# **Shihong Ding**

### List of Publications by Citations

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96<br/>papers2,808<br/>citations26<br/>h-index51<br/>g-index115<br/>ext. papers3,568<br/>ext. citations3.8<br/>avg, IF6.48<br/>L-index

#	Paper	IF	Citations
96	. IEEE Transactions on Industrial Electronics, <b>2017</b> , 64, 6752-6762	8.9	196
95	Second-order sliding mode controller design subject to mismatched term. <i>Automatica</i> , <b>2017</b> , 77, 388-3	92 <sub>5.7</sub>	152
94	Simple homogeneous sliding-mode controller. <i>Automatica</i> , <b>2016</b> , 67, 22-32	5.7	148
93	Stabilization of the attitude of a rigid spacecraft with external disturbances using finite-time control techniques. <i>Aerospace Science and Technology</i> , <b>2009</b> , 13, 256-265	4.9	131
92	Nonsmooth stabilization of a class of nonlinear cascaded systems. <i>Automatica</i> , <b>2012</b> , 48, 2597-2606	5.7	129
91	Disturbance Observer Design for Nonlinear Systems Represented by InputDutput Models. <i>IEEE Transactions on Industrial Electronics</i> , <b>2020</b> , 67, 1222-1232	8.9	125
90	. IEEE Transactions on Industrial Informatics, 2018, 14, 1990-2000	11.9	121
89	Global set stabilisation of the spacecraft attitude using finite-time control technique. <i>International Journal of Control</i> , <b>2009</b> , 82, 822-836	1.5	121
88	A New Second-Order Sliding Mode and Its Application to Nonlinear Constrained Systems. <i>IEEE Transactions on Automatic Control</i> , <b>2019</b> , 64, 2545-2552	5.9	113
87	Second-Order Sliding Mode Control for Nonlinear Uncertain Systems Bounded by Positive Functions. <i>IEEE Transactions on Industrial Electronics</i> , <b>2015</b> , 62, 5899-5909	8.9	107
86	Second-order sliding mode controller design with output constraint. <i>Automatica</i> , <b>2020</b> , 112, 108704	5.7	103
85	Global finite-time stabilisation by output feedback for a class of uncertain nonlinear systems. <i>International Journal of Control</i> , <b>2010</b> , 83, 2241-2252	1.5	96
84	A speed control for a PMSM using finite-time feedback control and disturbance compensation. <i>Transactions of the Institute of Measurement and Control</i> , <b>2010</b> , 32, 170-187	1.8	85
83	Global stabilization of a class of upper-triangular systems with unbounded or uncontrollable linearizations. <i>International Journal of Robust and Nonlinear Control</i> , <b>2011</b> , 21, 271-294	3.6	84
82	Global Stabilization of a Class of Feedforward Systems with Lower-Order Nonlinearities. <i>IEEE Transactions on Automatic Control</i> , <b>2010</b> , 55, 691-696	5.9	69
81	Finite-time stabilization for a class of high-order stochastic nonlinear systems with an output constraint. <i>Applied Mathematics and Computation</i> , <b>2019</b> , 358, 63-79	2.7	68
80	Composite Super-twisting Sliding Mode Control Design for PMSM Speed Regulation Problem Based on a Novel Disturbance Observer. <i>IEEE Transactions on Energy Conversion</i> , <b>2020</b> , 1-1	5.4	66

