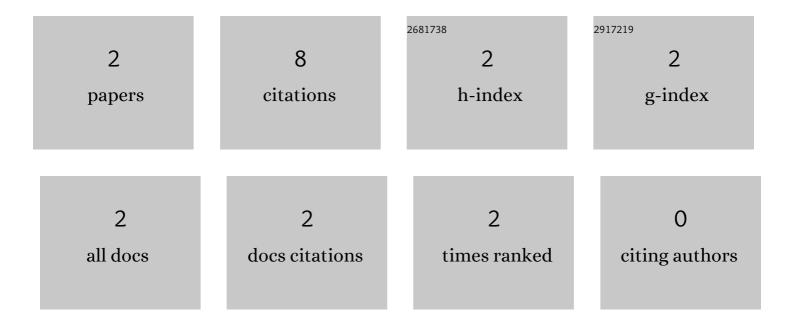
## Nidya M V

## List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/8329522/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	Feedback-linearization based robust relatively optimal trajectory tracking controller for 3-DOF helicopter. Engineering Science and Technology, an International Journal, 2022, 31, 101050.	2.0	5
2	Convex-Optimization-based Constrained Control Strategy for 3-DOF Tandem Helicopter using Feedback Linearization. Journal of Optimization Theory and Applications, 2021, 191, 736-755.	0.8	3