

# Masumi Ohno

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/8541220/publications.pdf>

Version: 2024-02-01

4  
papers

19  
citations

3311381

1  
h-index

3475538

1  
g-index

4  
all docs

4  
docs citations

4  
times ranked

7  
citing authors

#	ARTICLE	IF	CITATIONS
1	Design of target trajectories for the detection of joint clearances in parallel robot based on the actuation torque measurement. Mechanism and Machine Theory, 2021, 155, 104081.	4.5	18
2	Efficient computation of motion error of parallel robots with joint clearances based on joint force model. Transactions of the JSME (in Japanese), 2018, 84, 18-00057-18-00057.	0.2	1
3	Model Based Estimation of Passive Joint Clearance in Parallel Robot and Its Application to Failure Detection. Mechanisms and Machine Science, 2022, , 362-371.	0.5	0
4	Dynamic analysis of a parallel robot with spherical joints with consideration for joint clearance. Transactions of the JSME (in Japanese), 2022, 88, 21-00188-21-00188.	0.2	0