# (2010-2020)

79	An Adaptive SOSM Controller Design by Using a Sliding-Mode-Based Filter and its Application to Buck Converter. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , <b>2020</b> , 67, 2409-2418	3.9	56	
78	Second-Order Sliding Mode Controller Design Subject to an Upper-Triangular Structure. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2021</b> , 51, 497-507	7:3	56	
77	Nested saturation control for overhead crane systems. <i>Transactions of the Institute of Measurement and Control</i> , <b>2012</b> , 34, 862-875	1.8	44	
76	Nonsingular terminal sliding mode control of nonlinear second-order systems with input saturation. <i>International Journal of Robust and Nonlinear Control</i> , <b>2016</b> , 26, 1857-1872	3.6	43	
75	Bounded Consensus Algorithms for Multi-Agent Systems in Directed Networks. <i>Asian Journal of Control</i> , <b>2013</b> , 15, 282-291	1.7	39	
74	Stability analysis for a second-order continuous finite-time control system subject to a disturbance. Journal of Control Theory and Applications, 2009, 7, 271-276		39	
73	. IEEE Transactions on Aerospace and Electronic Systems, <b>2014</b> , 50, 1163-1181	3.7	38	
72	Second-Order Sliding Mode Control Design Subject to an Asymmetric Output Constraint. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , <b>2021</b> , 68, 1278-1282	3.5	29	
71	GPIO Based Super-Twisting Sliding Mode Control for PMSM. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , <b>2021</b> , 68, 747-751	3.5	28	
70	Robust finite-time stabilization of a class of high-order stochastic nonlinear systems subject to output constraint and disturbances. <i>International Journal of Robust and Nonlinear Control</i> , <b>2019</b> , 29, 555	5 <del>0</del> -557	3 <sup>26</sup>	
69	Fixed-time SOSM controller design with output constraint. <i>Nonlinear Dynamics</i> , <b>2020</b> , 102, 1567-1583	5	26	
68	Adaptive Fuzzy Control for Nontriangular Stochastic High-Order Nonlinear Systems Subject to Asymmetric Output Constraints. <i>IEEE Transactions on Cybernetics</i> , <b>2020</b> , PP,	10.2	21	
67	HOSM controller design with asymmetric output constraints. <i>Science China Information Sciences</i> , <b>2022</b> , 65, 1	3.4	21	
66	Finite-time controller design of multiple integrator nonlinear systems with input saturation. <i>Applied Mathematics and Computation</i> , <b>2020</b> , 372, 124986	2.7	20	
65	Direct yaw-moment control for 4WID electric vehicle via finite-time control technique. <i>Nonlinear Dynamics</i> , <b>2017</b> , 88, 239-254	5	19	
64	Quasi-Continuous Second-Order Sliding Mode Control of Buck Converter. <i>IEEE Access</i> , <b>2018</b> , 6, 17859-1	7 <u>8,6</u> 7	18	
63	Robust control of multiple integrators subject to input saturation and disturbance. <i>International Journal of Control</i> , <b>2015</b> , 88, 844-856	1.5	18	
62	Global uniform asymptotical stability of a class of nonlinear cascaded systems with application to a nonholonomic wheeled mobile robot. <i>International Journal of Systems Science</i> , <b>2010</b> , 41, 1301-1312	2.3	16	

61	Adaptive Nonsingular Terminal Sliding Model Control for Permanent Magnet Synchronous Motor Based on Disturbance Observer. <i>IEEE Access</i> , <b>2018</b> , 6, 48913-48920	3.5	16
60	Second-order sliding mode controller design subject to mismatched unbounded perturbations. <i>International Journal of Robust and Nonlinear Control</i> , <b>2017</b> , 27, 4706-4722	3.6	15
59	Composite Active Front Steering Controller Design for Vehicle System. <i>IEEE Access</i> , <b>2017</b> , 5, 6697-6706	3.5	15
58	A novel adaptive nonsingular terminal sliding mode controller design and its application to active front steering system. <i>International Journal of Robust and Nonlinear Control</i> , <b>2019</b> , 29, 4250	3.6	15
57	Integral sliding mode control for stochastic Markovian jump system with time-varying delay. <i>Neurocomputing</i> , <b>2016</b> , 179, 118-125	5.4	15
56	Global Finite-Time Stabilization for Nonholonomic Mobile Robots Based on Visual Servoing.  International Journal of Advanced Robotic Systems, <b>2014</b> , 11, 180	1.4	15
55	A Super-Twisting-Like Fractional Controller for SPMSM Drive System. <i>IEEE Transactions on Industrial Electronics</i> , <b>2021</b> , 1-1	8.9	15
54	Apple tree branch segmentation from images with small gray-level difference for agricultural harvesting robot. <i>Optik</i> , <b>2016</b> , 127, 11173-11182	2.5	15
53	Finite-Time Stabilization of High-Order Stochastic Nonlinear Systems With Asymmetric Output Constraints. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems,</i> <b>2020</b> , 1-13	7.3	14
52	Global decentralised stabilisation for a class of uncertain large-scale feedforward nonlinear systems. <i>International Journal of Control</i> , <b>2014</b> , 87, 1282-1296	1.5	13
51	Adaptive Fuzzy Control for Stochastic High-Order Nonlinear Systems With Output Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , <b>2020</b> , 1-1	8.3	12
50	Adaptive Second-order Sliding Mode Control: A Lyapunov Approach. <i>IEEE Transactions on Automatic Control</i> , <b>2021</b> , 1-1	5.9	12
49	Design of an adaptive nonsingular terminal sliding model control method for a bearingless permanent magnet synchronous motor. <i>Transactions of the Institute of Measurement and Control</i> , <b>2017</b> , 39, 1821-1828	1.8	11
48	New approach to second-order sliding mode control design. <i>IET Control Theory and Applications</i> , <b>2013</b> , 7, 2188-2196	2.5	11
47	Guidance law design based on non-smooth control. <i>Transactions of the Institute of Measurement and Control</i> , <b>2013</b> , 35, 1116-1128	1.8	10
46	Universal finite-time observer based second-order sliding mode control for DC-DC buck converters with only output voltage measurement. <i>Journal of the Franklin Institute</i> , <b>2020</b> , 357, 11863-11879	4	10
45	Adaptive Fuzzy SOSM Controller Design With Output Constraints. <i>IEEE Transactions on Fuzzy Systems</i> , <b>2021</b> , 1-1	8.3	9
44	Global stabilisation of a class of generalised cascaded systems by homogeneous method.  International Journal of Control, 2016, 89, 815-832	1.5	7

