

Jun Shintake

List of Publications by Year in descending order

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35
papers

3,263
citations

566801

15
h-index

500791

28
g-index

37
all docs

37
docs citations

37
times ranked

3068
citing authors

#	ARTICLE	IF	CITATIONS
1	Liquid metal-based soft actuators and sensors for biomedical applications. , 2022, , 585-594.		0
2	Characterization of slide ring materials for dielectric elastomer actuators. Smart Materials and Structures, 2022, 31, 025028.	1.8	3
3	A Variable Stiffness Magnetic Catheter Made of a Conductive Phase-Change Polymer for Minimally Invasive Surgery. Advanced Functional Materials, 2022, 32, .	7.8	40
4	Green Robotics: Toward Realization of Environmentally Friendly Soft Robots. Journal of Robotics and Mechatronics, 2022, 34, 270-272.	0.5	5
5	Grasping State and Object Estimation of a Flat Shell Gripper by Strain and Proximity Measurement using a Single Capacitance-Based Sensor. , 2022, , .		0
6	Rapid Fabrication Method for Soft Devices Using Off-the-shelf Conductive and Dielectric Acrylic Elastomers. Advanced Intelligent Systems, 2021, 3, 2000173.	3.3	6
7	Cartilage structure increases swimming efficiency of underwater robots. Scientific Reports, 2021, 11, 11288.	1.6	8
8	Stretchable and Soft Electrodeposition Using Liquid-Metal Subsurface Microelectrodes. Advanced Materials Technologies, 2021, 6, 2100263.	3.0	16
9	Self-Sensing McKibben Artificial Muscles Embedded With Dielectric Elastomer Sensor. IEEE Robotics and Automation Letters, 2021, 6, 6274-6280.	3.3	16
10	Deep Reinforcement Learning Framework for Underwater Locomotion of Soft Robot. , 2021, , .		12
11	Fiber-reinforced soft polymeric manipulator with smart motion scaling and stiffness tunability. Cell Reports Physical Science, 2021, 2, 100600.	2.8	6
12	Characterization of Sustainable Robotic Materials and Finite Element Analysis of Soft Actuators Under Biodegradation. Frontiers in Robotics and AI, 2021, 8, 760485.	2.0	7
13	Monolithic Stacked Dielectric Elastomer Actuators. Frontiers in Robotics and AI, 2021, 8, 714332.	2.0	8
14	Dielectric Elastomer Fiber Actuators with Aqueous Electrode. Polymers, 2021, 13, 4310.	2.0	8
15	Phase Changing Materials-Based Variable-Stiffness Tensegrity Structures. Soft Robotics, 2020, 7, 362-369.	4.6	40
16	Lighter and Stronger: Cofabricated Electrodes and Variable Stiffness Elements in Dielectric Actuators. Advanced Intelligent Systems, 2020, 2, 2000069.	3.3	24
17	Bio-inspired Tensegrity Fish Robot. , 2020, , .		20
18	Low-Cost Sensor-Rich Fluidic Elastomer Actuators Embedded with Paper Electronics. Advanced Intelligent Systems, 2020, 2, 2080073.	3.3	0

#	ARTICLE	IF	CITATIONS
19	Foldable Kirigami Paper Electronics. <i>Physica Status Solidi (A) Applications and Materials Science</i> , 2020, 217, 1900891.	0.8	5
20	Large, Fast, and Bidirectional Bending of Slide-Ring Polymer Materials. <i>Advanced Intelligent Systems</i> , 2020, 2, 1900155.	3.3	6
21	Low-Cost Sensor-Rich Fluidic Elastomer Actuators Embedded with Paper Electronics. <i>Advanced Intelligent Systems</i> , 2020, 2, 2000025.	3.3	17
22	Stretchable pumps for soft machines. <i>Nature</i> , 2019, 572, 516-519.	13.7	263
23	Sensitivity Improvement of Highly Stretchable Capacitive Strain Sensors by Hierarchical Auxetic Structures. <i>Frontiers in Robotics and AI</i> , 2019, 6, 127.	2.0	42
24	All-Fabric Wearable Electrodehesive Clutch. <i>Advanced Materials Technologies</i> , 2019, 4, 1800313.	3.0	43
25	Characterization of dielectric elastomer actuators made of slide ring materials. , 2019, , .		3
26	Characterization of Bio-Degradable Materials for Soft Robotics. , 2019, , .		2
27	Ultrastretchable Strain Sensors Using Carbon Black-Filled Elastomer Composites and Comparison of Capacitive Versus Resistive Sensors. <i>Advanced Materials Technologies</i> , 2018, 3, 1700284.	3.0	219
28	Soft Robotic Grippers. <i>Advanced Materials</i> , 2018, 30, e1707035.	11.1	1,097
29	Soft Biomimetic Fish Robot Made of Dielectric Elastomer Actuators. <i>Soft Robotics</i> , 2018, 5, 466-474.	4.6	222
30	Bioinspired dual-stiffness origami. <i>Science Robotics</i> , 2018, 3, .	9.9	115
31	Versatile Soft Grippers with Intrinsic Electrodehesion Based on Multifunctional Polymer Actuators. <i>Advanced Materials</i> , 2016, 28, 231-238.	11.1	593
32	Variable Stiffness Fiber with Self-Healing Capability. <i>Advanced Materials</i> , 2016, 28, 10142-10148.	11.1	142
33	Rollable Multisegment Dielectric Elastomer Minimum Energy Structures for a Deployable Microsatellite Gripper. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015, 20, 438-446.	3.7	209
34	A Foldable Antagonistic Actuator. <i>IEEE/ASME Transactions on Mechatronics</i> , 2015, 20, 1997-2008.	3.7	60
35	Enhancement of pressure-sensitive adhesive by CO ₂ laser treatment. <i>Advanced Engineering Materials</i> , 0, , .	1.6	0