Petar Durdevic

List of Publications by Year in descending order

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759233 794594 35 422 12 19 h-index citations g-index papers 37 37 37 271 docs citations times ranked citing authors all docs

| # | Article | IF | CITATIONS |
|----|--|-----------------------------|-----------|
| 1 | Multi-Phase Flow Metering in Offshore Oil and Gas Transportation Pipelines: Trends and Perspectives. Sensors, 2019, 19, 2184. | 3.8 | 67 |
| 2 | Challenges in slug modeling and control for offshore oil and gas productions: A review study. International Journal of Multiphase Flow, 2017, 88, 270-284. | 3.4 | 55 |
| 3 | Modeling phosphorous dynamics in a wastewater treatment process using Bayesian optimized LSTM. Computers and Chemical Engineering, 2022, 160, 107738. | 3.8 | 22 |
| 4 | Review of Slug Detection, Modeling and Control Techniques for Offshore Oil & Description Processes and 2—âr—Supported by the Danish National Advanced Technology Foundation through PDPWAC Project (J.nr. 95-2012-3) IFAC-PapersOnLine, 2015, 48, 89-96. | 0.9 | 20 |
| 5 | Control Oriented Modeling of a De-oiling Hydrocyclone. IFAC-PapersOnLine, 2015, 48, 291-296. | 0.9 | 20 |
| 6 | Application of Hâ^ž Robust Control on a Scaled Offshore Oil and Gas De-Oiling Facility. Energies, 2018, 11, 287. | 3.1 | 19 |
| 7 | Smart-Spider: Autonomous Self-driven In-line Robot for Versatile Pipeline Inspection ⎠âŽThe authors would like to the support from Danish Hydrocarbon Research and Technology Centre(DHRTC) through DHRTC Radical Project Programme. IFAC-PapersOnLine, 2018, 51, 251-256. | 0.9 | 18 |
| 8 | Internal Wind Turbine Blade Inspections Using UAVs: Analysis and Design Issues. Energies, 2021, 14, 294. | 3.1 | 17 |
| 9 | Vision Aided Navigation of a Quad-Rotor for Autonomous Wind-Farm Inspection. IFAC-PapersOnLine, 2019, 52, 61-66. | 0.9 | 14 |
| 10 | Dynamic Oil-in-Water Concentration Acquisition on a Pilot-Scaled Offshore Water-Oil Separation Facility. Sensors, 2017, 17, 124. | 3.8 | 13 |
| 11 | Model-free <mml:math altimg="si4.svg" display="inline" id="d1e230" xmlns:mml="http://www.w3.org/1998/Math/MathML"> <mml:msub> <mml:mrow> <mml:mi>H</mml:mi></mml:mrow> <mml:mrow> <mml:mi>â^žtracking control for de-oiling hydrocyclone systems via off-policy reinforcement learning. Automatica, 2021, 133, 109862.</mml:mi></mml:mrow></mml:msub></mml:math> | ոl:mi> <td>ml:mgow></td> | ml:mgow> |
| 12 | Plant-wide Optimal Control of an Offshore De-oiling Process Using MPC Technique. IFAC-PapersOnLine, 2018, 51, 144-150. | 0.9 | 12 |
| 13 | Dynamic Efficiency Analysis of an Off-Shore Hydrocyclone System, Subjected to a Conventional PID-and Robust-Control-Solution. Energies, 2018, 11, 2379. | 3.1 | 12 |
| 14 | Classical and Deep Learning based Visual Servoing Systems: a Survey on State of the Art. Journal of Intelligent and Robotic Systems: Theory and Applications, 2022, 104, 1. | 3.4 | 12 |
| 15 | Experimental study of stable surfaces for anti-slug control in multi-phase flow. International Journal of Automation and Computing, 2016, 13, 81-88. | 4.5 | 10 |
| 16 | Influence of riser-induced slugs on the downstream separation processes. Journal of Petroleum Science and Engineering, 2017, 154, 337-343. | 4.2 | 10 |
| 17 | Cost-Effective ERT Technique for Oil-in-Water Measurement for Offshore Hydrocyclone Installations. IFAC-PapersOnLine, 2015, 48, 147-153. | 0.9 | 9 |
| 18 | Experimental modeling of a deoiling hydrocyclone system. , 2015, , . | | 9 |

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|----|---|-----|-----------|
| 19 | Challenges in Modelling and Control of Offshore De-oiling Hydrocyclone Systems. Journal of Physics: Conference Series, 2017, 783, 012048. | 0.4 | 9 |
| 20 | A Deep Neural Network Sensor for Visual Servoing in 3D Spaces. Sensors, 2020, 20, 1437. | 3.8 | 9 |
| 21 | Optimal Tracking Control Based on Integral Reinforcement Learning for An Underactuated Drone. IFAC-PapersOnLine, 2019, 52, 55-60. | 0.9 | 8 |
| 22 | Cleaning the produced water in offshore oil production by using plant-wide optimal control strategy. , 2014, , . | | 6 |
| 23 | Online Slug Detection in Multi-phase Transportation Pipelines Using Electrical Tomographyâ^—â^—Supported by the Danish National Advanced Technology Foundation through PDPWAC Project (J.nr. 95-2012-3) IFAC-PapersOnLine, 2015, 48, 159-164. | 0.9 | 6 |
| 24 | Hovering Control for Automatic Landing Operation of An Inspection Drone to A Mobile Platform. IFAC-PapersOnLine, 2018, 51, 245-250. | 0.9 | 5 |
| 25 | LiDAR Assisted Camera Inspection of Wind Turbines: Experimental Study., 2019,,. | | 5 |
| 26 | Experimental study of stable surfaces for anti-slug control in multi-phase flow. , 2014, , . | | 4 |
| 27 | Evaluation of OiW measurement technologies for deoiling hydrocyclone efficiency estimation and control. , 2016, , . | | 4 |
| 28 | Potential for Real-Time Monitoring and Control of Dissolved Oxygen in the Injection Water Treatment Process. IFAC-PapersOnLine, 2018, 51, 170-177. | 0.9 | 3 |
| 29 | Compressor Scheduling and Pressure Control for an Alternating Aeration Activated Sludge Process—A Simulation Study Validated on Plant Data. Water (Switzerland), 2021, 13, 1037. | 2.7 | 3 |
| 30 | Hybrid control of a two-wheeled automatic-balancing robot with backlash feature. , 2013, , . | | 2 |
| 31 | Control of variable-speed pressurization fan for an offshore HVAC system. , 2014, , . | | 2 |
| 32 | Modeling separation dynamics in a multi-tray bio-ethanol distillation column. , 2015, , . | | 1 |
| 33 | Operational performance of offshore de-oiling hydrocyclone systems. , 2017, , . | | 1 |
| 34 | Trajectory Tracking of Underactuated VTOL Aerial Vehicles With Unknown System Parameters Via IRL. IEEE Transactions on Automatic Control, 2022, 67, 3043-3050. | 5.7 | 1 |
| 35 | Game Theoretical Reinforcement Learning for Robust Hâ^ž Tracking Control of Discrete-Time Linear Systems with Unknown Dynamics. , 2021, , . | | O |