## (2019-2018)

43	Design and testing of a control system associated with the automatic feeding boat for farming Chinese river crabs. <i>Computers and Electronics in Agriculture</i> , <b>2018</b> , 150, 14-25	6.5	7	
42	Controller design for nonlinear affine systems by control Lyapunov functions. <i>Systems and Control Letters</i> , <b>2013</b> , 62, 930-936	2.4	7	
41	High-order sliding mode controller design subject to lower-triangular nonlinearity and its application to robotic system. <i>Journal of the Franklin Institute</i> , <b>2020</b> , 357, 10367-10386	4	7	
40	Global stabilization of a class of cascaded systems with upper-triangular structures. <i>International Journal of Robust and Nonlinear Control</i> , <b>2018</b> , 28, 4330	3.6	6	
39	Finite-time Extended State Observer Based Super-twisting Sliding Mode Controller for PMSM Drives with Inertia Identification. <i>IEEE Transactions on Transportation Electrification</i> , <b>2021</b> , 1-1	7.6	6	
38	Fuzzy Adaptive SOSM Based Control of A Type of Nonlinear Systems. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , <b>2021</b> , 1-1	3.5	6	
37	Direct yaw-moment control of in-wheel electric vehicle by sliding mode technique 2016,		5	
36	New families of high-order sliding-mode controllers 2015,		5	
35	Global stabilization of partially linear composite systems using homogeneous method. <i>Asian Journal of Control</i> , <b>2011</b> , 13, 1028-1034	1.7	5	
34	Adaptive set stabilization of the attitude of a rigid spacecraft without angular velocity measurements. <i>Journal of Systems Science and Complexity</i> , <b>2011</b> , 24, 105-119	1	5	
33	Fixed-Time Stabilization for a Class of Output-Constrained Nonlinear Systems. <i>IEEE Transactions on Systems, Man, and Cybernetics: Systems</i> , <b>2022</b> , 1-13	7.3	4	
32	Composite finite-time straight-line path-following control of an underactuated surface vessel. <i>Journal of the Franklin Institute</i> , <b>2020</b> , 357, 11496-11517	4	4	
31	Straight-Line Tracking Control of an Agricultural Vehicle with Finite-Time Control Technique. <i>Asian Journal of Control</i> , <b>2015</b> , 17, 2218-2228	1.7	3	
30	Active front steering controller design for electric vehicle system by using disturbance observer method <b>2017</b> ,		3	
29	Adaptive Fuzzy Output-Feedback Control Design for a Class of p-Norm Stochastic Nonlinear Systems With Output Constraints. <i>IEEE Transactions on Circuits and Systems I: Regular Papers</i> , <b>2021</b> , 68, 2626-2638	3.9	3	
28	A unified control approach to finite-time stabilization of SOSM dynamics subject to an output constraint. <i>Applied Mathematics and Computation</i> , <b>2021</b> , 394, 125752	2.7	3	
27	TCP/AWM network congestion algorithm with funnel control and arbitrary setting time. <i>Applied Mathematics and Computation</i> , <b>2020</b> , 385, 125410	2.7	2	
26	A novel second-order sliding mode control based on the Lyapunov method. <i>Transactions of the Institute of Measurement and Control</i> , <b>2019</b> , 41, 1068-1078	1.8	2	

