling: Use of inter-sample information. , 2017, , .		O
26	System identification with partial inheritance of existing model. , 2017, , .		0
27	Performance evaluation of graph-reduction in SLAM through pose rejection. , 2017, , .		O
28	State-of-charge estimation of rechargeable battery with hysteresis characteristics using robust gain-scheduled observer. , 2017, , .		0
29	State Estimation under Lebesgue Sampling and an Approach to Event-Triggered Control. SICE Journal of Control Measurement and System Integration, 2017, 10, 259-265.	0.7	3

State-space <mml:math xmlns:mml="http://www.w3.org/1998/Math/MathML" altimg="si2.gif" display="inline" overflow="scroll"><mml:mrow><mml:mrow><mml:mi>4</mml:mi></mml:mrow><mml:mrow><mml:mi>â^ž</mml:mi></mml:mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow></mrow>< 30