

Guan-Hao Liang

List of Publications by Year in descending order

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citing authors

#	ARTICLE	IF	CITATIONS
1	Collision-Free Path Planning Method for Robots Based on an Improved Rapidly-Exploring Random Tree Algorithm. Applied Sciences (Switzerland), 2020, 10, 1381.	2.5	45
2	Stability Criterion for Dynamic Gaits of Quadruped Robot. Applied Sciences (Switzerland), 2018, 8, 2381.	2.5	12
3	A Planning Method for Multi-Axis Point-to-Point Synchronization Based on Time Constraints. IEEE Access, 2020, 8, 85575-85604.	4.2	10
4	A General Approach Based on Newton's Method and Cyclic Coordinate Descent Method for Solving the Inverse Kinematics. Applied Sciences (Switzerland), 2019, 9, 5461.	2.5	5
5	Modeling and diving control of a vector propulsion AUV. , 2016, , .		4