25	Parameterisation of a special class of saturated controllers and application to mechanical systems. <i>IET Control Theory and Applications</i> , <b>2017</b> , 11, 3146-3155	2.5	2
24	Fuzzy Non-singular Terminal Sliding Mode Controller Design for Nonlinear Systems with Input Saturation. <i>International Journal of Fuzzy Systems</i> , <b>2020</b> , 22, 2271-2283	3.6	2
23	Observer-based adaptive scheme for fixed-time frequency estimation of biased sinusoidal signals. <i>Automatica</i> , <b>2021</b> , 127, 109559	5.7	2
22	A Compound Controller Design for a Buck Converter. <i>Energies</i> , <b>2018</b> , 11, 2354	3.1	2
21	Fixed-time SOSM controller design subject to an asymmetric output constraint. <i>Journal of the Franklin Institute</i> , <b>2021</b> , 358, 7485-7506	4	2
20	Output-feedback finite-time stabilization of a class of constrained planar systems. <i>Applied Mathematics and Computation</i> , <b>2022</b> , 412, 126573	2.7	2
19	An Improved Three-vector-based Model Predictive Current Control Method for Surface-mounted PMSM Drives. <i>IEEE Transactions on Transportation Electrification</i> , <b>2022</b> , 1-1	7.6	2
18	Controller design of second order sliding mode control systems with mismatached perturbations <b>2017</b> ,		1
17	Terminal sliding mode control of second-order systems with bounded input 2013,		1
16	Global stabilization of a class of upper-triangular systems with higher-order nonlinearities 2010,		1
15	Second-Order Sliding Mode Controller Design with a Larger Domain of Attraction. <i>Journal of Systems Science and Complexity</i> , <b>2020</b> , 33, 61-73	1	1
14	Nonsmooth stabilization for distributed electric vehicle based on direct yaw-moment control 2016,		1
13	Design of a run-to-run controller based on discrete sliding-mode observer. <i>Asian Journal of Control</i> , <b>2021</b> , 23, 908-919	1.7	1
12	A new optimization particle filtering navigation location method for aquatic plants cleaning workboat in crab farming. <i>International Journal of Advanced Robotic Systems</i> , <b>2018</b> , 15, 1729881418787	′9 <sup>1</sup> 1·4	1
11	Second-order sliding mode controller design with mismatched term and time-varying output constraint. <i>Applied Mathematics and Computation</i> , <b>2021</b> , 407, 126331	2.7	1
10	Fixed-time HOSM controller design for constrained sliding mode systems with mismatched terms. <i>Information Sciences</i> , <b>2022</b> , 585, 366-381	7.7	O
9	Finite-time stabilization for a class of stochastic output-constrained systems by output feedback. <i>International Journal of Robust and Nonlinear Control</i> , <b>2022</b> , 32, 1256	3.6	0
8	On robust stability of switched homogeneous systems. <i>IET Control Theory and Applications</i> , <b>2021</b> , 15, 758-770	2.5	О

#### LIST OF PUBLICATIONS

7	Fuzzy Disturbance Observer Design for a Class of Nonlinear SISO Systems. <i>International Journal of Fuzzy Systems</i> ,1	3.6	О	
6	Design of high-order sliding mode controller under asymmetric output constraints. <i>International Journal of Robust and Nonlinear Control</i> , <b>2021</b> , 31, 7107-7124	3.6	O	
5	HOSM controller design with an output constraint and its application. ISA Transactions, 2021, 116, 71-8	3 <b>0</b> 5.5	О	
4	Finite-time fuzzy output-feedback control for \$ p \$-norm stochastic nonlinear systems with output constraints. <i>AIMS Mathematics</i> , <b>2021</b> , 6, 2244-2267	2.2	O	
3	Second-Order Sliding Mode Control for BUCK Converters. <i>Lecture Notes in Electrical Engineering</i> , <b>2016</b> , 69-76	0.2		
2	SOSM controller design for output constrained systems subject to disturbances with unknown magnitudes. <i>IEEE Transactions on Circuits and Systems II: Express Briefs</i> , <b>2022</b> , 1-1	3.5		
1	Global Finite-Time Controller Design for HOSM Dynamics Subject to Upper-Triangular Structure.  IEEE Transactions on Circuits and Systems I: Regular Papers, 2022, 1-14	3.9		